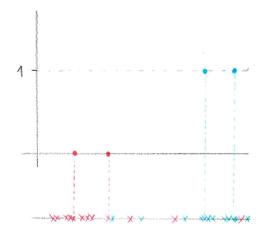
Logistic Regression & SVM

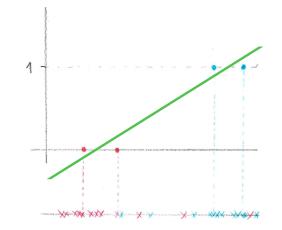
What about classification using regression?

Binary classification: Desired outputs 0 and 1 ... we want to capture the probability distribution of the classes



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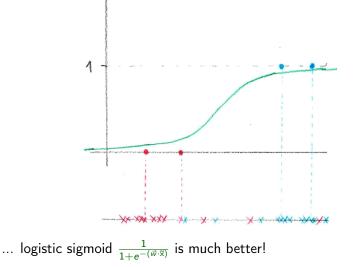
Binary classification: Desired outputs 0 and 1 ... we want to capture the probability distribution of the classes



... does not capture the probability well (it is not probability at all)

What about classification using regression?

Binary classification: Desired outputs 0 and 1 ... we want to capture the probability distribution of the classes



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Given
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,

$$h[\vec{w}](\vec{x}) := rac{1}{1 + e^{-\left(w_0 + \sum_{k=1}^n w_k x_k
ight)}} = rac{1}{1 + e^{-\vec{w}\cdot\widetilde{\mathbf{x}}}}$$

Here

$$\tilde{\mathsf{x}} = (x_0, x_1, \dots, x_n)$$
 where $x_0 = 1$

is the *augmented feature vector*.

The model gives probability $h[\vec{w}](\vec{x})$ of the class 1 given an input \vec{x} . But why do we model such probability using $1/(1 + e^{-\vec{w}\cdot\tilde{x}})$??

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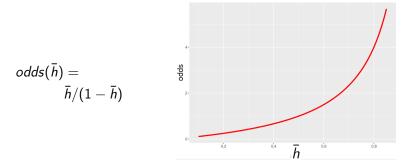
Denote by \overline{h} the probability $P(Y = 1 | X = \overline{x})$, i.e., the "true" probability of the class 1 given features \overline{x} .

The probability \overline{h} cannot be easily modeled using a linear function (the probabilities are between 0 and 1).

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What about odds of the class 1?

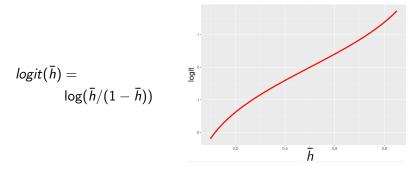


Better, at least it is unbounded on one side ...

The model gives probability $h[\vec{w}](\vec{x})$ of the class 1 given an input \vec{x} . But why do we model such probability using $1/(1 + e^{-\vec{w}\cdot\tilde{x}})$??

Denote by \overline{h} the probability $P(Y = 1 | X = \overline{x})$, i.e., the "true" probability of the class 1 given features \overline{x} .

What about log odds (aka logit) of the class 1?



Looks almost linear, at least for probabilities not too close to 0 or 1

Assume that \bar{h} is the true probability of the class 1 for an "object" with features $\vec{x} \in \mathbb{R}^n$. Put

 $\log(ar{h}/(1-ar{h})) = ec{w}\cdot\widetilde{\mathsf{x}}$

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and

$$ar{h} = rac{1}{1+e^{-ec{w}\cdot\widetilde{\mathbf{x}}}} = h[ec{w}](ec{x})$$

That is, if we model log odds using a linear function, the probability is obtained by applying the logistic sigmoid on the result of the linear function.

► Given a set *D* of training samples:

$$D = \{ (\vec{x}_1, c_1), (\vec{x}_2, c_2), \dots, (\vec{x}_p, c_p) \}$$

Here $\vec{x}_k = (x_{k1} \dots, x_{kn}) \in \mathbb{R}^n$ and $c_k \in \{0, 1\}$.

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Recall that $h[\vec{w}](\vec{x}_k) = 1 / (1 + e^{-\vec{w}\cdot\vec{x}_k})$ where $\vec{x}_k = (x_{k0}, x_{k1} \dots, x_{kn})$, here $x_{k0} = 1$ **Our goal:** Find \vec{w} such that for every $k = 1, \dots, p$ we have that $h[\vec{w}](\vec{x}_k) \approx c_k$

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Binary Cross-entropy:

$$E(\vec{w}) = -\sum_{k=1}^{p} c_k \log(h[\vec{w}](\vec{x}_k)) + (1 - c_k) \log(1 - h[\vec{w}](\vec{x}_k))$$

Gradient of the Error Function

Consider the gradient of the error function:

$$\nabla E(\vec{w}) = \left(\frac{\partial E}{\partial w_0}(\vec{w}), \dots, \frac{\partial E}{\partial w_n}(\vec{w})\right) = \sum_{k=1}^p \left(\frac{h[\vec{w}](\vec{x}_k) - c_k}{\vec{x}_k}\right) \cdot \tilde{x}_k$$

Fakt

If $\nabla E(\vec{w}) = \vec{0} = (0, ..., 0)$, then \vec{w} is a global minimum of E. This follows from the fact that E is convex.

Note that using the squared error with the logistic sigmoid would lead to a non-convex error with several minima!

Gradient Descent:

• Weights $\vec{w}^{(0)}$ are initialized randomly close to $\vec{0}$.

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Here $0 < \varepsilon \leq 1$ is the learning rate.

Note that the algorithm is almost similar to the batch perceptron algorithm!

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Tvrzení

For sufficiently small $\varepsilon > 0$ the sequence $\vec{w}^{(0)}, \vec{w}^{(1)}, \vec{w}^{(2)}, \ldots$ converges (in a component-wise manner) to the global minimum of the error function E.

Logistic Regression - Using the Trained Model

Assume that we have already trained our logistic regression model, i.e., we have a vector of weights $\vec{w} = (w_0, w_1, \dots, w_n)$.

The model is the function $h[\vec{w}]$ which for a given feature vector $\vec{x} = (x_1, \dots, x_n)$ returns the probability

$$h[\vec{w}](\vec{x}) = rac{1}{1 + e^{-(w_0 + \sum_{k=1}^n w_k x_k)}}$$

that \vec{x} belongs to the class 1.

To decide whether a given \vec{x} belongs to the class 1 we use $h[\vec{w}]$ as a Bayes classifier: Assign \vec{x} to the class 1 iff $h[\vec{w}](\vec{x}) \ge 1/2$. Other thresholds can also be used depending on the application and properties of the model. In such a case, given a threshold $\xi \in [0, 1]$, assign \vec{x} to the class 1 iff $h[\vec{w}](\vec{x}) \ge \xi$.

Maximum Likelihood vs Cross-entropy (Dim 1)

Fix a training set $D = \{(x_1, c_1), (x_2, c_2), \dots, (x_p, c_p)\}$ Generate a sequence $c'_1, \dots, c'_p \in \{0, 1\}^p$ where each c'_k has been generated independently by the Bernoulli trial generating 1 with probability

$$h[w_0, w_1](x_k) = \frac{1}{1 + e^{-(w_0 + w_1 \cdot x_k)}}$$

and 0 otherwise.

Here w₀, w₁ are unknown weights.

How "probable" is it to generate the correct classes c_1, \ldots, c_p ?

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The following conditions are equivalent:

• w_0, w_1 minimize the binary cross-entropy E

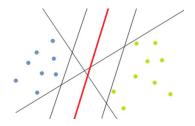
▶ w_0, w_1 maximize the likelihood (i.e., the "probability") of generating the correct values c_1, \ldots, c_p using the above described Bernoulli trials (i.e., that $c'_k = c_k$ for all $k = 1, \ldots, p$)

Note that the above equivalence is a property of the cross-entropy and is not dependent on the "implementation" of $h[w_0, w_1](x_k)$ using the logistic sigmoid.

SVM Idea – Which Linear Classifier is the Best?



SVM Idea – Which Linear Classifier is the Best?



Benefits of maximum margin:

- Intuitively, maximum margin is good w.r.t. generalization.
- Only the support vectors (those on the magin) matter, others can, in principle, be ignored.

•
$$\vec{w} = (w_0, w_1, \dots, w_n)$$
 a vector of weights,

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Consider a linear classifier:

$$h[\vec{w}](\vec{x}) := \begin{cases} 1 & w_0 + \sum_{i=1}^n w_i \cdot x_i = \vec{w} \cdot \widetilde{x} \ge 0 \\ -1 & w_0 + \sum_{i=1}^n w_i \cdot x_i = \vec{w} \cdot \widetilde{x} < 0 \end{cases}$$

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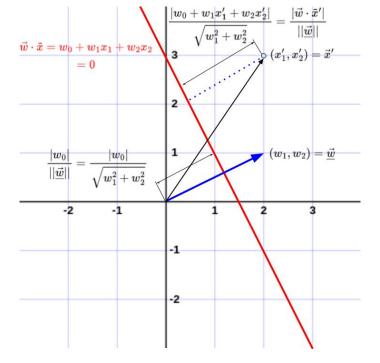
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The *distance* of \vec{x} from the separating hyperplane determined by \vec{w} is

$$d[ec{w}](ec{x}) = rac{|ec{w}\cdot\widetilde{ extsf{x}}|}{\|ec{w}\|}$$

Recall that $\vec{w} \cdot \vec{x}$ is positive for \vec{x} on the side to which $\underline{\vec{w}}$ points and negative on the opposite side.



Margin

Given a training set

 $D = \{ (\vec{x_1}, y_1), (\vec{x_2}, y_2), \dots, (\vec{x_p}, y_p) \}$ Here $\vec{x_k} = (x_{k1} \dots, x_{kn}) \in X \subseteq \mathbb{R}^n$ and $y_k \in \{-1, 1\}$.

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Assume that D is linearly separable, let \vec{w} be consistent with D.

Margin of \vec{w} is twice the minimum distance between feature vectors \vec{x}_k and the separating hyperplane determined by \vec{w} , i.e.,

$$2\min_{k} d[\vec{w}](\vec{x}_{k}) = 2\min_{k} \frac{|\vec{w} \cdot \widetilde{\mathbf{x}}_{k}|}{\|\vec{w}\|}$$

Our goal is to find w consistent with D that maximizes the margin. Note that to maximize the margin it suffices to maximize min_k ^{|w x_k|}/_{|w|} over w consistent with D.

Finding the Maximum Margin Classifier

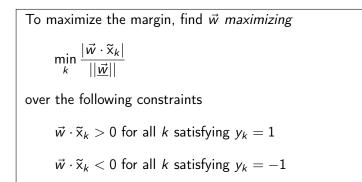
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Finding the Maximum Margin Classifier

We want to maximize the minimum distance of the feature vectors \vec{x}_k from the separating hyperplane determined by \vec{w} .

Formally, we use the following:

To maximize the margin, find \vec{w} maximizing $\min_{k} \frac{|\vec{w} \cdot \tilde{x}_{k}|}{||\vec{w}||}$ (= the distance of closest \vec{x}_k 's to the sep. hyperplane) over the following constraints $\vec{w} \cdot \tilde{x}_k > 0$ for all k satisfying $y_k = 1$ $\vec{w} \cdot \tilde{x}_k < 0$ for all k satisfying $y_k = -1$ (the contraints make sure that \vec{w} is consistent with the training set D)



To maximize the margin, find
$$\vec{w}$$
 maximizing

$$\begin{array}{l} \min_{k} \frac{|\vec{w} \cdot \widetilde{\mathbf{x}}_{k}|}{||\vec{w}||} \\
\text{over the following constraints} \\
\vec{w} \cdot \widetilde{\mathbf{x}}_{k} > 0 \text{ for all } k \text{ satisfying } y_{k} = 1 \\
\vec{w} \cdot \widetilde{\mathbf{x}}_{k} < 0 \text{ for all } k \text{ satisfying } y_{k} = -1
\end{array}$$

can be made more succinct:

To maximize the margin, find \vec{w} maximizing $\min_{k} \frac{y_k \cdot \vec{w} \cdot \widetilde{x}_k}{\|\vec{w}\|} \quad \text{over} \quad \min_{k} (y_k \cdot \vec{w} \cdot \widetilde{x}_k) > 0$

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To maximize the margin, find
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Observation: For every \vec{w} satisfying $\min_k(y_k \cdot \vec{w} \cdot \vec{x}_k) > 0$ there is \vec{w}' satisfying $\min_k(y_k \cdot \vec{w}' \cdot \vec{x}_k) = 1$ such that

$$\min_{k} \frac{y_{k} \cdot \vec{w} \cdot \widetilde{\mathbf{x}}_{k}}{\|\vec{w}\|} = \min_{k} \frac{y_{k} \cdot \vec{w'} \cdot \widetilde{\mathbf{x}}_{k}}{\|\vec{w'}\|}$$

Proof: Just consider $\vec{w}' = \vec{w}/\xi$ where $\xi = \min_k (y_k \cdot \vec{w} \cdot \tilde{x}_k)$.

To maximize the margin, find
$$\vec{w}$$
 maximizing
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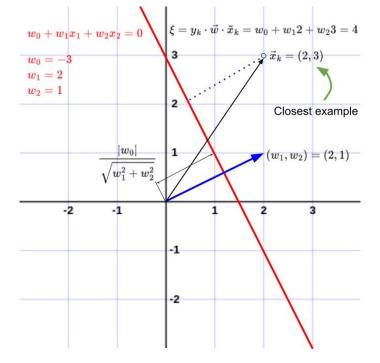
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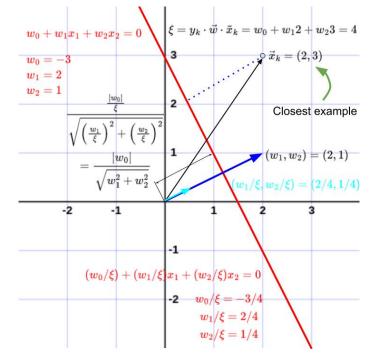
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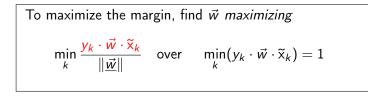
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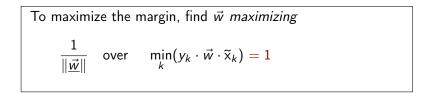


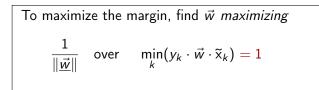


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 maximizing
 $\min_k rac{y_k \cdot \vec{w} \cdot \widetilde{x}_k}{\|\vec{w}\|}$ over $\min_k (y_k \cdot \vec{w} \cdot \widetilde{x}_k) = 1$

can be further simplified to

To maximize the margin, find
$$ec{w}$$
 maximizing $rac{1}{\|ec{w}\|}$ over $\min_k(y_k\cdotec{w}\cdot\widetilde{\mathsf{x}}_k)=1$





can be adjusted by loosening the constraints:

1

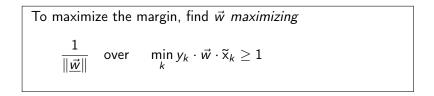
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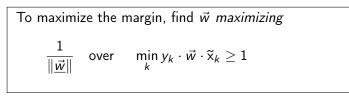
$$\frac{1}{\|\vec{w}\|} \quad \text{over} \quad \min_{k} (y_k \cdot \vec{w} \cdot \widetilde{x}_k) \ge 1$$

If the latter is solved by \vec{w}' with $\min_k(y_k \cdot \vec{w}' \cdot \tilde{x}_k) > 1$, then

$$\min_{k} \frac{y_k \cdot \vec{w'} \cdot \widetilde{\mathbf{x}}_k}{\left|\left|\underline{\vec{w'}}\right|\right|} > \frac{1}{\left|\left|\underline{\vec{w'}}\right|\right|} \ge \frac{1}{\left|\left|\underline{\vec{w}}\right|\right|} = \frac{\min_k y_k \cdot \vec{w} \cdot \widetilde{\mathbf{x}}_k}{\left|\left|\underline{\vec{w}}\right|\right|}$$

for all \vec{w} satisfying $\min_k(y_k \cdot \vec{w} \cdot \tilde{x}_k) = 1$ which contradicts the fact that the maximum margin is attained by such a \vec{w} .





can be turned into

To maximize the margin, find
$$ec{w}$$
 minimizing $||ec{w}||$ over $\min_k y_k \cdot ec{w} \cdot \widetilde{\mathsf{x}}_k \geq 1$

To maximize the margin, find
$$\vec{w}$$
 maximizing
 $rac{1}{\| \underline{\vec{w}} \|}$ over $\min_k y_k \cdot \vec{w} \cdot \widetilde{\mathbf{x}}_k \geq 1$

can be turned into

To maximize the margin, find
$$\vec{w}$$
 minimizing $||\vec{w}||$ over $\min_k y_k \cdot \vec{w} \cdot \widetilde{x}_k \ge 1$

and, finally,

To maximize the margin, find \vec{w} minimizing

 $\underline{\vec{w}} \cdot \underline{\vec{w}}$ over $y_k \cdot \vec{w} \cdot \widetilde{x}_k \ge 1$ for all k

Indeed, just note that $||\underline{\vec{w}}|| = \sqrt{\underline{\vec{w}} \cdot \underline{\vec{w}}}$.

Assume a given training set

$$D = \{ (\vec{x}_1, y_1) \}, (\vec{x}_2, y_2), \dots, (\vec{x}_p, y_p) \}$$

Here
$$\vec{x}_k = (x_{k1} \dots, x_{kn}) \in X \subseteq \mathbb{R}^n$$
 and $y_k \in \{-1, 1\}$.
(recall $\tilde{x}_k = (x_{k0}, x_{k1}, \dots, x_{kn})$ where $x_{k0} = 1$)

Margin maximization as a quadratic optimization problem:

Find *w* minimizing

 $\underline{\vec{w}} \cdot \underline{\vec{w}}$

under the constraints

 $y_k \cdot \vec{w} \cdot \tilde{\mathbf{x}}_k \geq 1$ for all k

Support vectors are vectors \vec{x}_k closest to the optimal separating hyperplane, i.e., those satisfying $y_k \cdot \vec{w} \cdot \tilde{x}_k = 1$ for a minimizing \vec{w} .

Example

Training set:

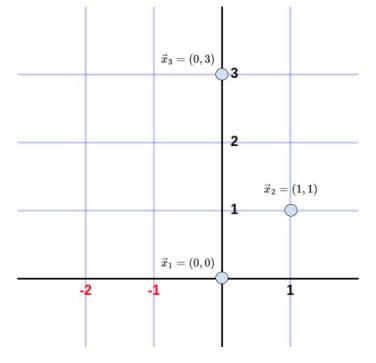
 $D = \{((0,0),-1),((1,1),1),((0,3),1)\}$

That is

$$egin{array}{rcl} ec{x}_1 &=& (0,0) & & & & & & & & & & \ ec{x}_2 &=& (1,1) & & & & & & & & \ ec{x}_3 &=& (0,3) & & & & & & & & \ ec{x}_3 &=& (1,0,3) & & & & & & \ ec{x}_3 &=& (1,0,3) & & & & & \ ec{x}_1 &=& (1,0,3) & & & & \ ec{x}_2 &=& ec{x}_1 &=& \ ec{x}_1 &=& ec$$

$$y_1 = -1$$

 $y_2 = 1$
 $y_3 = 1$



Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $(-1) \cdot (1w_0 + 0w_1 + 0w_2) = -w_0 \ge 1$ $1 \cdot (1w_0 + 1w_1 + 1w_2) = w_0 + w_1 + w_2 \ge 1$ $1 \cdot (1w_0 + 0w_1 + 3w_2) = w_0 + 3w_2 \ge 1$

Can be solved using a quadratic programming solver.

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Can be solved using a quadratic programming solver.

To solve by hand, assume that we know that $\vec{x_1}$ and $\vec{x_2}$ are support vectors.

Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $-w_0 = 1$ $w_0 + w_1 + w_2 = 1$ $w_0 + 3w_2 \ge 1$

Note that the equality constraints correspond to our assumption that $\vec{x_1}$ and $\vec{x_2}$ are support vectors.

Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $-w_0 = 1$ $w_0 + w_1 + w_2 = 1$ $w_0 + 3w_2 \ge 1$ Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $-w_0 = 1$ $w_0 + w_1 + w_2 = 1$ $w_0 + 3w_2 \ge 1$

can be transformed to

Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $w_1 + w_2 = 2$ $3w_2 \ge 2$ Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $w_1 + w_2 = 2$ $3w_2 \ge 2$ Find \vec{w} minimizing $w_1^2 + w_2^2$ under the constraints $w_1 + w_2 = 2$ $3w_2 \ge 2$

Substituting $w_2 = 2 - w_1$ into the quadratic function we obtain

$$w_1^2 + (2 - w_1)^2 = w_1^2 + w_1^2 - 4w_1 + 4 = 2w_1^2 - 4w_1 + 4$$

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which reduces our problem to

Find \vec{w} minimizing $2w_1^2 - 4w_1 + 4$ under the constraint $w_1 \leq \frac{4}{3}$

Is solved by

 $w_1 = 1$

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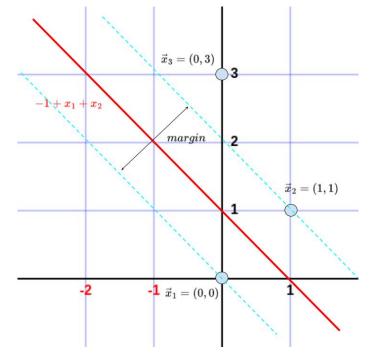
 $w_0 = -1$

The final model is

 $h[\vec{w}](\vec{x}) = -1 + x_1 + x_2$

The separating hyperplane is determined by

 $-1 + x_1 + x_2 = 0$



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... the improvement by finding the maximum margin classifier does not seem to be so strong ... right?

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But why the SVM have been so successful?

 \ldots the improvement by finding the maximum margin classifier does not seem to be so strong \ldots right?

The answer lies in their ability to deal with non-linearly separable sets in an efficient way using so called *kernel trick* (see a later lecture).

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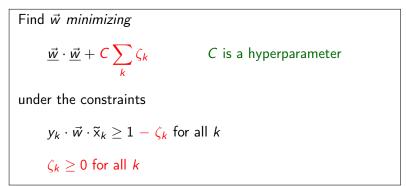
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 - This iterative procedure decreases the (general) cost function.

Soft-margin SVM

Tradeo-off few misclassifications with a wide margin for the rest.



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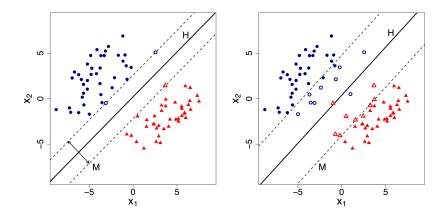
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Find
$$\vec{w}$$
 minimizing
 $\underline{\vec{w}} \cdot \underline{\vec{w}} + C \sum_{k} \zeta_{k}$ C is a hyperparameter
under the constraints
 $y_{k} \cdot \vec{w} \cdot \tilde{x}_{k} \ge 1 - \zeta_{k}$ for all k
 $\zeta_{k} \ge 0$ for all k

which is the same as the following *unconstrained* optimization:

Find \vec{w} minimizing the hinge loss $\underline{\vec{w}} \cdot \underline{\vec{w}} + C \sum_{k} \max(0, 1 - y_k \cdot \vec{w} \cdot \widetilde{x}_k)$

Hard vs Soft Margin SVM



Source: Dishaa Agarwal https://www.analyticsvidhya.com/blog/2021/04/insight-into-svm-support-vector-machine-along-with-code/

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- SVMs can be applied to complex data types beyond feature vectors (e.g. graphs, sequences, relational data) by designing kernel functions for such data.
- SVM techniques have been extended to a number of tasks such as regression [Vapnik et al. '97], principal component analysis [Schölkopf et al. '99], etc.