

# On Decidability of MSO Theories of Representable Matroids

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# 1 Motivation

## Graph Tree-Width and Logic

- [Seese, 1975] Undecidability of an *MSO theory of large grids*.
- [Robertson and Seymour, 80's – 90's] The *Graph Minor Project*: WQO of (finite) graphs by minors, notion of tree-width, algorithmic consequences.
- [Courcelle, 1988] Decidability of an *MSO theory* of graphs: The class of all (finite) graphs of bounded tree-width has decidable  $MS_2$  theory. (Independently by [Arnborg, Lagergren, and Seese, 1991].)
- [Seese, 1991] Decidability of the  $MS_2$  theory *implies bounded tree-width*.

Results closely related to *linear-time algorithms* on bounded tree-width graphs.

## Extending to Matroids

- [Geelen, Gerards, Robertson, Whittle, and . . . , late 90's – future] Extending the *ideas of graph minors* to matroids (over finite fields).
- [PH, 2002] *Decidability for matroids*: The class of all  $GF(q)$ -representable matroids of bounded branch-width has a decidable MSO theory.
- [PH, Seese] Decidability of matr. MSO *implies bounded branch-width*.

## 2 Basics of Matroids

A **matroid** is a pair  $M = (E, \mathcal{B})$  where

- $E = E(M)$  is the *ground set* of  $M$  (elements of  $M$ ),
- $\mathcal{B} \subseteq 2^E$  is a collection of *bases* of  $M$ ,
- the bases satisfy the “exchange axiom”  
 $\forall B_1, B_2 \in \mathcal{B}$  and  $\forall x \in B_1 - B_2$ ,  
 $\exists y \in B_2 - B_1$  s.t.  $(B_1 - \{x\}) \cup \{y\} \in \mathcal{B}$ .

**Otherwise**, a *matroid* is a pair  $M = (E, \mathcal{I})$  where

- $\mathcal{I} \subseteq 2^E$  is the collection of *independent sets* (subsets of bases) of  $M$ .

The definition was inspired by an abstract view of *independence* in linear algebra and in combinatorics [Whitney, Birkhoff, Tutte, ...].

Notice **exponential amount of information** carried by a matroid.

Literature: J. Oxley, Matroid Theory, Oxford University Press 1992,1997.

Some **elementary matroid terms** are

- independent set = a subset of some basis,  
dependent set = not independent,
- circuit = minimal dependent set of elements,  
triangle = circuit on 3 elements,
- hyperplane = maximal set containing no basis,
- rank function  $r_M(X)$  = maximal size of an  $M$ -independent subset  
 $I_X \subseteq X$  (“dimension” of  $X$ ).

(Notation is taken from linear algebra and from graph theory...)

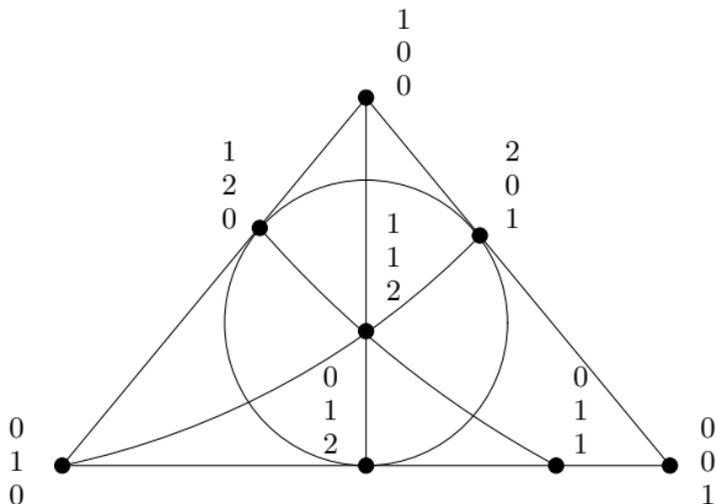
Axiomatic descriptions of matroids via independent sets, circuits, hyperplanes, or rank function are possible, and often used.

**Vector matroid** — a straightforward motivation:

- Elements are vectors over  $\mathbb{F}$ ,
- independence is usual **linear independence**,
- the vectors are considered as columns of a matrix  $\mathbf{A} \in \mathbb{F}^{r \times n}$ .  
( $\mathbf{A}$  is called a **representation** of the matroid  $M(\mathbf{A})$  over  $\mathbb{F}$ .)

Not all matroids are vector matroids.

An example of a rank-3 vector matroid with 8 elements over  $GF(3)$ :



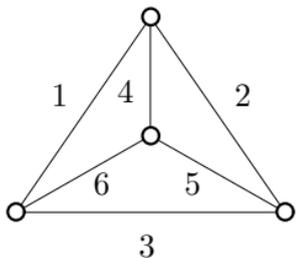
**Graphic matroid**  $M(G)$  — the combinatorial link:

- Elements are the **edges** of a graph,
- independence  $\sim$  **acyclic** edge subsets,
- bases  $\sim$  spanning (maximal) forests,
- circuits  $\sim$  graph cycles,
- the **rank function**  $r_M(X) =$  the number of vertices minus the number of components induced by  $X$ .

Only few matroids are graphic, but all *graphic ones are vector matroids* over any field.

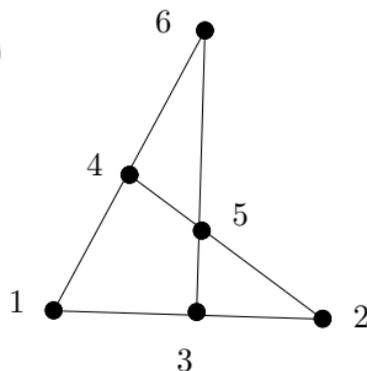
**Example:**

$K_4$



$\rightarrow$

$M(K_4)$



## Matroid operations

**Rank of  $X$**   $\sim$  **matrix rank**, or the number of vertices minus the number of components induced by  $X$  in graphs.

**Matroid duality**  $M^*$  (exchanging bases with their complements)  
 $\sim$  **topological duality** in planar graphs, or **transposition** of standard-form matrices (i.e. without some basis).

**Matroid element deletion**  $\sim$  usual deletion of a graph edge or a vector.

**Matroid element contraction** (corresponds to **deletion in the dual** matroid)  
 $\sim$  edge contraction in a graph, or projection of the matroid from a vector (i.e. a linear transformation having a kernel formed by this vector).

**Matroid minor** — obtained by a sequence of element **deletions and contractions**, order of which does not matter.

### 3 MSO Theories

**MSOL** – monadic second-order logic:

propositional + quantification over elements and sets.

MSOL + class of structures  $\implies$  **MSO theory** (of the structures).

#### For graphs

- *Adjacency graphs* – formed by vertices and an adjacency relation.  
→ *MS<sub>1</sub> theory*.
- *Incidence graphs* – formed by vertices and edges (two-sorted structure), with an incidence relation.  
→ *MS<sub>2</sub> theory*.

#### Decidability of theories

A theory  $\text{Th}_L(\mathcal{S})$  – language  $L$  (=MSO) applied to a class  $\mathcal{S}$  of structures.

*Input:* A sentence  $\phi \in L$  (closed formula).

*Question:* Is  $\mathcal{S} \models \phi$ ? In other words, is  $\phi$  true for **all structures**  $S \in \mathcal{S}$ ?

This problem algorithmically solvable  $\leftrightarrow \text{Th}_L(\mathcal{S})$  *decidable*.

## MSO Theory of Matroids

A **matroid in logic** – the ground set  $E = E(M)$  with all subsets  $2^E$ ,  
– and a predicate *indep* on  $2^E$ , s.t. *indep*( $F$ ) iff  $F \subseteq E$  is independent.

The *MSO theory of matroids* – language of MSOL applied to such matroids.

Basic expressions:

- $\text{basis}(B) \equiv \text{indep}(B) \wedge \forall D (B \not\subseteq D \vee B = D \vee \neg \text{indep}(D))$   
A basis is a maximal independent set.
- $\text{circuit}(C) \equiv \neg \text{indep}(C) \wedge \forall D (D \not\subseteq C \vee D = C \vee \text{indep}(D))$   
A circuit  $C$  is dependent, but all proper subsets of  $C$  are independent.
- $\text{cocircuit}(C) \equiv \forall B [\text{basis}(B) \rightarrow \exists x (x \in B \wedge x \in C)] \wedge$   
 $\wedge \forall X [X \not\subseteq C \vee X = C \vee \exists B (\text{basis}(B) \wedge \forall x (x \notin B \vee x \notin X))]$   
A cocircuit  $C$  (a dual circuit) intersects every basis, but each proper subset of  $C$  is disjoint from some basis.

**Theorem 3.1.** (PH) *Any  $MS_2$  sentence about a graph  $G$  can be formulated as a (matroidal) MSO sentence about the cycle matroid  $M(G \uplus K_3)$ .*

( $G \uplus K_3$ , adding three vertices adjacent to everything, makes a *3-connected graph*.)

## Computability and decidability on matroids

Graph or matroid *branch-width* – like tree-width, being “close to a tree”.

A matroid  $M$  of bounded branch-width  $\rightarrow$  a *parse tree*  $\bar{T}$  for  $M = P(\bar{T})$ .

**Theorem 3.2.** (PH) *Let  $\mathbb{F}$  be a finite field,  $t \geq 1$ , and  $\phi$  be a sentence in MSOL of matroids. Then there exists a (constructible) finite tree automaton  $\mathcal{A}_t^\phi$  accepting those parse trees for matroids which possess  $\phi$ , i.e. those  $\bar{T}$  such that  $P(\bar{T}) \models \phi$ .*

This result, together with an algorithm constructing the parse tree, provides an efficient way to verify MSO-definable properties over matroids of bounded branch-width.

**Corollary 3.3.** *If  $\mathcal{B}_t$  is the class of all matroids representable over  $\mathbb{F}$  of branch-width at most  $t$ , then the theory  $\text{Th}_{MSO}(\mathcal{B}_t)$  is decidable.*

Sketch: It is enough to verify emptiness of the complementary automaton  $\neg\mathcal{A}_t^\phi$  over all valid parse trees.

Our **main result** reads:

**Theorem 3.4.** *Let  $\mathbb{F}$  be a finite field, and let  $\mathcal{N}$  be a class of matroids that are representable by matrices over  $\mathbb{F}$ . If the monadic second-order theory  $\text{Th}_{MSO}(\mathcal{N})$  is decidable, then the class  $\mathcal{N}$  has bounded branch-width.*

(Analogous to a result of [Seese, 1991] on the  $MS_2$  theory of graphs.)

## 4 Interpretation of Theories

... the way to prove (un)decidability of logic theories.

An interpretation  $I$  of a theory  $\text{Th}_L(\mathcal{K})$  in a theory  $\text{Th}_{L'}(\mathcal{K}')$  is as follows:

$$\begin{array}{ccc} \forall \varphi \in L & \xrightarrow{I} & \varphi^I \in L' \\ \forall H \in \mathcal{K} & & G \in \mathcal{K}' \\ \\ H \simeq G^I & \xleftarrow{I} & \forall G \end{array}$$

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We are using the results of:

**Theorem 4.1.** (Rabin) *If  $\text{Th}_L(\mathcal{K})$  is interpretable in  $\text{Th}_{L'}(\mathcal{K}')$ , then undecidability of  $\text{Th}_L(\mathcal{K})$  implies undecidability of  $\text{Th}_{L'}(\mathcal{K}')$ .*

**Theorem 4.2.** (Seese) *Let  $\mathcal{K}$  be a class of adjacency graphs such that for every integer  $m > 1$  there is a graph  $G \in \mathcal{K}$  such that  $G$  has the  $m \times m$  grid  $Q_m$  as an induced subgraph. Then the  $MS_1$  theory of  $\mathcal{K}$  is *undecidable*.*

**Theorem 4.3.** (Geelen, Gerards, Whittle) *For every finite field  $\mathbb{F}$ ; a class  $\mathcal{N}$  of  $\mathbb{F}$ -representable matroids has bounded branch-width if and only if there exists a constant  $m$  such that *no matroid  $N \in \mathcal{N}$  has a minor isomorphic to  $M(Q_m)$ .**

Hence, we interpret the  $MS_1$  theory of grids in the matroidal MSO theory of  $\mathcal{N} \dots$

## Sketch of the interpretation proof

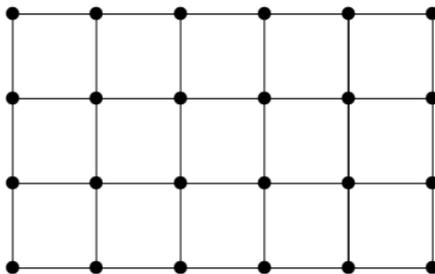
The seemingly straightforward way – interpreting graphs ( $\sim$ large grids) in their cycle matroids, gets stuck due to **technical details**.

(Definability of the underlying graphs, insufficient connectivity, ...)

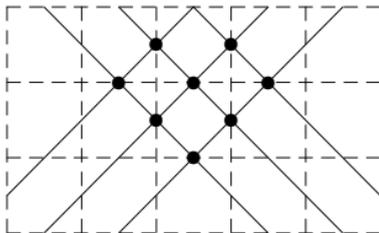
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Our approach to *Theorem 3.4* (“decidability  $\Rightarrow$  bounded branch-width”):

- If the matroid theory  $\text{Th}_{MSO}(\mathcal{N})$  is decidable, then so is the theory  $\text{Th}_{MSO}(\mathcal{N}_{\text{minor}})$  of all minors of the class  $\mathcal{N}$  (i.e. **minors are definable** in matroid MSOL).
- By Theorem 4.3 [Geelen, Gerards, Whittle], the class  $\mathcal{N}_{\text{minor}}$  contains arbitrary matroid grids  $M(Q_m)$  if  $\mathcal{N}$  has unbounded branch-width.



- A *4CC-graph of a matroid  $M$*  is the graph on the vertex set  $E(M)$ , with edges joining those pairs of elements which belong to a common 4-element circuit and a 4-element cocircuit (bond) in  $M$ .



The 4CC-graph of the grid matroid  $M(Q_m)$  ( $m \geq 6$  even) has an induced subgraph isomorphic to the grid  $Q_{m-2}$ .

- Let  $\mathcal{F}_{\mathcal{N}}$  be the class of all 4CC-graphs of matroids in  $\mathcal{N}$ . Then the theory  $\text{Th}_{MS_1}(\mathcal{F}_{\mathcal{N}})$  is interpretable in the theory  $\text{Th}_{MSO}(\mathcal{N})$ . Hence by Theorem 4.1 [Rabin], undecidability of  $\text{Th}_{MS_1}(\mathcal{F}_{\mathcal{N}})$  implies **undecidability of  $\text{Th}_{MSO}(\mathcal{N})$** .
- Finally, Theorem 4.2 [Seese] states that  $\text{Th}_{MS_1}(\mathcal{F}_{\mathcal{N}})$  is undecidable if  $\mathcal{F}_{\mathcal{N}}$ , hence also if  $\mathcal{N}$ , contain large grids. Conversely, if  $\text{Th}_{MSO}(\mathcal{N})$  is decidable, then the previous (large grids) cannot be true, and **so  $\mathcal{N}$  has bounded branch-width**. ■