

The Satisfiability Problem for Probabilistic CTL

Tomáš Brázdil

Vojtěch Forejt

Jan Křetínský

Antonín Kučera

Faculty of Informatics, Masaryk University,

Botanická 68a, 60200 Brno,

Czech Republic.

{brazdil,forejt,xkretins,kucera}@fi.muni.cz

Abstract

We study the satisfiability problem for qualitative PCTL (Probabilistic Computation Tree Logic), which is obtained from “ordinary” CTL by replacing the EX, AX, EU, and AU operators with their qualitative counterparts $X^{>0}$, $X^{=1}$, $U^{>0}$, and $U^{=1}$, respectively. As opposed to CTL, qualitative PCTL does not have a small model property, and there are even qualitative PCTL formulae which have only infinite-state models. Nevertheless, we show that the satisfiability problem for qualitative PCTL is **EXPTIME**-complete and we give an exponential-time algorithm which for a given formula φ computes a finite description of a model (if it exists), or answers “not satisfiable” (otherwise). We also consider the finite satisfiability problem and provide analogous results. That is, we show that the finite satisfiability problem for qualitative PCTL is **EXPTIME**-complete, and every finite satisfiable formula has a model of an exponential size which can effectively be constructed in exponential time. Finally, we give some results about the quantitative PCTL, where the numerical bounds in probability constraints can be arbitrary rationals between 0 and 1. We prove that the problem whether a given quantitative PCTL formula φ has a model of the branching degree at most k , where $k \geq 2$ is an arbitrary but fixed constant, is highly undecidable. We also show that every satisfiable formula φ has a model with branching degree at most $|\varphi| + 2$. However, this does not yet imply the undecidability of the satisfiability problem for quantitative PCTL, and we in fact conjecture the opposite.

1. Introduction

Probabilistic CTL (PCTL) [14] is a probabilistic extension of the well-known branching-time logic CTL [8] obtained by replacing the existential and universal path quantifiers

with the probabilistic operator, which allows to quantify the probability of all runs that satisfy a given path formula. More precisely, the syntax of PCTL is built upon atomic propositions, using Boolean connectives and operators “next” and “until” of the form $X^{\bowtie \varrho} \varphi$ and $\varphi_1 U^{\bowtie \varrho} \varphi_2$, respectively, where \bowtie is a numerical comparison such as \leq or $>$, and $\varrho \in [0, 1]$ is a rational constant. We also use the standard abbreviations $F\varphi$ and $G\varphi$ to denote the path formulae $\text{tt}U\varphi$ and $\neg F\neg\varphi$. A simple example of a PCTL formula is $G^{=1}(a \Rightarrow F^{\geq 0.2}b)$ which says “in each reachable state that satisfies a , the probability of visiting a state satisfying b is at least 0.2”. Formally, PCTL formulae are interpreted over Markov chains where each state is assigned a subset of atomic propositions that are valid in a given state.

In this paper, we study the satisfiability problem for the *qualitative fragment* of PCTL, which is obtained by restricting the probabilistic operator to its qualitative forms (i.e., the constant ϱ in $X^{\bowtie \varrho} \varphi$ and $\varphi_1 U^{\bowtie \varrho} \varphi_2$ can be just 0 or 1). Since the syntax of PCTL includes negation, we need to consider only the probability constraints >0 and $=1$ (for example, the formula $X^{<1} \varphi$ is equivalent to $\neg X^{=1} \varphi$). Hence, there are only four modal operators $X^{>0}$, $X^{=1}$, $U^{>0}$, and $U^{=1}$. At first glance, they seem to be closely related to standard CTL operators EX, AX, EU, and AU, respectively. To a large extent, this is true for $X^{>0}$, $X^{=1}$, $U^{>0}$, but the properties of $U^{=1}$ and AU are very different, which leads to the phenomena described in the next paragraphs.

First, let us recall known results about the satisfiability problem for CTL and related logics. For CTL, the problem is known to be **EXPTIME**-complete [9]. In the same paper [9], it is also shown that CTL has a *small model property*, i.e., every satisfiable CTL formula φ has a finite-state model whose size is exponential in φ . For the logic CTL*, the satisfiability problem is **2-EXPTIME**-complete [10, 21]. The **2-EXPTIME** lower bound holds even for the weaker logic CTL+ [17]. The complexity of the satisfiability and validity problems for other fragments of CTL and CTL* (such as the existential and universal fragments) has also been studied (see, e.g., [20]). The satisfiability for the modal μ -calculus is

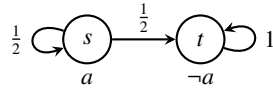
The presented work has been supported by the research center Institute for Theoretical Computer Science (ITI), project No. 1M0545.

EXPTIME-complete [2, 13], and even this powerful logic has the small model property [18]. The satisfiability and validity for some fragments of the modal μ -calculus have been studied in greater depth in [15]. To the best of our knowledge, the satisfiability problem for probabilistic CTL has not yet been examined. Nonetheless, there are some related results about PCTL model-checking (both for infinite- and finite-state systems, see e.g. [7, 16, 12, 11, 6]) and strategy synthesis for Markov decision processes with branching-time objectives [1, 19, 3, 5].

As we already noted, the qualitative PCTL formulae seem to be rather similar to “ordinary” CTL formulae. One may even be tempted to think that a qualitative PCTL formula φ is satisfiable iff the corresponding CTL formula φ' is satisfiable, where φ' is obtained from φ by replacing each occurrence of $X^{>0}$, $X^{=1}$, $U^{>0}$, and $U^{=1}$ with EX, AX, EU, and AU, respectively. This is not true; for example, the qualitative PCTL formula

$$\varphi \equiv a \wedge (G^{=1}(a \Rightarrow X^{>0}a)) \wedge (F^{=1}\neg a)$$

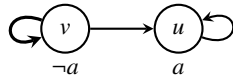
has the following model:



Note that $s \models \varphi$ because the probability of all runs initiated in s which eventually visit t is equal to 1. However, the corresponding CTL formula

$$\varphi' \equiv a \wedge (AG(a \Rightarrow EXa)) \wedge (AF\neg a)$$

is not satisfiable. Further, qualitative PCTL does not have the small model property, and there are even satisfiable qualitative PCTL formulae that only have *infinite-state* models. A simple example of such a formula is $G^{>0}(\neg a \wedge F^{>0}a)$. Intuitively, this formula does not have a finite-state model, because for every finite-state Markov chain M there is a fixed constant $\varepsilon > 0$ such that every state of M which satisfies $F^{>0}a$ also satisfies $F^{2\varepsilon}a$. This means that the probability of all runs satisfying the path formula $G(\neg a \wedge F^{>0}a)$ is zero, hence $G^{>0}(\neg a \wedge F^{>0}a)$ does not hold. On the other hand, $G^{>0}(\neg a \wedge F^{>0}a)$ has an infinite-state model, which admits a simple symbolic description in a form of the following *marked graph*:

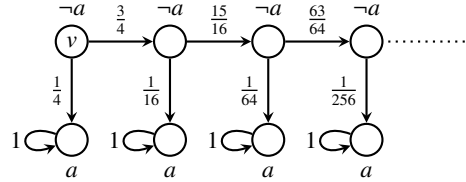


In general, a marked graph is a finite binary graph where each node has at least one out-going transition, and some transitions are “marked” (in the above figure, the only marked transition is the loop on v , which is indicated by a thick arrow). Each node v in a given marked graph \mathcal{G} determines a unique infinite-state Markov chain $M_{\mathcal{G}}$ obtained

by unfolding the structure of \mathcal{G} into an infinite tree (with the root v), where the probabilities of outgoing transitions at each state s of $M_{\mathcal{G}}$ are determined as follows:

- if all outgoing transitions of s are either marked or non-marked, then all of them have the same probability p ;
- otherwise, the probability of all marked transitions is p_1 , the probability of all non-marked transitions is p_2 , and the total probability of all marked transitions is $1 - 1/4^{d+1}$, where d is the distance of s from the root of $M_{\mathcal{G}}$ (note that p_1 and p_2 are uniquely determined by these conditions).

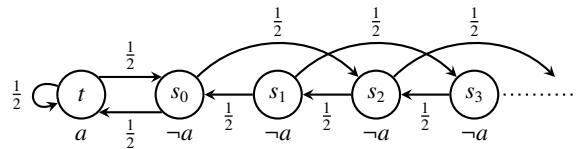
For example, the initial part of the chain $M_{\mathcal{G}}$, where \mathcal{G} is the marked graph above, looks as follows (for simplicity, the loop on u is not unfolded):



Observe that $v \models G^{>0}(\neg a \wedge F^{>0}a)$, because the only run which satisfies the formula $G(\neg a \wedge F^{>0}a)$ has a positive probability.

We prove that *every* satisfiable qualitative PCTL formula φ has a model which can be represented by a marked graph whose size is exponential in $|\varphi|$, and we design an exponential-time algorithm which for a given φ computes a suitable marked graph if it exists, and outputs “unsatisfiable” otherwise. Hence, the satisfiability problem for qualitative PCTL is in **EXPTIME** and we also give the matching lower bound (the lower bound is proved by standard techniques). Since the logic PCTL contains negation and **EXPTIME** is closed under complement, the validity problem for qualitative PCTL is also **EXPTIME**-complete.

One may also ask whether the use of exponentially small probabilities in the way indicated above is indeed necessary. For example, the mentioned formula $G^{>0}(\neg a \wedge F^{>0}a)$ has another infinite-state model, where the probability of every transition is exactly $1/2$. The model looks as follows:



We have that $s_0 \models G^{>0}(\neg a \wedge F^{>0}a)$. To see this, realize that the probability of all runs initiated in s_0 which do not visit t is positive (this is a standard result of Markov chain theory; the exact value of this probability is $(3 - \sqrt{5})/2$). However, the use of “exponentially small probabilities” is

unavoidable in some cases. For example, one can easily show that the formula $G^{=1}(X^{>0}a) \wedge G^{>0}\neg a$ does not have a model where the probabilities of all transitions are uniformly bounded from below. However, the formula $G^{=1}(X^{>0}a) \wedge G^{>0}\neg a$ is satisfiable, which is witnessed by the marked graph for the formula $G^{>0}(\neg a \wedge F^{>0}a)$ constructed earlier.

Since some qualitative PCTL formulae have only infinite-state models, we also consider the *finite satisfiability* problem, where we ask whether a given qualitative PCTL formula has a *finite-state* model. We obtain similar results as for general satisfiability. We show that the existence of a finite-state model implies the existence of a model whose size is exponential in the size of a given formula, and we give an exponential-time algorithm which computes such a model if it exists, and outputs “not finite satisfiable” otherwise. Hence, the finite satisfiability/validity problems for qualitative PCTL are also in **EXPTIME**, and in fact **EXPTIME**-complete.

Finally, we give some results concerning the satisfiability problem for general PCTL. We show that the problem whether a given PCTL formula has a model where the branching degree is bounded by a fixed k is *highly undecidable* for every $k \geq 2$ (note that the k is *not* a part of the problem instance, but a fixed parameter—for a different choice of k we have a different problem, and each of these infinitely many problems is highly undecidable). Then, we show that every satisfiable PCTL formula φ has a model with branching degree at most $|\varphi| + 2$. At first glance, one may be tempted to think that these two results imply the undecidability of the satisfiability problem for the general PCTL, but in fact it is *not* the case. Despite a reasonable amount of effort, we did not manage to extend the undecidability proof to the satisfiability problem for PCTL, and the difficulties seem to be fundamental (at least, the undecidability proof techniques developed in [3, 6] specifically for probabilistic systems seem insufficient). On the other hand, there are some structural regularities in PCTL models which suggest that the problem might in fact be decidable. We present the decidability hypothesis as an open conjecture which surely deserves further attention.

Due to space constraints, we had to omit or shorten some proofs. These can be found in the full version of this paper [4].

2. Definitions

In this paper, we use \mathbb{N} , \mathbb{N}_0 , \mathbb{Q} , and \mathbb{R} to denote the sets of positive integers, non-negative integers, rational numbers, and real numbers, respectively. We also use the standard notation for intervals of real numbers, writing, e.g., $(0, 1]$ to denote the set $\{x \in \mathbb{R} \mid 0 < x \leq 1\}$.

The set of all finite words over a given alphabet Σ is denoted Σ^* , and the set of all infinite words over Σ is denoted Σ^ω . We also use Σ^+ to denote the set $\Sigma^* \setminus \{\varepsilon\}$ where ε is the empty word. The length of a given $w \in \Sigma^* \cup \Sigma^\omega$ is denoted $len(w)$, where the length of an infinite word is ω . Given a word (finite or infinite) over Σ , the individual letters of w are denoted $w(0), w(1), \dots$.

Let $V \neq \emptyset$, and let $\rightarrow \subseteq V \times V$ be a *total* relation (i.e., for every $v \in V$ there is some $u \in V$ such that $v \rightarrow u$). A *path* in V is a finite or infinite word $w \in V^+ \cup V^\omega$ such that $w(i-1) \rightarrow w(i)$ for every $1 \leq i < len(w)$. Sometimes we also write $s_0 \rightarrow \dots \rightarrow s_n$ to denote the finite path s_0, \dots, s_n , particularly in situations when the underlying relation \rightarrow is not completely obvious from the context. We also use \rightarrow^+ to denote the transitive closure of \rightarrow , and \rightarrow^* to denote the reflexive and transitive closure of \rightarrow . A *run* in V is an infinite path in V . The set of all runs that start with a given finite path w is denoted $Run(w)$. Let $U \subseteq V$. We say that U is *strongly connected* if $v \rightarrow^+ u$ for all $v, u \in U$ (from a graph-theoretic point of view, this definition is somewhat non-standard, because a singleton $\{s\}$ is strongly connected iff $s \rightarrow s$). Further, we say that U is a *strongly connected component (SCC)* if $U \neq \emptyset$ is a maximal strongly connected subset of V , and U is a *bottom SCC (BSCC)* if U is a SCC and for every $u \in U$ and every $u \rightarrow v$ we have that $v \in U$.

A *probability distribution* over a finite or countably infinite set X is a function $f : X \rightarrow [0, 1]$ such that $\sum_{x \in X} f(x) = 1$. A probability distribution f over X is *positive* if $f(x) > 0$ for every $x \in X$, and *uniform* if $f(x) = f(y)$ for all $x, y \in X$. A σ -*algebra* over a set Ω is a set $\mathcal{F} \subseteq 2^\Omega$ that includes Ω and is closed under complement and countable union. A *probability space* is a triple $(\Omega, \mathcal{F}, \mathcal{P})$ where Ω is a set called *sample space*, \mathcal{F} is a σ -algebra over Ω whose elements are called *events* (or *measurable sets*), and $\mathcal{P} : \mathcal{F} \rightarrow [0, 1]$ is a *probability measure* such that, for each countable collection $\{X_i\}_{i \in I}$ of pairwise disjoint elements of \mathcal{F} , $\mathcal{P}(\bigcup_{i \in I} X_i) = \sum_{i \in I} \mathcal{P}(X_i)$, and moreover $\mathcal{P}(\Omega) = 1$.

Definition 2.1 (Markov Chain). A Markov chain is a triple $M = (St, \rightarrow, Prob)$ where St is a finite or countably infinite set of states, $\rightarrow \subseteq St \times St$ is a total transition relation, and $Prob$ is a function which to each state $s \in St$ assigns a positive probability distribution over the outgoing transitions of s . As usual, we write $s \xrightarrow{x} t$ when $s \rightarrow t$ and x is the probability of $s \rightarrow t$.

When defining the semantics of PCTL (see below), we need to measure the probability of certain sets of runs. Formally, to every $s \in St$ we associate the probability space $(Run(s), \mathcal{F}, \mathcal{P})$ where \mathcal{F} is the σ -algebra generated by all *basic cylinders* $Run(w)$ where w is a finite path starting with s , and $\mathcal{P} : \mathcal{F} \rightarrow [0, 1]$ is the unique probability measure such that $\mathcal{P}(Run(w)) = \prod_{i=1}^{len(w)-1} x_i$ where $w(i-1) \xrightarrow{x_i} w(i)$

for every $1 \leq i < \text{len}(w)$. If $\text{len}(w) = 1$, we put $\mathcal{P}(\text{Run}(w)) = 1$. Hence, only certain subsets of $\text{Run}(s)$ are measurable, but in this paper we only deal with “safe” subsets that are guaranteed to be in \mathcal{F} .

Definition 2.2. Let $Ap = \{a, b, c, \dots\}$ be a countably infinite set of atomic propositions. The syntax of PCTL state and path formulae is defined by the following abstract syntax equations:

$$\begin{aligned}\varphi &::= a \mid \neg\varphi \mid \varphi_1 \wedge \varphi_2 \mid \mathcal{P}^{\bowtie\varrho}\psi \\ \psi &::= X\varphi \mid \varphi_1 U\varphi_2\end{aligned}$$

Here a ranges over Ap , \bowtie is a comparison (i.e., $\bowtie \in \{<, >, \leq, \geq, =, \neq\}$), and $\varrho \in [0, 1]$ is a rational constant. The qualitative fragment of PCTL is obtained by restricting ϱ to 0 and 1 (to prevent a confusion between PCTL and qualitative PCTL, we sometimes refer to “quantitative PCTL” instead of PCTL).

In the rest of this paper, “PCTL formula” means “PCTL state formula”. Since the probabilistic operator $\mathcal{P}^{\bowtie\varrho}$ is always bound to exactly one modal connective, we simplify the syntax by writing $X^{\bowtie\varrho}\varphi$ instead of $\mathcal{P}^{\bowtie\varrho}(X\varphi)$, and $\varphi_1 U^{\bowtie\varrho}\varphi_2$ instead of $\mathcal{P}^{\bowtie\varrho}(\varphi_1 U\varphi_2)$. For every PCTL formula φ , the symbol $\hat{\varphi}$ denotes either the formula ξ or $\neg\xi$, depending on whether φ is of the form $\neg\xi$ or not, respectively.

Let $M = (St, \rightarrow, Prob)$ be a Markov chain, and let $\nu : St \rightarrow 2^{Ap}$ be a valuation. The validity of PCTL formulae in the states of M is defined inductively as follows:

$$\begin{aligned}M, s \models^{\nu} a & \quad \text{iff} \quad a \in \nu(s) \\ M, s \models^{\nu} \neg\varphi & \quad \text{iff} \quad M, s \not\models^{\nu} \varphi \\ M, s \models^{\nu} \varphi_1 \wedge \varphi_2 & \quad \text{iff} \quad M, s \models^{\nu} \varphi_1 \text{ and } M, s \models^{\nu} \varphi_2 \\ M, s \models^{\nu} X^{\bowtie\varrho}\varphi & \quad \text{iff} \quad \mathcal{P}(\{w \in \text{Run}(s) \mid M, w(1) \models^{\nu} \varphi\}) \bowtie \varrho \\ M, s \models^{\nu} \varphi_1 U^{\bowtie\varrho}\varphi_2 & \quad \text{iff} \quad \mathcal{P}(\{w \in \text{Run}(s) \mid \exists j \geq 0 : M, w(j) \models^{\nu} \varphi_2 \\ & \quad \text{and } \forall 0 \leq i < j : M, w(i) \models^{\nu} \varphi_1\}) \bowtie \varrho\end{aligned}$$

A PCTL formula φ is *satisfiable* if $M, s \models^{\nu} \varphi$ for some M , s , and ν . The formula φ is *finite satisfiable* if $M, s \models^{\nu} \varphi$ for some finite-state M . The formula φ is *valid* if $M, s \models^{\nu} \varphi$ for all M , s , and ν .

3. A Solution for Qualitative PCTL

In this section, we solve the satisfiability and the finite satisfiability problems for qualitative PCTL. To emphasize (and identify) the main difference between qualitative PCTL and CTL, we follow the traditional approach based on filtration through Fischer-Ladner closure [13]. In the case of CTL, the main problem with this technique is the introduction of new cycles which can “spoil” universally quantified formulae such as $AF\varphi$ [9]. In the case of qualitative PCTL, these new cycles are not a problem because, roughly speaking, they are either harmless or they are eventually left with probability 1. On the other hand, the *invalidity* of a formula

$\varphi_1 U^=1\varphi_2$ cannot be witnessed just by a single run which violates the path formula $\varphi_1 U\varphi_2$, because this single run can have zero probability. This means that the heart of our construction for qualitative PCTL is actually rather different from the one for CTL.

We start by recalling a folklore observation which is used quite frequently in the proofs of our main results.

Lemma 3.1. Let $M = (St, \rightarrow, Prob)$ be a Markov chain, $\nu : St \rightarrow 2^{Ap}$ a valuation, and $\varphi_1 U^=1\varphi_2$ a qualitative PCTL formula. If $M, s \not\models^{\nu} \varphi_1 U^=1\varphi_2$ for a given $s \in St$, then there are two possibilities:

- There is a finite path $s=s_0 \rightarrow \dots \rightarrow s_n$ such that $M, s_i \models^{\nu} \hat{\varphi}_2$ for all $0 \leq i \leq n$, and $M, s_n \models^{\nu} \hat{\varphi}_1$.
- $\mathcal{P}(\mathcal{R}) > 0$, where \mathcal{R} is the set of all $w \in \text{Run}(s)$ such that $w(i) \models^{\nu} \varphi_1 \wedge \hat{\varphi}_2$ for all $i \in \mathbb{N}_0$. If M is finite-state, this is equivalent to the existence of a finite path $s=s_0 \rightarrow \dots \rightarrow s_n$ and a BSCC α of M such that for every state t that appears in the path or in α we have that $M, t \models^{\nu} \varphi_1 \wedge \hat{\varphi}_2$.

A proof of Lemma 3.1 is simple and standard. Now we recall the Fischer-Ladner closure [13].

Definition 3.2. Let ψ be a qualitative PCTL formula. The closure of ψ , denoted $Cl(\psi)$, is the least set C of PCTL formulae such that $\psi \in C$ and the following conditions are satisfied:

- if $\varphi \in C$, then $\hat{\varphi} \in C$
- if $\varphi_1 \wedge \varphi_2 \in C$, then $\varphi_1, \varphi_2 \in C$
- if $X^{>0}\varphi \in C$, then $\varphi \in C$
- if $X^=1\varphi \in C$, then $\varphi \in C$
- if $\varphi_1 U^{>0}\varphi_2 \in C$, then $\varphi_1, \varphi_2, X^{>0}(\varphi_1 U^{>0}\varphi_2) \in C$
- if $\varphi_1 U^=1\varphi_2 \in C$, then $\varphi_1, \varphi_2, X^=1(\varphi_1 U^=1\varphi_2) \in C$
- if $\varphi_1 U^=1\varphi_2 \in C$, then $\varphi_1 U^{>0}\varphi_2 \in C$

Definition 3.2 mimics the variant of Fischer-Ladner closure used in [9] for the logic CTL. The only notable difference is the last item, where we require that if $\varphi_1 U^=1\varphi_2$ is in the closure, then $\varphi_1 U^{>0}\varphi_2$ is also there. The exact purpose of this rule is clarified in the proofs of our main results.

In our next definition we identify certain formulae that should be satisfied “together” in a given state.

Definition 3.3. A set $S \subseteq Cl(\psi)$ is eligible if for every $\varphi \in Cl(\psi)$ we have that φ or $\hat{\varphi}$ belongs to S , and the following conditions hold:

- if $\varphi \in S$, then $\hat{\varphi} \notin S$
- if $\varphi_1 \wedge \varphi_2 \in S$, then $\varphi_1, \varphi_2 \in S$
- if $\neg(\varphi_1 \wedge \varphi_2) \in S$, then $\hat{\varphi}_1 \in S$ or $\hat{\varphi}_2 \in S$
- if $\varphi_1 U^{>0}\varphi_2 \in S$, then $\varphi_2 \in S$ or $\varphi_1, X^{>0}(\varphi_1 U^{>0}\varphi_2) \in S$

- if $\neg(\varphi_1 U^{>0} \varphi_2) \in S$, then $\hat{\varphi}_1, \hat{\varphi}_2 \in S$ or $\hat{\varphi}_2, \neg X^{>0}(\varphi_1 U^{>0} \varphi_2) \in S$
- if $\varphi_1 U^=1 \varphi_2 \in S$, then $\varphi_2 \in S$ or $\varphi_1, X^=1(\varphi_1 U^=1 \varphi_2) \in S$
- if $\neg(\varphi_1 U^=1 \varphi_2) \in S$, then $\hat{\varphi}_1, \hat{\varphi}_2 \in S$ or $\hat{\varphi}_2, \neg X^=1(\varphi_1 U^=1 \varphi_2) \in S$

Definition 3.4. A pseudo-structure for a qualitative PCTL formula ψ is a pair $\mathcal{A} = (A, \rightarrow)$, where A is a set of eligible subsets of $Cl(\psi)$ and $\rightarrow \subseteq A \times A$ is a total relation.

Every pseudo-structure $\mathcal{A} = (A, \rightarrow)$ for a formula ψ determines a unique Markov chain $M_{\mathcal{A}} = (A, \rightarrow, Prob)$ where *Prob* assigns a uniform probability distribution to every state. Further, to each $\varphi \in Cl(\psi)$ we associate a fresh atomic proposition $[\varphi]$ and define a valuation ν over A such that $[\varphi] \in \nu(S)$ iff $\varphi \in S$. In the following, we write

- $\mathcal{A}, S \models X^{\bowtie q} \varphi$ instead of $M_{\mathcal{A}}, S \models^{\nu} X^{\bowtie q} [\varphi]$
- $\mathcal{A}, S \models \neg X^{\bowtie q} \varphi$ instead of $M_{\mathcal{A}}, S \models^{\nu} \neg X^{\bowtie q} [\varphi]$
- $\mathcal{A}, S \models \varphi_1 U^{\bowtie q} \varphi_2$ instead of $M_{\mathcal{A}}, S \models^{\nu} [\varphi_1] U^{\bowtie q} [\varphi_2]$
- $\mathcal{A}, S \models \neg(\varphi_1 U^{\bowtie q} \varphi_2)$ instead of $M_{\mathcal{A}}, S \models^{\nu} \neg([\varphi_1] U^{\bowtie q} [\varphi_2])$

where “ $\bowtie q$ ” is of the form “ >0 ” or “ $=1$ ”.

As we already mentioned, the invalidity of a formula $\varphi_1 U^=1 \varphi_2$ cannot be witnessed just by a single run that violates the path formula $\varphi_1 U \varphi_2$. A suitable witness for $\neg(\varphi_1 U^=1 \varphi_2)$ is identified in our next definition.

Definition 3.5. Let ψ be a qualitative PCTL formula and $\mathcal{A} = (A, \rightarrow)$ a pseudo-structure for ψ . A witness for a formula $\neg(\varphi_1 U^=1 \varphi_2) \in Cl(\psi)$ in \mathcal{A} is a pseudo-structure $\mathcal{B} = (B, \leftrightarrow)$ where $\emptyset \neq B \subseteq A$ and $\leftrightarrow \subseteq \rightarrow$ such that

- \mathcal{B} is strongly connected.
- For every $S \in B$ we have that $\hat{\varphi}_2 \in S$.
- For every $S \in B$ and every $\xi_1 U^=1 \xi_2 \in S$ we have that $\mathcal{B}, S \models \xi_1 U^=1 \xi_2$.

Definition 3.6. Let ψ be a qualitative PCTL formula. A pseudo-model for ψ is a pseudo-structure $\mathcal{A} = (A, \rightarrow)$ for ψ such that $\psi \in T$ for some $T \in A$, and every $S \in A$ satisfies the following conditions:

- (1) If $\xi \in S$, where ξ is of the form $X^=1 \varphi$, $\neg X^=1 \varphi$, $X^{>0} \varphi$, $\neg X^{>0} \varphi$, $\varphi_1 U^{>0} \varphi_2$, $\neg(\varphi_1 U^{>0} \varphi_2)$, or $\varphi_1 U^=1 \varphi_2$, then $\mathcal{A}, S \models \xi$.
- (2) If $\neg(\varphi_1 U^=1 \varphi_2) \in S$, then one of the following conditions is satisfied:
 - (a) $\mathcal{A}, S \not\models \varphi_1 U^=1 \varphi_2$.
 - (b) There is a witness $\mathcal{B} = (B, \leftrightarrow)$ for $\neg(\varphi_1 U^=1 \varphi_2)$ and a finite path $S_0 \rightarrow \dots \rightarrow S_n$ such that $S_0 = S$, $S_n \in B$, and $\hat{\varphi}_2 \in S_i$ for every $0 \leq i \leq n$.

A pseudo-model is simple if the condition (2) is always satisfied by item (a), i.e., no witness is employed.

The next theorem says that the satisfiability of a given qualitative PCTL formula is always certified by a pseudo-model.

Theorem 3.7. Let ψ be a qualitative PCTL formula. If ψ is satisfiable, then there is a pseudo-model $\mathcal{A} = (A, \mapsto)$ for ψ . Moreover, if ψ is finite-satisfiable, then \mathcal{A} is simple.

Proof. Let us fix a satisfiable qualitative PCTL formula ψ . Then there is a Markov chain $M = (St, \rightarrow, Prob)$, a valuation ν , and a state $s_{\psi} \in St$ such that $M, s_{\psi} \models^{\nu} \psi$. For every $s \in St$, let $[s] = \{\varphi \in Cl(\psi) \mid M, s \models^{\nu} \varphi\}$. We define $A = \{[s] \mid s \in St\}$, and $[s] \mapsto [t]$ iff there are some $s', t' \in St$ such that $[s] = [s']$, $[t] = [t']$, and $s' \rightarrow t'$. We show that $\mathcal{A} = (A, \mapsto)$ is a pseudo-model for ψ . Clearly, all elements of A are eligible, and $\psi \in [s_{\psi}]$. Now let $[s] \in A$ and $\xi \in [s]$. We verify the two conditions of Definition 3.6.

Condition (1). If ξ is of the form $X^=1 \varphi$, $\neg X^=1 \varphi$, $X^{>0} \varphi$, $\neg X^{>0} \varphi$, or $\varphi_1 U^{>0} \varphi_2$, then it is easy to show that $\mathcal{A}, [s] \models \xi$.

Let $\xi = \neg(\varphi_1 U^{>0} \varphi_2)$, and let us assume (for the sake of deriving a contradiction) that $\mathcal{A}, [s] \not\models \neg(\varphi_1 U^{>0} \varphi_2)$, i.e., $\mathcal{A}, [s] \models \varphi_1 U^{>0} \varphi_2$. Then there is a finite path $[s_0] \mapsto \dots \mapsto [s_n]$, where $n \in \mathbb{N}_0$, $[s] = [s_0]$, $\varphi_2 \in [s_n]$, and $\varphi_1 \in [s_i]$ for all $0 \leq i < n$. By induction on n we show that some $[s_i]$ in this finite path is not eligible, which is a contradiction.

- $n = 0$. Then we have that $\varphi_2 \in [s_0]$ and $\neg(\varphi_1 U^{>0} \varphi_2) \in [s_0]$, which means that $\varphi_2, \hat{\varphi}_2 \in [s_0]$, hence $[s_0]$ is not eligible.
- **Induction step.** Since $\neg(\varphi_1 U^{>0} \varphi_2) \in [s_0]$, there are two possibilities (see Definition 3.3): Either $\hat{\varphi}_1, \hat{\varphi}_2 \in [s_0]$, which means that $\hat{\varphi}_1, \varphi_1 \in [s_0]$ and hence $[s_0]$ is not eligible, or $\neg X^{>0}(\varphi_1 U^{>0} \varphi_2) \in [s_0]$, which means that $\neg(\varphi_1 U^{>0} \varphi_2) \in [s_1]$ and we can apply induction hypothesis.

Let $\xi = \varphi_1 U^=1 \varphi_2$, and let us assume that $\mathcal{A}, [s] \not\models \varphi_1 U^=1 \varphi_2$. According to Lemma 3.1, there are two possibilities:

- (a) There is a finite path $[s_0] \mapsto \dots \mapsto [s_n]$, where $n \in \mathbb{N}_0$, $[s] = [s_0]$, $\hat{\varphi}_2 \in [s_i]$ for all $0 \leq i \leq n$, and $\hat{\varphi}_1 \in [s_n]$. Since $\hat{\varphi}_1, \hat{\varphi}_2 \in [s_n]$, we have that $M, s_n \models^{\nu} \hat{\varphi}_1 \wedge \hat{\varphi}_2$, hence $M, s_n \models^{\nu} \varphi_1 U^=1 \varphi_2$. By a straightforward induction on j we can show that $M, s_{n-j} \models^{\nu} \varphi_1 U^{<1} \varphi_2$ for all $0 \leq j \leq n$, which means that $\varphi_1 U^=1 \varphi_2 \notin [s_0] = [s]$, and we have a contradiction.
- (b) There is a BSCC α of \mathcal{A} such that $\hat{\varphi}_2 \in [t]$ for every $[t] \in \alpha$, and a finite path $[s_0] \mapsto \dots \mapsto [s_n]$ such that $n \in \mathbb{N}_0$, $[s] = [s_0]$, $[s_n] \in \alpha$, and $\hat{\varphi}_2 \in [s_i]$ for all $0 \leq i \leq n$. First, let us realize that if $[t] \in \alpha$, then for every $t' \in St$ such that $t \rightarrow^* t'$ we have that $M, t' \not\models^{\nu} \varphi_2$. Hence, $M, t \models^{\nu} \varphi_1 U^=0 \varphi_2$. Since $[s_n] \in \alpha$, we have that $M, s_n \models^{\nu} \varphi_1 U^=0 \varphi_2$. From this we obtain (similarly as

in (a) that $\varphi_1 U^1 \varphi_2 \notin [s_0] = [s]$, which is a contradiction.

Condition (2). Let $\neg(\varphi_1 U^1 \varphi_2) \in [s]$. First we show that if M is a finite-state Markov chain (i.e., the formula ψ is finite satisfiable), then $\mathcal{A}, [s] \not\models \varphi_1 U^1 \varphi_2$. Since $M, s \not\models \varphi_1 U^1 \varphi_2$ and M is a finite-state Markov chain, there are two possibilities (see Lemma 3.1):

- (a) There is a finite path $s = s_0 \rightarrow \dots \rightarrow s_n, n \in \mathbb{N}_0$, such that $M, s_i \models^v \hat{\varphi}_2$ for all $0 \leq i \leq n$, and $M, s_n \models^v \hat{\varphi}_1$. But then $[s] = [s_0] \mapsto \dots \mapsto [s_n], \hat{\varphi}_2 \in [s_i]$ for all $0 \leq i \leq n$, and $\hat{\varphi}_1 \in [s_n]$, which means that $\mathcal{A}, [s] \not\models \varphi_1 U^1 \varphi_2$ as needed.
- (b) There is a BSCC α of M such that $M, t \models^v \hat{\varphi}_2$ for every $t \in \alpha$, and a finite path $s = s_0 \rightarrow \dots \rightarrow s_n, n \in \mathbb{N}_0$, such that $s_n \in \alpha$ and $M, s_i \models^v \hat{\varphi}_2$ for all $0 \leq i \leq n$. Consider the finite path $[s]=[s_0] \mapsto \dots \mapsto [s_n]$. Clearly $\hat{\varphi}_2 \in [s_i]$ for all $0 \leq i \leq n$. We show that $\mathcal{A}, [s_n] \models \neg(\varphi_1 U^1 \varphi_2)$, which implies that $\mathcal{A}, [s] \not\models \varphi_1 U^1 \varphi_2$ as needed.

Since $M, t \models^v \neg(\varphi_1 U^1 \varphi_2)$ for every $t \in \alpha$, we have that $\neg(\varphi_1 U^1 \varphi_2) \in [t]$ for every $t \in \alpha$ (here we rely on the last rule of Definition 3.2 which guarantees that $\neg(\varphi_1 U^1 \varphi_2) \in Cl(\psi)$). In particular, $\neg(\varphi_1 U^1 \varphi_2) \in [s_n]$. By applying the analysis of Condition (1), we can conclude that $\mathcal{A}, [s_n] \models \neg(\varphi_1 U^1 \varphi_2)$.

Now consider the general case when the Markov chain M is not necessarily finite-state. Since $M, s \not\models \varphi_1 U^1 \varphi_2$, there are two possibilities (see Lemma 3.1):

- (a) There is a finite path $s = s_0 \rightarrow \dots \rightarrow s_n, n \in \mathbb{N}_0$, such that $M, s_i \models^v \hat{\varphi}_2$ for all $0 \leq i \leq n$, and $M, s_n \models^v \hat{\varphi}_1$. Then we obtain $\mathcal{A}, [s] \not\models \varphi_1 U^1 \varphi_2$ as in (a) above.
- (b) $\mathcal{P}(\mathcal{R}) > 0$, where $\mathcal{R} = \{w \in Run(s) \mid M, w(i) \models \varphi_1 \wedge \hat{\varphi}_2\}$. For every $w \in \mathcal{R}$, the type of w is the pseudo-structure $\mathcal{B} = (B, \leftrightarrow)$ where

- $[t] \in B$ iff there are infinitely many $i \in \mathbb{N}_0$ such that $[w(i)] = [t]$;
- $[t] \leftrightarrow [u]$ iff there are infinitely many $i \in \mathbb{N}_0$ such that $[w(i)] = [t], [w(i+1)] = [u]$, and $w(i) \rightarrow w(i+1)$.

For every type \mathcal{B} , let $\mathcal{R}(\mathcal{B}) = \{w \in \mathcal{R} \mid \text{the type of } w \text{ is } \mathcal{B}\}$. Since there are only finitely many types, $\mathcal{R} = \bigcup_{\mathcal{B}} \mathcal{R}(\mathcal{B})$, and $\mathcal{P}(\mathcal{R}) > 0$, there must be a type \mathcal{B} such that $\mathcal{P}(\mathcal{R}(\mathcal{B})) > 0$. For the rest of this proof, let us fix such a type $\mathcal{B} = (B, \leftrightarrow)$. We claim that \mathcal{B} is a witness for $\neg(\varphi_1 U^1 \varphi_2)$. Clearly \mathcal{B} is strongly connected and $\hat{\varphi}_2 \in [t]$ for every $[t] \in B$. It remains to show that for every $[t] \in B$ and every $\xi_1 U^1 \xi_2 \in [t]$ we have that $\mathcal{B}, [t] \models \xi_1 U^1 \xi_2$. Suppose that $\mathcal{B}, [t] \not\models \xi_1 U^1 \xi_2$. Since \mathcal{B} has finitely many states and is strongly connected, there are two possibilities (see Lemma 3.1):

- (a) There is a finite path $[t_0] \leftrightarrow \dots \leftrightarrow [t_n]$, where $n \in \mathbb{N}_0$, $[t] = [t_0], \hat{\xi}_2 \in [t_i]$ for all $0 \leq i \leq n$, and $\hat{\varphi}_1 \in [t_n]$. Then we obtain $\xi_1 U^1 \xi_2 \notin [t_0] = [t]$ in the same way as in the paragraph Condition (1) (a).

- (b) $\xi_1, \hat{\xi}_2 \in [u]$ for every $[u] \in B$ (note that \mathcal{B} is strongly connected). We show that $\xi_1 U^1 \xi_2 \notin [t]$. For this we need the observation formulated in the next paragraph.

For every $u \in St$ such that $[u] \in B$ we define $Run(u, \mathcal{B})$ as the set of all $w \in Run(u)$ such that $[w(i)] \leftrightarrow [w(i+1)]$ for all $i \in \mathbb{N}_0$. We claim that for every $u \in St$ such that $[u] \in B$ there is some $u' \in St$ such that $[u] = [u']$ and $\mathcal{P}(Run(u', \mathcal{B})) > 0$. Suppose that this condition is violated by some $u \in St$. Let \mathcal{H} be the set of all finite paths in M initiated in s and terminated in some $u' \in St$ where $[u'] = [u]$. Since every run of $\mathcal{R}(\mathcal{B})$ eventually visits some u' such that $[u'] = [u]$, we have that $\mathcal{R}(\mathcal{B}) \subseteq \bigcup_{v \in \mathcal{H}} (v \cdot Run(u_v, \mathcal{B}))$, where u_v is the last state of v and $v \cdot Run(u_v, \mathcal{B})$ the set of all runs of the form $v\bar{w}$ where $u_v, \bar{w} \in Run(u_v, \mathcal{B})$. Hence, $\mathcal{P}(\mathcal{R}(\mathcal{B})) \leq \sum_{v \in \mathcal{H}} \mathcal{P}(Run(v)) \cdot \mathcal{P}(Run(u_v, \mathcal{B}))$. Since $\mathcal{P}(Run(u_v, \mathcal{B})) = 0$ for every $v \in \mathcal{H}$, we obtain $\mathcal{P}(\mathcal{R}(\mathcal{B})) = 0$, which is a contradiction.

Due to the observation formulated in the previous paragraph, there is some $t' \in St$ such that $[t'] = [t]$ and $\mathcal{P}(Run(t', \mathcal{B})) > 0$. Since $M, w(i) \not\models^v \xi_2$ for every $w \in Run(t', \mathcal{B})$ and $i \in \mathbb{N}_0$, we obtain that $M, t' \not\models^v \xi_1 U^1 \xi_2$, hence $\xi_1 U^1 \xi_2 \notin [t'] = [t]$. \square

According to Theorem 3.7, every satisfiable qualitative PCTL formula has a finite pseudo-model. Now we show that this pseudo-model can be turned into a “real” model, which can be infinite but always admits a finite description in the form of a *marked graph*.

Definition 3.8. A marked graph is a triple $\mathcal{G} = (G, \leftrightarrow, L)$ where G is a finite set of nodes, $\leftrightarrow \subseteq G \times G$ is a total relation, and $L \subseteq \leftrightarrow$ a subset of marked transitions.

Each marked graph $\mathcal{G} = (G, \leftrightarrow, L)$ determines a unique Markov chain $M_{\mathcal{G}} = (G^+, \rightarrow, Prob)$ where

- for all $w \in G^*$ and $v \in G$, $wv \rightarrow \bar{w}$ iff $\bar{w} = wv v'$ for some $v' \in G$ such that $v \leftrightarrow v'$. We say that $wv \rightarrow wv v'$ is *marked* iff $v \leftrightarrow v'$ is marked;
- for every $w \in G^+$, $Prob(w)$ is a uniform distribution if none or all outgoing transitions of w are marked. Otherwise, $Prob$ assigns the same probability p to all non-marked transitions and the same probability p' to all marked transitions so that $\sum_{w \rightarrow w' \in L} p$ is equal to $1 - 1/4^{len(w)}$.

In other words, each marked graph \mathcal{G} is a finite representation of an infinite-state Markov chain $M_{\mathcal{G}}$ obtained by “unfolding” the structure of \mathcal{G} and assigning larger and larger probabilities to marked transitions.

Remark 3.9. Let $\mathcal{G} = (G, \leftrightarrow, L)$ be a marked graph. For every run $w \in Run(u)$ of \mathcal{G} there is a corresponding run $\bar{w} \in Run(u)$ of $M_{\mathcal{G}}$, where $\bar{w}(k) = w(0) \dots w(k)$ for every $k \in \mathbb{N}_0$. Further, each $\eta : G \rightarrow 2^{Ap}$ can be naturally extended to a

valuation $\eta' : G^+ \rightarrow 2^{Ap}$ where $\eta'(wv) = \eta(v)$ for every $w \in G^*$ and $v \in G$. For the sake of simplicity, we introduce the following notation:

- for every PCTL formula φ and every $\eta : G \rightarrow 2^{Ap}$, we write $\mathcal{G}, v \models^\eta \varphi$ iff $M_{\mathcal{G}, v} \models^{\eta'} \varphi$
- for every set of runs $\mathcal{L} \subseteq \text{Run}(u)$ in \mathcal{G} we put $\bar{\mathcal{L}} = \{\bar{w} \mid w \in \mathcal{L}\}$ and define $\mathcal{P}(\mathcal{L}) = \mathcal{P}(\bar{\mathcal{L}})$ whenever $\bar{\mathcal{L}}$ is measurable.

Let v be a finite path in \mathcal{G} initiated in some $S \in G$. One can easily prove that for every $\mathcal{L} \subseteq \text{Run}(v)$ such that $\mathcal{P}(\mathcal{L})$ is defined we have that $\mathcal{P}(\mathcal{L}) = \mathcal{P}(\text{Run}(v)) \cdot \mathcal{P}(\{w \mid vw \in \mathcal{L}\})$, and this observation is frequently used in the proof of Theorem 3.10.

Theorem 3.10. *Let ψ be a qualitative PCTL formula. If there is a pseudo-model \mathcal{A} for ψ , then there is a marked graph $\mathcal{G} = (G, \hookrightarrow, L)$ whose size is exponential in $|\varphi|$, a valuation $\eta : G \rightarrow 2^{Ap}$, and $v \in G$ such that $\mathcal{G}, v \models^\eta \psi$. Moreover, if \mathcal{A} is simple, then $L = \emptyset$ and ψ has a finite-state model whose size is exponential in $|\psi|$.*

Proof. Let $\mathcal{A} = (A, \mapsto)$ be a pseudo-model for ψ . If \mathcal{A} is simple, we can put $\mathcal{G} = (A, \mapsto, \emptyset)$ and $\eta(S) = \{p \in Ap \mid p \in S\}$ for every $S \in A$. It is easy to verify that for every $S \in A$ and $\varphi \in S$ we have that $\mathcal{G}, S \models^\eta \varphi$. (A proof is a straightforward induction on the structure of φ , where all subcases follow immediately from Definition 3.6).

If \mathcal{A} is not simple, we proceed as follows. Let $\mathcal{B}_i = (B_i, \rightsquigarrow_i)$, $1 \leq i \leq m$, be a family of pseudo-structures such that

- for every $S \in A$ and every $\neg(\varphi_1 U^1 \varphi_2) \in S$ there is a suitable \mathcal{B}_i and a finite path $S = S_0 \mapsto \dots \mapsto S_n$ such that $\hat{\varphi}_2 \in S_j$ for every $0 \leq j \leq n$, $S_n \in B_i$, and \mathcal{B}_i is a witness for $\neg(\varphi_1 U^1 \varphi_2)$ in \mathcal{A} ;
- each \mathcal{B}_i is a witness for some $\neg(\varphi_1 U^1 \varphi_2) \in Cl(\psi)$ in \mathcal{A} .

Since we need at most one witness for every $S \in A$ and every $\neg(\varphi_1 U^1 \varphi_2) \in S$, we can safely assume that $m \leq |A| \cdot |\psi|$.

The nodes of \mathcal{G} are obtained by taking the disjoint union of A and all B_i , $1 \leq i \leq m$. Formally, we put $G = \bigcup_{i=0}^m B_i \times \{i\}$, where $B_0 = A$. The \hookrightarrow and L are defined as follows: if $S \mapsto T$, then

- $(S, 0) \hookrightarrow (T, i)$ for every $0 \leq i \leq m$ such that $T \in B_i$;
- for every $1 \leq i \leq m$ such that $S, T \in B_i$ and $S \rightsquigarrow_i T$ we have that $(S, i) \hookrightarrow (T, i)$ and this transition is marked;
- for every $1 \leq i \leq m$ such that $S \in B_i$ and $T \notin B_i$ we have that $(S, i) \hookrightarrow (T, 0)$.

Both \hookrightarrow and L contain only those transitions which can be derived by the above rule. Note that the size of \mathcal{G} is exponential in $|\psi|$.

Before continuing with the main proof, we need to formulate auxiliary observations about \mathcal{G} . We say that a run w of \mathcal{G} stays at i , where $0 \leq i \leq m$, if $w(k) \in B_i \times \{i\}$ for every $k \in \mathbb{N}_0$. We say that a run w enters i , where $0 \leq i \leq m$, if w is of the form $u\bar{w}$, where \bar{w} stays at i . Now observe that

- for every $(S, i) \in G$ where $i \geq 1$, the probability of all $w \in \text{Run}((S, i))$ that stay at i is at least $2/3$. To see this, realize that the probability of all $w \in \text{Run}((S, i))$ such that a non-marked transition is performed in w is bounded by $\sum_{k=1}^{\infty} 1/4^k = 1/3$. This follows directly from the definition of $M_{\mathcal{G}}$.
- for every $(S, i) \in G$, the probability of all $w \in \text{Run}((S, i))$ such that w does not enter any j , where $0 \leq j \leq m$, is zero. This is an immediate consequence of the previous observation.
- for every $(S, i) \in G$ and every $\xi_1 U^1 \xi_2 \in S$, the conditional probability of all $w \in \text{Run}((S, i))$ such that $\mathcal{G}, w \models \xi_1 U \xi_2$, under the condition that w stays at i , is equal to 1. This follows from Definition 3.5.

Now we continue with the main proof. Let η be a valuation given by $\eta((S, i)) = \{p \in Ap \mid p \in S\}$ for every $0 \leq i \leq m$. We show that for every $\varphi \in Cl(\psi)$ and every $(S, i) \in G$ we have that $\varphi \in S$ iff $\mathcal{G}, (S, i) \models^\eta \varphi$ (from now on, the η in \models^η is omitted). We proceed by induction on the structure of φ .

- The cases when φ is of the form p , $\neg\varphi_1$, $\varphi_1 \wedge \varphi_2$, $X^{>0}\varphi_1$, or $X^1\varphi_1$ follow immediately.
- Let φ be of the form $\varphi_1 U^{>0} \varphi_2$. If $\varphi_1 U^{>0} \varphi_2 \in S$, then $\mathcal{A}, S \models \varphi_1 U^{>0} \varphi_2$, and there is a finite path $S = S_0 \mapsto \dots \mapsto S_n$, where $\varphi_1 \in S_j$ for every $0 \leq j < n$ and $\varphi_2 \in S_n$. Hence, $(S, i) = (S_0, i_0) \hookrightarrow \dots \hookrightarrow (S_n, i_n)$, where $0 \leq i_j \leq m$ for every $0 \leq j < n$ (this follows from the definition of \mathcal{G}). Further, $\mathcal{G}, (S_j, i_j) \models \varphi_1$ for every $0 \leq j < n$ and $\mathcal{G}, (S_n, i_n) \models \varphi_2$ (by induction hypothesis), hence $\mathcal{G}, (S, i) \models \varphi_1 U^{>0} \varphi_2$ as required. Similarly, we show that if $\mathcal{G}, (S, i) \models \varphi_1 U^{>0} \varphi_2$, then $\mathcal{A}, S \models \varphi_1 U^{>0} \varphi_2$, hence $\varphi_1 U^{>0} \varphi_2 \in S$ as needed.
- Let φ be of the form $\varphi_1 U^1 \varphi_2$. We start with the “ \Rightarrow ” direction, i.e., we prove that if $\mathcal{G}, (S, i) \not\models \varphi_1 U^1 \varphi_2$ for some $(S, i) \in G$, then $\varphi_1 U^1 \varphi_2 \notin S$.

Since $\mathcal{G}, (S, i) \not\models \varphi_1 U^1 \varphi_2$, there are two possibilities (see Lemma 3.1):

- There is a finite path $(S, i) = (S_0, i_0) \hookrightarrow \dots \hookrightarrow (S_n, i_n)$ such that $\mathcal{G}, (S_j, i_j) \models \hat{\varphi}_2$ for every $0 \leq j \leq n$ and $\mathcal{G}, (S_n, i_n) \models \hat{\varphi}_1$. But then $S = S_0 \mapsto \dots \mapsto S_n$ where $\mathcal{A}, S_j \models \hat{\varphi}_2$ for every $0 \leq j \leq n$ and $\mathcal{A}, S_n \models \hat{\varphi}_1$ (by induction hypothesis), which means $\mathcal{A}, S \not\models \varphi_1 U^1 \varphi_2$, and hence $\varphi_1 U^1 \varphi_2 \notin S$ by definition.

- We have $\mathcal{P}(\mathcal{R}) > 0$, where $\mathcal{R} = \{w \in \text{Run}((S, i)) \mid \mathcal{G}, w(k) \models \varphi_1 \wedge \hat{\varphi}_2\}$. Let us assume that $\varphi_1 U^1 \varphi_2 \in S$, for a contradiction. Observe that for every run

$(S, i) = (S_0, i_0), (S_1, i_1), \dots$ of \mathcal{R} and every $k \in \mathbb{N}_0$ we have that $\varphi_1 U^=1 \varphi_2 \in S_k$. This can be shown by induction k :

- $k = 0$. This is immediate because $\varphi_1 U^=1 \varphi_2 \in S$.
- **Induction step:** Let us assume $\varphi_1 U^=1 \varphi_2 \in S_{k-1}$ and $(S_{k-1}, i_{k-1}) \hookrightarrow (S_k, i_k)$. Since we have $\mathcal{G}, (S_{k-1}, i_{k-1}) \not\models \varphi_2$, we obtain $\varphi_2 \notin S_{k-1}$ by induction hypothesis (here we consider the “outer” structural induction). Since S_{k-1} is eligible, we have that $X^=1(\varphi_1 U^=1 \varphi_2) \in S_{k-1}$ (see Definition 3.3). Since (\mathcal{A}, \mapsto) is a pseudo-model and $S_{k-1} \mapsto S_k$, we obtain $\varphi_1 U^=1 \varphi_2 \in S_k$ as needed.

For every $0 \leq j \leq m$, let $\mathcal{R}_j = \{w \in \mathcal{R} \mid w \text{ enters } j\}$. Due to observation (ii) above, $\mathcal{P}(\mathcal{R}) = \sum_{j=0}^m \mathcal{P}(\mathcal{R}_j)$, and hence there is some j such that $\mathcal{P}(\mathcal{R}_j) > 0$. For the rest of this paragraph, let us fix such a j . Let \mathcal{H} be the set of all finite paths initiated in (S, i) . For every $u \in \mathcal{H}$, let $\mathcal{R}_j(u) = \{w \in \mathcal{R}_j \mid w = u\bar{w} \text{ where } \bar{w} \text{ stays at } j\}$. Since $\mathcal{P}(\mathcal{R}_j) > 0$ and $\mathcal{R}_j = \bigcup_{u \in \mathcal{H}} \mathcal{R}_j(u)$, there is some $u \in \mathcal{H}$ such that $\mathcal{P}(\mathcal{R}_j(u)) > 0$. For the rest of this paragraph, we fix such a u . Let $u = u'(S_k, i_k)$, and let $\mathcal{L} = \{\bar{w} \mid u'\bar{w} \in \mathcal{R}_j(u)\}$. Since $\mathcal{P}(\mathcal{R}_j(u)) > 0$, we have that $\mathcal{P}(\mathcal{L}) > 0$. Since $\varphi_1 U^=1 \varphi_2 \in S_k$ and $\mathcal{G}, \bar{w} \not\models \varphi_1 U \varphi_2$ for every $\bar{w} \in \mathcal{L}$, we obtain a contradiction with observation (iii).

It remains to prove the “ \Leftarrow ” direction. We show that if $\varphi_1 U^=1 \varphi_2 \notin S$, then $\mathcal{G}, (S, i) \not\models \varphi_1 U^=1 \varphi_2$ for every $0 \leq i \leq m$ such that $(S, i) \in G$. According to Definition 3.6, two cases arise:

(a) $\mathcal{A}, S \not\models \varphi_1 U^=1 \varphi_2$. Since A is finite-state, there are two possibilities (see Lemma 3.1):

- i. There is a finite path $S = S_0 \mapsto \dots \mapsto S_n$ where $\mathcal{A}, S_j \models \hat{\varphi}_2$ for every $0 \leq j \leq n$ and $\mathcal{A}, S_n \models \hat{\varphi}_1$. From this we easily obtain that $\mathcal{G}, (S, i) \not\models \varphi_1 U^=1 \varphi_2$.
- ii. There is a BSCC α of \mathcal{A} such that $\mathcal{A}, T \models \hat{\varphi}_2$ for every $T \in \alpha$, and a finite path $S = S_0 \mapsto \dots \mapsto S_n$, $n \in \mathbb{N}_0$, such that $S_n \in \alpha$ and $\mathcal{A}, S_i \models \hat{\varphi}_2$ for all $0 \leq i \leq n$. Then $(S, i) = (S_0, i_0) \hookrightarrow \dots \hookrightarrow (S_n, i_n)$ where $\mathcal{G}, (S_n, i_n) \models \varphi_1 U^=0 \varphi_2$. From this we get $\mathcal{G}, (S, i) \not\models \varphi_1 U^=1 \varphi_2$.

(b) There is a witness $\mathcal{B}_k = (B_k, \rightsquigarrow_k)$ and a finite path $S = S_0 \mapsto \dots \mapsto S_n \in B_k$, where $\hat{\varphi}_2 \in S_j$ for every $0 \leq j \leq n$, and $\hat{\varphi}_2 \in T$ for every $T \in B_k$. Hence also $(S, i) = (S_0, j_0) \hookrightarrow \dots \hookrightarrow (S_n, j_n)$ where $j_n = k$. Let $\mathcal{R} = \{w \in \text{Run}((S, i)) \mid w = (S_0, j_0) \dots (S_n, j_n)u, \text{ where } u \text{ stays at } k\}$. Since $\mathcal{G}, w(\ell) \models \hat{\varphi}_2$ for every $w \in \mathcal{R}$ and $\ell \in \mathbb{N}_0$, and $\mathcal{P}(\mathcal{R}) > 0$ using observation (i), we receive $\mathcal{G}, (S, i) \not\models \varphi_1 U^=1 \varphi_2$. \square

Note that the construction of the marked graph \mathcal{G} in Theorem 3.10 is effective (provided that the family \mathcal{B}_i of witnesses has already been computed). Hence, it remains to show how to compute a (simple) pseudo-model for a given qualitative PCTL formula (if it exists) together with the associated family of witnesses.

Theorem 3.11. *Let ψ be a qualitative PCTL formula. The existence of a (simple) pseudo-model for ψ is decidable in time exponential in $|\psi|$. Moreover, if a (simple) pseudo-model for ψ exists, it can be effectively constructed in time exponential in $|\psi|$.*

Proof. Let ψ be a qualitative PCTL formula. An algorithm for constructing a (finite) pseudo-model for ψ is given in Figure 1. The algorithm executes either the line 10a or 10b (not both), depending on whether the constructed pseudo-model is to be simple or not, respectively. We show that the algorithm has the required properties. This is done in three steps. We show that

- (a) if the algorithm returns some $\mathcal{A} = (A, \mapsto)$, then \mathcal{A} is a (simple) pseudo-model for ψ ;
- (b) if ψ is (finite) satisfiable, then the algorithm returns a (simple) pseudo-model for ψ ;
- (c) the algorithm terminates in time which is exponential in $|\psi|$.

Step (a). It suffices to verify the conditions stated in Definition 3.6. Let $S \in A$ and $\xi \in S$. If ξ is of the form $X^=1 \varphi$ or $\neg X^{>0} \varphi$, then $\mathcal{A}, S \models \xi$ because only the “safe” outgoing edges of S satisfy the conditions given at line 5 and line 6, respectively. Similarly, if ξ is of the form $X^{>0} \varphi$, $\neg X^=1 \varphi$, or $\varphi_1 U^{>0} \varphi_2$, then $\mathcal{A}, S \models \xi$ because otherwise S would have to be deleted from A at line 7.

Now let $\xi \equiv \neg(\varphi_1 U^{>0} \varphi_2)$. We need to show that $\mathcal{A}, S \models \xi$. Suppose the converse, i.e., $\mathcal{A}, S \not\models \varphi_1 U^{>0} \varphi_2$. Then there is a finite path $S = S_0 \mapsto \dots \mapsto S_n$, where $\varphi_2 \in S_n$ and $\varphi_1 \in S_i$ for all $0 \leq i < n$. By induction on n we show that some S_i in this finite path is not eligible, which is a contradiction.

- $n = 0$. Then $\varphi_2 \in S_0$ and $\neg(\varphi_1 U^{>0} \varphi_2) \in S_0$, which means that $\varphi_2, \hat{\varphi}_2 \in S_0$, hence S_0 is not eligible.
- **Induction step.** Since $\neg(\varphi_1 U^{>0} \varphi_2) \in S_0$, there are two possibilities (see Definition 3.3): Either $\hat{\varphi}_1, \hat{\varphi}_2 \in S_0$, which means that $\hat{\varphi}_1, \varphi_1 \in S_0$ and hence S_0 is not eligible, or $\neg X^{>0}(\varphi_1 U^{>0} \varphi_2) \in S_0$, which means that $\neg(\varphi_1 U^{>0} \varphi_2) \in S_1$ and we can apply induction hypothesis.

The next case is $\xi \equiv \varphi_1 U^=1 \varphi_2$. Again, we need to show that $\mathcal{A}, S \models \xi$. Suppose the converse, i.e., $\mathcal{A}, S \not\models \neg(\varphi_1 U^=1 \varphi_2)$. According to Lemma 3.1, there are two possibilities:

Input: A qualitative PCTL formula ψ .

Output: A (simple) pseudo-model $\mathcal{A} = (A, \mapsto)$ if ψ is (finite) satisfiable, *unsatisfiable* otherwise.

```

1:   $A :=$  the set of all eligible subsets of  $Cl(\psi)$ 
2:   $\mapsto := A \times A$ 
3:  repeat
4:    for all  $S \in A, \xi \in S$  (in any order) do
5:      if  $\xi \equiv X^{-1}\varphi$  then delete all edges  $S \mapsto T$  where  $\varphi \notin T$ 
6:      if  $\xi \equiv \neg X^{>0}\varphi$  then delete all edges  $S \mapsto T$  where  $\varphi \in T$ 
7:      if  $\xi \equiv X^{>0}\varphi$  or  $\xi \equiv \neg X^{-1}\varphi$  or  $\xi \equiv \varphi_1 U^{>0}\varphi_2$  then
          if  $\mathcal{A}, S \not\models \xi$  then  $A := A \setminus \{S\}$ 
8:      if  $\xi \equiv \varphi_1 U^{-1}\varphi_2$  then
          for every BSCC  $B$  of  $(A, \mapsto)$  (in any order) do
              if  $\varphi_1, \hat{\varphi}_2, \varphi_1 U^{-1}\varphi_2 \in T$  for every  $T \in B$  then
                   $A := A \setminus B$ 
          done
9:      if  $\xi \equiv \neg(\varphi_1 U^{-1}\varphi_2)$  then
          if there is no finite path  $S = S_0 \mapsto \dots \mapsto S_n$  where  $\neg(\varphi_1 U^{-1}\varphi_2) \in S_n$  and  $\varphi_1, \hat{\varphi}_2 \in S_i$  for all  $0 \leq i \leq n$  then
10a:          $A := A \setminus \{S\}$ 
10b:         if there is no witness  $(B, \leftrightarrow)$  for  $\neg(\varphi_1 U^{-1}\varphi_2)$  in  $(A, \mapsto)$  such that there is a finite path
               $S = S_0 \mapsto \dots \mapsto S_n$  where  $S_n \in B$  and  $\hat{\varphi}_2 \in S_i$  for all  $0 \leq i \leq n$  then
                   $A := A \setminus \{S\}$ 
11:    repeat
           $\mapsto := \mapsto \cap (A \times A)$ 
           $A := A \setminus \{S \in A \mid S \text{ has no outgoing edges}\}$ 
        until  $A$  does not change
    done
12: until  $(A, \mapsto)$  does not change
13: if  $\psi \in S$  for some  $S \in A$  then
        return  $\mathcal{A} = (A, \mapsto)$ 
    else return unsatisfiable

```

Figure 1. An algorithm for constructing a (simple) pseudo-model.

- There is a finite path $S = S_0 \mapsto \dots \mapsto S_n$ such that $\hat{\varphi}_1 \in S_n$ and $\hat{\varphi}_2 \in S_i$ for all $0 \leq i \leq n$. Similarly as above, we can show (by a straightforward induction on n) that some S_i is not eligible.
- There is a BSCC B of $\mathcal{A} = (A, \mapsto)$ and a finite path $S = S_0 \mapsto \dots \mapsto S_n$ such that $S_n \in B$ and $\varphi_1, \hat{\varphi}_2 \in T$ for every $T \in A$ which appears in the path or in B . A simple induction reveals that $\varphi_1 U^{-1}\varphi_2 \in S_n$, and in fact $\varphi_1 U^{-1}\varphi_2 \in T$ for every $T \in B$. Hence, the BSCC B was deleted from A at line 8, which is a contradiction.

Finally, let us consider the case when $\xi \equiv \neg(\varphi_1 U^{-1}\varphi_2)$. According to Definition 3.6, we need to verify that $\mathcal{A}, S \models \neg(\varphi_1 U^{-1}\varphi_2)$ or there is a suitable witness for $\neg(\varphi_1 U^{-1}\varphi_2)$. The latter possibility is considered only if the algorithm is supposed to construct a pseudo-model that is not necessarily simple. Let us assume that $\mathcal{A}, S \models \varphi_1 U^{-1}\varphi_2$. But then there cannot be any finite path $S = S_0 \mapsto \dots \mapsto$

S_n such that $\neg(\varphi_1 U^{-1}\varphi_2) \in S_n$ and $\varphi_1, \hat{\varphi}_2 \in S_i$ for all $0 \leq i \leq n$, which means that the condition of line 9 is satisfied. If the algorithm is supposed to construct a simple pseudo-model, we obtain a contradiction because S is deleted from A at line 10a. Otherwise, the algorithm proceeds with line 10b, which verifies the existence of a suitable witness for $\neg(\varphi_1 U^{-1}\varphi_2)$. If there was no witness, S would have been deleted from A at line 10b.

Step (b). Let us assume that ψ is (finite) satisfiable. By Theorem 3.7, there is a (simple) pseudo-model $\mathcal{A}' = (A', \rightsquigarrow)$ for ψ . We show that $\mathcal{A}' \subseteq \mathcal{A}$ (taken componentwise) is an invariant of the main **repeat-until** loop at lines 3–12. Here we consider each of the **if** statements individually and show that no element of \mathcal{A}' can be deleted from the current \mathcal{A} , assuming that $\mathcal{A}' \subseteq \mathcal{A}$. The arguments are straightforward.

Since A is initialized to the set of all eligible states and \mapsto is initialized to $A \times A$, the invariant $\mathcal{A}' \subseteq \mathcal{A}$ surely holds be-

fore executing the main **repeat-until** loop. Hence, we also have that $\mathcal{A}' \subseteq \mathcal{A}$ after this loop terminates.

Step (c). Since the model-checking problem for qualitative PCTL and finite-state Markov chains is decidable in polynomial time, all steps can be implemented in time which is polynomial in $|\psi|$ and the size of A (i.e., exponential in $|\psi|$). The existence of a suitable witness at line 10b can be decided as follows: suppose that $\neg(\varphi_1 U^{-1} \varphi_2) \in S$. First, initialize B to $\{T \in A \mid \hat{\varphi}_2 \in T\}$, and then do the following:

- (A) Compute the strongly connected components B_1, \dots, B_n of B using the current \mapsto , and put $\mathcal{B}_i = (B_i, \hookrightarrow_i)$, where $S \hookrightarrow_i T$ iff $S, T \in B_i$ and $S \mapsto T$.
- (B) Compute the set C of all $S \in B_i$, where $1 \leq i \leq n$, such that for some $\xi_1 U^{-1} \xi_2 \in S$ we have that $\mathcal{B}_i, S \not\models \xi_1 U^{-1} \xi_2$.
- (C) Put $B := B \setminus C$. If $C = \emptyset$ or $B = \emptyset$, terminate. Otherwise, goto (A).

Obviously, the above procedure can be implemented in time which is polynomial in $|\psi|$ and the size of A . One can show that every witness for $\neg(\varphi_1 U^{-1} \varphi_2)$ in the current $\mathcal{A} = (A, \mapsto)$ is contained in some SCC of the resulting B , and each of these SCCs itself is a witness for $\neg(\varphi_1 U^{-1} \varphi_2)$. \square

For the sake of completeness, we explicitly verify the corresponding lower complexity bound, although the proof is not very different from the non-probabilistic case.

Theorem 3.12. *The satisfiability problem and the finite-satisfiability problem are EXPTIME-hard.*

A direct corollary to the previously presented results is the following:

Theorem 3.13. *Let ψ be a qualitative PCTL formula. The problem whether ψ is satisfiable (or finite-satisfiable) is EXPTIME-complete. Moreover, if ψ is satisfiable (or finite satisfiable), then there is a marked graph (or a finite Markov chain) of size exponential in $|\psi|$ constructible in time exponential in $|\psi|$ which defines a model for ψ .*

4. Some Notes on Quantitative PCTL

In this section, we present some results about the satisfiability problem for quantitative PCTL formulae, which seem confusing at first glance, but which in fact indicate that this problem is more “fragile” and subtle than it looks.

First, we show that the satisfiability problem for quantitative PCTL is highly undecidable for a restricted class of models where the branching degree is bounded by a fixed constant $k \geq 2$. Our proof uses a technique for encoding the computations of nondeterministic Minsky machines, which

was developed and used in [3] to show the high undecidability of $1\frac{1}{2}$ -player games with PCTL objectives.

Theorem 4.1. *Let ψ be a quantitative PCTL formula, and let $k \geq 2$. The existence of a model for ψ where each state has at most k outgoing transitions is highly undecidable. Moreover, the existence of a finite model for ψ where each state has at most k outgoing transitions is undecidable.*

Proof. Omitted due to the lack of space. Main ideas of the proof are sketched in [4]. \square

Note that this theorem does not allow to conclude that the satisfiability problem as such is undecidable for quantitative PCTL, because the branching degree of the model cannot be bounded by any fixed constant.

Finally, we present a result which reveals some kind of regularity in PCTL models. First we formulate a general lemma which will be used in the proof of our main result. Intuitively, the lemma says that a countable convex combination of vectors is expressible as a convex combination of a finite number of these vectors. Moreover, if n is the dimension of the vector space, $n + 1$ vectors are sufficient (the lemma is a basic result in geometry; a self-contained proof is included in [4]).

Lemma 4.2. *Let I be a countable set, $v \in \mathbb{R}^n$, and $u_i \in \mathbb{R}^n$ for every $i \in I$. If $v = \sum_{i \in I} a_i u_i$ where $a_i \geq 0$ and $\sum_{i \in I} a_i = 1$, then there is $J \subseteq I$ such that $|J| \leq n + 1$, and for each $j \in J$ there is $b_j \geq 0$ such that $\sum_{j \in J} b_j = 1$ and $v = \sum_{j \in J} b_j u_j$.*

Now we show that every satisfiable PCTL formula ψ has a model where each state has at most $|\psi| + 2$ outgoing transitions. This result is non-trivial and uses a combination of geometrical and probabilistic arguments.

Theorem 4.3. *Every satisfiable PCTL formula ψ has a model where each state has at most $|\psi| + 2$ outgoing transitions.*

Proof Sketch. Let ψ be a satisfiable formula. This means that there are $M = (St, \rightarrow, Prob)$, $s_{in} \in St$ and ν satisfying M , $s_{in} \models^\nu \psi$. We may safely assume that M is a (possibly infinite branching) tree rooted in s_{in} , i.e., that every state of M distinct from s_{in} has precisely one incoming transition and s_{in} has no incoming transitions (note that every model of ψ can be “unfolded” into a tree). We construct a model with branching degree bounded by $|\psi| + 2$. The proof is based on choosing suitable successors and assigning them appropriate probabilities, and pruning the others while keeping a model.

Let us denote $\mathcal{S}(\psi)$ the set of all state subformulae of ψ . Further, let

$$I = \mathcal{S}(\psi) \cup \{X\varphi \mid X^{bq}\varphi \in \mathcal{S}(\psi)\} \cup \{\varphi_1 U \varphi_2 \mid \varphi_1 U^{bq} \varphi_2 \in \mathcal{S}(\psi)\}$$

Let us consider vectors of dimension $|I|$ over real numbers with components indexed by elements of I . For every state s of M we define a vector $\vec{s} \in \mathbb{R}^{|I|}$ as follows:

$$\begin{aligned}\vec{s}_{X\varphi} &= r && \text{iff } M, s \models X^{-r}\varphi \\ \vec{s}_{\varphi_1 \cup \varphi_2} &= r && \text{iff } M, s \models \varphi_1 \cup^{-r}\varphi_2\end{aligned}$$

and for $\varphi \in \mathcal{S}(\psi)$ we put

$$\vec{s}_\varphi = \begin{cases} 1 & \text{if } M, s \models^v \varphi; \\ 0 & \text{otherwise.} \end{cases}$$

It is easy to verify that for every state s the vector \vec{s} satisfies the following ‘‘local consistency’’ equations:

$$\vec{s}_{X\varphi} = \sum_{s \xrightarrow{x} t} x \cdot \vec{t}_\varphi$$

and

$$\vec{s}_{\varphi_1 \cup \varphi_2} = \sum_{s \xrightarrow{x} t} x \cdot \vec{t}_{\varphi_1 \cup \varphi_2}$$

for $\varphi_1 \cup \varphi_2 \in I$ such that $M, s \models^v \varphi_1$ and $M, s \not\models^v \varphi_2$. Note also that components of \vec{s} not occurring in the above equations are determined by other components of \vec{s} . Hence, if we are to prune the transition relation of M we should strive to satisfy the above equations.

Let us denote

$$N(s) = \{X\varphi \in I\} \cup \{\varphi_1 \cup \varphi_2 \in I \mid M, s \models^v \varphi_1; M, s \not\models^v \varphi_2\}$$

For every t such that $s \rightarrow t$ we define a vector $p(t) \in \mathbb{R}^{|N(s)|}$ (indexed by elements of $N(s)$) as follows:

$$p(t)_{X\varphi} = \vec{t}_\varphi \text{ and } p(t)_{\varphi_1 \cup \varphi_2} = \vec{t}_{\varphi_1 \cup \varphi_2}$$

Let s be a state of M . Observe that now we may apply Lemma 4.2 to prune outgoing transitions from s while preserving the model. Indeed, it suffices to apply Lemma 4.2 to $\sum_{s \xrightarrow{x} t} x \cdot p(t)$ and obtain numbers b_1, \dots, b_k and successors t_1, \dots, t_k of s such that $\sum_{s \xrightarrow{x} t} x \cdot p(t) = \sum_{i=1}^k b_i \cdot p(t_i)$. Consequently, it suffices to modify transitions of M in such a way that $s \xrightarrow{b_i} t_i$. It is easy to verify that the resulting Markov chain is still a model of ψ . However, this pruning cannot be treated out for all states of M . Intuitively, the problem is that fulfilling $\varphi_1 \cup \varphi_2$ can be deferred indefinitely while still preserving the local consistency (a path formula $\varphi_1 \cup \varphi_2$ is *fulfilled* on a run w in n steps if φ_2 is satisfied in $w(n)$ and φ_1 is satisfied in $w(i)$ for all $0 \leq i < n$; a formula $\varphi_1 \cup \varphi_2$ is fulfilled if it is fulfilled in n steps for some n). Therefore, the chain M has to be pruned carefully so that a progress in fulfilling ‘‘until’’ formulae is ensured.

Let ξ_1, \dots, ξ_ℓ be all formulae of I of the form $\varphi_1 \cup \varphi_2$. Observe that there is $n_1 \geq 0$ such that with a probability $r_s \geq \frac{1}{2} \vec{s}_{\xi_1}$ the formula ξ_1 is fulfilled in at most n_1 steps. Let us assign to every state t reachable from s in $k \leq n_1$

steps the probability r_t of fulfilling ξ_1 in less than $n_1 - k$ steps (i.e., up to the n_1 'th level of the subtree rooted in s). First, assume that $\xi_1 \in N(s)$. Note that $r_s = \sum_{s \xrightarrow{x} t} x \cdot r_t$. Let us apply Lemma 4.2 to $\sum_{s \xrightarrow{x} t} x \cdot (p(t), r_t)$ and obtain numbers b_1, \dots, b_m and successors t_1, \dots, t_m of s such that $\sum_{s \xrightarrow{x} t} x \cdot (p(t), r_t) = \sum_{i=1}^m b_i \cdot (p(t_i), r_{t_i})$. Now we may safely prune the outgoing transitions from s so that $s \xrightarrow{b_i} t_i$. On the other hand, if $\xi_1 \notin N(s)$, we may ignore r_t and apply Lemma 4.2 to $\sum_{s \xrightarrow{x} t} x \cdot p(t)$ in the same way as above. We inductively repeat this pruning for all states reachable from s in at most n_1 steps. Observe that after this pruning the resulting chain is still a model of ψ .

Now let us repeat the above procedure for all states reachable from s in $n_1 + 1$ steps and for the formula ξ_2 . We obtain $n_2 \geq n_1$ and a new Markov chain, a model of ψ , which has the property that ξ_1 and ξ_2 are fulfilled with probability at least $\frac{1}{2} \vec{s}_{\xi_1}$ and $\frac{1}{2} \vec{s}_{\xi_2}$, resp., in n_2 steps (starting in s). Note that while taking care of ξ_2 the part of the chain reachable from s in at most n_1 steps remains unaltered. Similarly, we carry out this process for the remaining formulae ξ_3, \dots, ξ_ℓ . We obtain a model M_1 of ψ such that for some $m_1 \geq 0$ all states reachable from s in at most m_1 steps have a branching degree bounded by $|\psi| + 2$. Moreover, every $\varphi_1 \cup \varphi_2 \in I$ is fulfilled in at most m_1 steps with probability at least $\frac{1}{2} \vec{s}_{\varphi_1 \cup \varphi_2}$.

Repeating the whole construction for states reachable from s in $m_1 + 1$ steps we obtain M_2 and $m_2 \geq m_1$ with similar properties as M_1 and m_1 , resp., except that every $\varphi_1 \cup \varphi_2 \in I$ is fulfilled in at most m_2 steps with probability at least $\frac{3}{4} \vec{s}_{\varphi_1 \cup \varphi_2}$. Repeating this process ad infinitum we obtain a model M_∞ of ψ such that every state reachable from s has a branching degree bounded by $|\psi| + 2$.

Finally, to obtain a model for ψ with branching degree bounded by $|\psi| + 2$ it suffices to perform the construction of M_∞ for $s = s_{in}$. \square

5. Conclusions, Future Work

We solved the satisfiability problem for qualitative PCTL. Although there are some similarities with the logic CTL, the actual properties of these two logics are rather different. Since qualitative PCTL formulae may have only infinite-state models, we also considered the finite satisfiability problem. Since some qualitative PCTL formulae may also require transition probabilities arbitrarily close to zero, another refinement of the satisfiability question might be to consider only models which are possibly infinite-state, but where all probability distributions are uniform. For example, the (satisfiable) formula $G^{>0}(X^{>0}p) \wedge G^{>0}\neg p$ does not have this kind of model, while the formula $G^{>0}(\neg p \wedge F^{>0}p)$ (which has only infinite-state models) has a model where the probabilities of all transitions are equal to $\frac{1}{2}$. Another direction for future work is to design a complete deduc-

tive system for qualitative PCTL. The decidability of the satisfiability problem for quantitative PCTL remains also open. It seems that proof techniques known to the authors are not sufficient to prove the undecidability. On the other hand, there is some indication that the problem might actually be decidable; of course, all the problems that have successfully been defeated in the qualitative case now rise with a new power.

References

- [1] C. Baier, M. Größer, M. Leucker, B. Bollig, and F. Ciesinski. Controller synthesis for probabilistic systems. In *Proceedings of IFIP TCS'2004*, pp. 493–506. Kluwer, 2004.
- [2] B. Banieqbal and H. Barringer. Temporal logic with fixed points. In *Temporal Logic in Specification*, vol. 398 of *Lecture Notes in Computer Science*, pp. 62–74. Springer, 1987.
- [3] T. Brázdil, V. Brožek, V. Forejt, and A. Kučera. Stochastic games with branching-time winning objectives. In *Proceedings of LICS 2006*, pp. 349–358. IEEE Computer Society Press, 2006.
- [4] T. Brázdil, V. Forejt, J. Křetínský, and A. Kučera. The satisfiability problem for probabilistic CTL. Technical report FIMU-RS-2008-03, Faculty of Informatics, Masaryk University, 2008.
- [5] T. Brázdil, V. Forejt, and A. Kučera. Controller synthesis and verification for Markov decision processes with qualitative branching time objectives. In *Proceedings of ICALP 2008*, *Lecture Notes in Computer Science*. Springer, 2008.
- [6] T. Brázdil, A. Kučera, and O. Stražovský. On the decidability of temporal properties of probabilistic pushdown automata. In *Proceedings of STACS 2005*, vol. 3404 of *Lecture Notes in Computer Science*, pp. 145–157. Springer, 2005.
- [7] C. Courcoubetis and M. Yannakakis. The complexity of probabilistic verification. *Journal of the Association for Computing Machinery*, 42(4):857–907, 1995.
- [8] E.A. Emerson. Temporal and modal logic. *Handbook of Theoretical Computer Science*, B:995–1072, 1991.
- [9] E.A. Emerson and J.Y. Halpern. Decision procedures and expressiveness in the temporal logic of branching time. In *Proceedings of STOC'82*, pp. 169–180. ACM Press, 1982.
- [10] E.A. Emerson and C.S. Jutla. Tree automata and the logics of programs. *SIAM-JC*, 29(1):132–158, 1986.
- [11] J. Esparza, A. Kučera, and R. Mayr. Model-checking probabilistic pushdown automata. *Logical Methods in Computer Science*, 2(1:2):1–31, 2006.
- [12] K. Etessami and M. Yannakakis. Recursive Markov chains, stochastic grammars, and monotone systems of non-linear equations. In *Proceedings of STACS 2005*, vol. 3404 of *Lecture Notes in Computer Science*, pp. 340–352. Springer, 2005.
- [13] M. Fischer and R. Ladner. Propositional dynamic logic of regular programs. *Journal of Computer and System Sciences*, 18:194–211, 1979.
- [14] H. Hansson and B. Jonsson. A logic for reasoning about time and reliability. *Formal Aspects of Computing*, 6:512–535, 1994.
- [15] T. Henzinger, O. Kupferman, and R. Majumdar. On the universal and existential fragments of the μ -calculus. *Theoretical Computer Science*, 354(2):173–186, 2006.
- [16] M. Huth and M.Z. Kwiatkowska. Quantitative analysis and model checking. In *Proceedings of LICS'97*, pp. 111–122. IEEE Computer Society Press, 1997.
- [17] J. Johannsen and M. Lange. CTL+ is complete for double exponential time. In *Proceedings of ICALP 2003*, vol. 2719 of *Lecture Notes in Computer Science*, pp. 767–775. Springer, 2003.
- [18] D. Kozen. A finite-model theorem for the propositional μ -calculus. *Studia Logica*, 47(3):233–241, 1988.
- [19] A. Kučera and O. Stražovský. On the controller synthesis for finite-state Markov decision processes. In *Proceedings of FST&TCS 2005*, vol. 3821 of *Lecture Notes in Computer Science*, pp. 541–552. Springer, 2005.
- [20] O. Kupferman and M.Y. Vardi. An automata-theoretic approach to modular model checking. *ACM Transactiona on Programming Languages and Systems*, 22:87–128, 2000.
- [21] M. Vardi and L. Stockmeyer. Improved upper and lower bounds for modal logics of programs. In *Proceedings of STOC'85*, pp. 240–251. ACM Press, 1985.