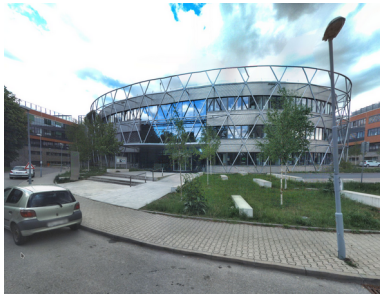
3D Data Visualization

Vladimír (Vlado) Ulman

EMBO Course on Lightsheet Microscopy

16th Aug 2022
CEITEC MUNI, Brno

About me



- Applied Computer Scientists & Open-source SW believer
- Image processing & analysis & vizu, big images in parallel
- Algorithms benchmarking (synth. data)
- Support for DL methods training (silver ground-truth)

- Central European Institute of Technology (CEITEC, Masaryk University, Brno)

- Centre for Biomedical Image Processing (CBIA, Faculty of Informatics, MU, Brno)
- CellTrackingChallenge.net

- IT4Innovations National Supercomuting Center (IT4I, VSB – Technical University of Ostrava, Ostrava)
- HPC Workflow Manager (for Fiji) + DataStore

About the talk

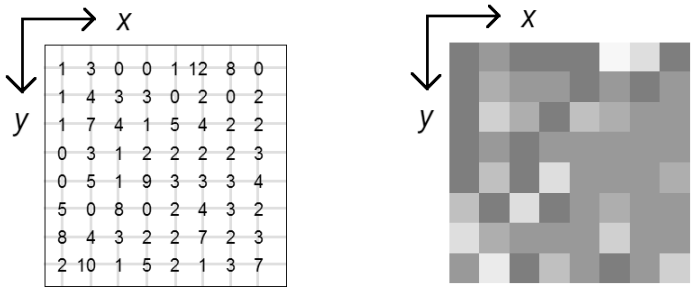
- Main theme:
  - 3D data vizu is actually mostly about
    - Some form of 3D-to-2D projection
    - Some form of information reduction
  - Principles used under the hood

- Outline:
  - Slice rendering
  - Volume rendering
  - Cartographic projections
  - Graphical representations

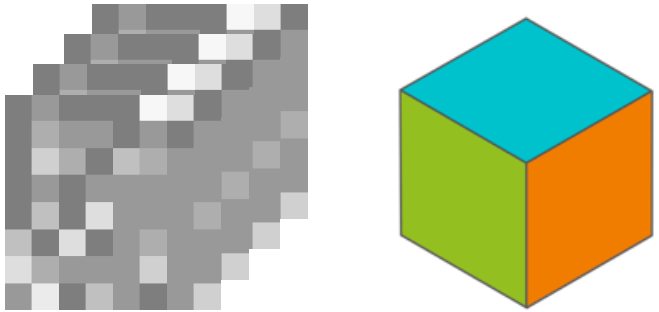
- Download: **https://www.fi.muni.cz/~xulman/files/EMBO_LS2022.pdf**

Terminology

- 2D image
  - Regularly displaced (scalar) values on an orthogonal 2D grid
  - Aka. frame, slice or section



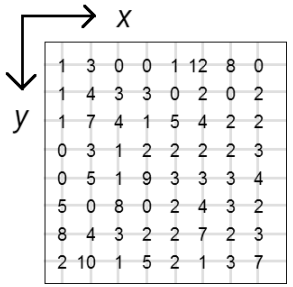
- 3D image
  - A sequence of 2D images → 3D grid
  - Aka. stack or volume
  - No triangles & textures (computer games)
  - Raw data



- Tabular data that include x,y,z coordinates
  - Processed data, e.g. Point cloud

Terminology

- Dimensionality increases
  - By 1D when time-lapse
  - By 1D with every imaged channel
  - By 1D with every view angle

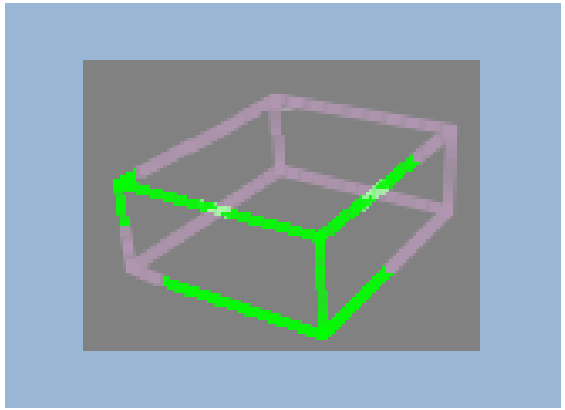


- Picture element → **Pixel**, Volumetric pixel → **Voxel**
- Pixel consumes memory:
  - 8 *or* **16 bits** (1 *or* 2 Bytes, integers, 0-255 *or* 0-65535)
  - 32 *or* 64 bits (4 *or* 8 Bytes, floating-point, single *or* double precision)
- Pixel/Voxel represents a physical area/volume
  - “Microns per pixel” along each axis → Resolution
  - Same sizes in all axes = **isotropic resolution**

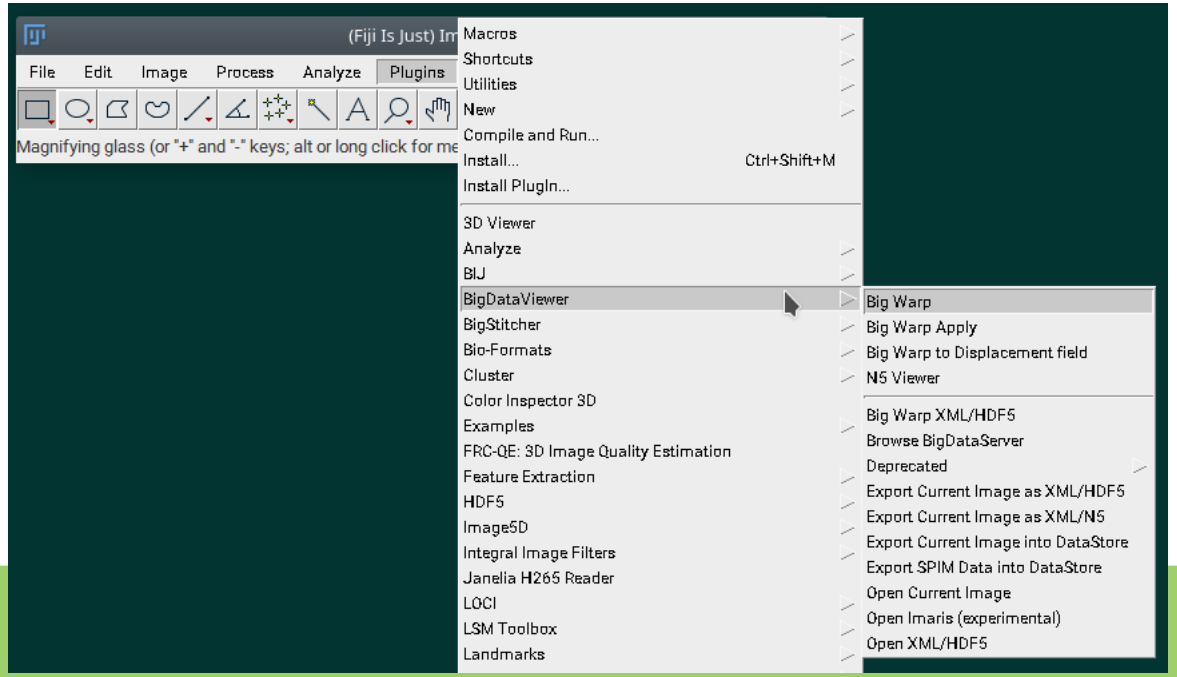
Slice Rendering

Idea: Show the voxels at the intersection of an user-given plane with the Volume.

Orthogonal views are a special case of this.



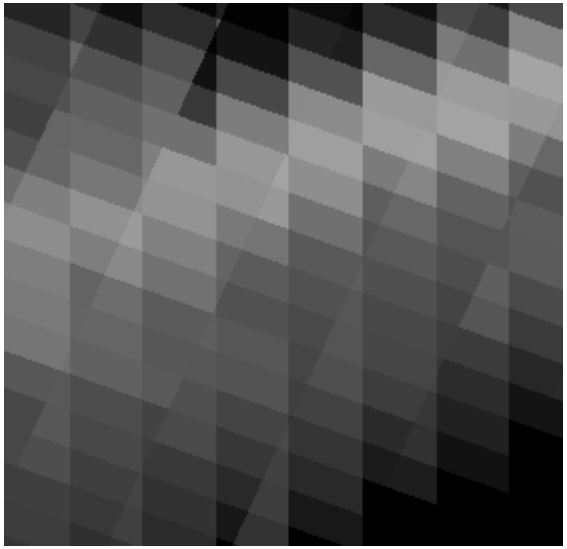
Example SW: BigDataViewer → **BDV**



…available in Fiji

Slice Rendering

Idea: Show the voxels at the intersection of an user-given plane with the Volume.



BigDataViewer (BDV):

- Considers Voxels only (even for 2D images)
- Considers **16 bits** only!
- Fast to determine voxels that are hit by the plane
- Fast to compute (and display) their intersection polygons
- **Fast to fetch their values**
  …when using an intelligent data storage: chunks + pyramids

- Since all is fast, BDV can afford displaying multiple images at once

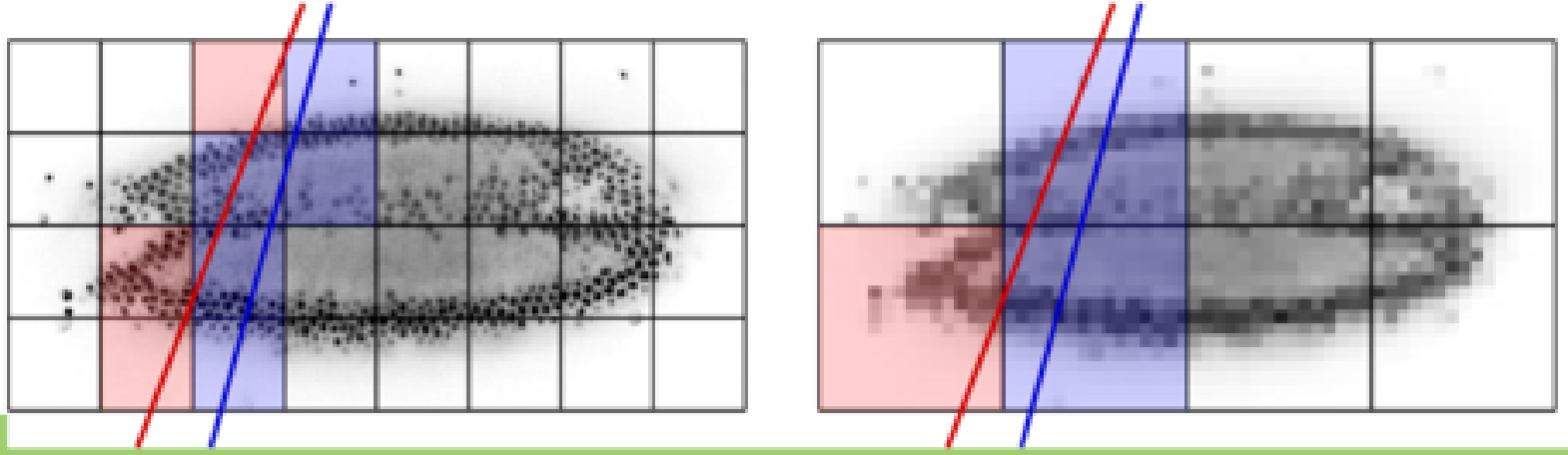
Slice Rendering

BigDataViewer:

- ***Fast to fetch their values***

  …when using an intelligent data storage: chunks + pyramids

- Chunks – to read a voxel, only an including small chunk of Bytes needs to be loaded
- Pyramids – small copies of the image at increasingly lower resolution are available



Slice Rendering

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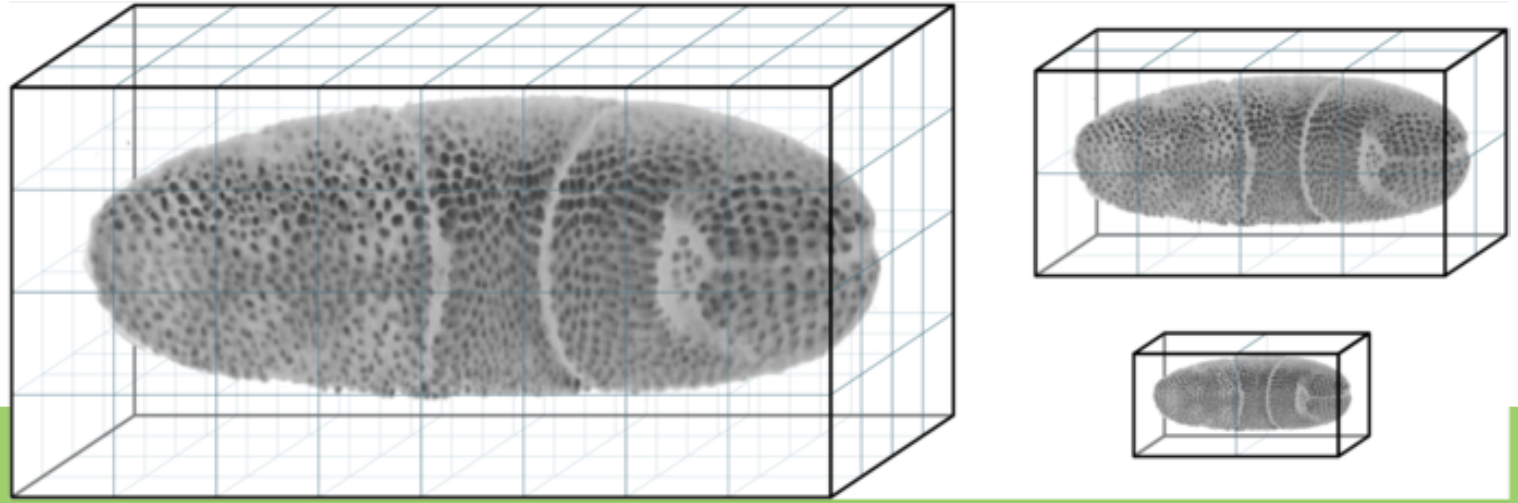

Slice Rendering

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- Google Maps store (and show) maps in the same way
- **Requires appropriate image file format**
  - Baseline: BDV.HDF5
  - Rising star: OME.Zarr (Dialect.GenericContainer)

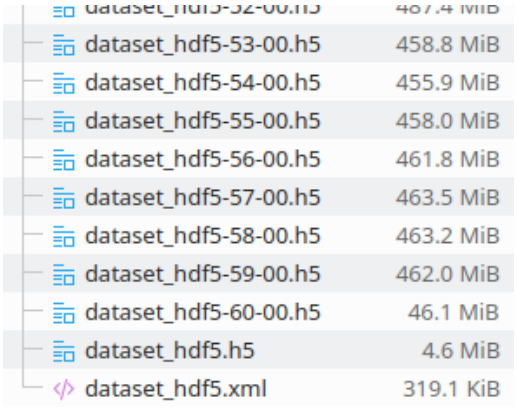
Slice Rendering

BigDataViewer:

- *Requires appropriate image file format*
  - *Baseline: BDV.HDF5*

- Traditionally: **dataset.xml** plus some container(s)
- **.xml** holds conveniently metadata about the image
  - Small, human-readable, editable
  - Also includes a pointer on the container

- BDV “flattens” dimensionality
  to 4D: x, y, z, **source = ViewSetup**




```
<ViewSetups>
  <ViewSetup>
    <id>0</id>
    <size>700 660 113</size>
    <voxelSize>
      <unit>um</unit>
      <size>0.406 0.406 2.031</size>
    </voxelSize>
    <attributes>
      <illumination>0</illumination>
      <channel>0</channel>
      <angle>0</angle>
    </attributes>
  </ViewSetup>
```

Slice Rendering

BigDataViewer:

- *Since all is fast, BDV can afford displaying multiple images at once*

- Recall: BDV considers Voxels only (even for 2D images)
- Recall: Dimensionality increases
  - By 1D when time-lapse
  - By 1D with every imaged channel
  - By 1D with every view angle

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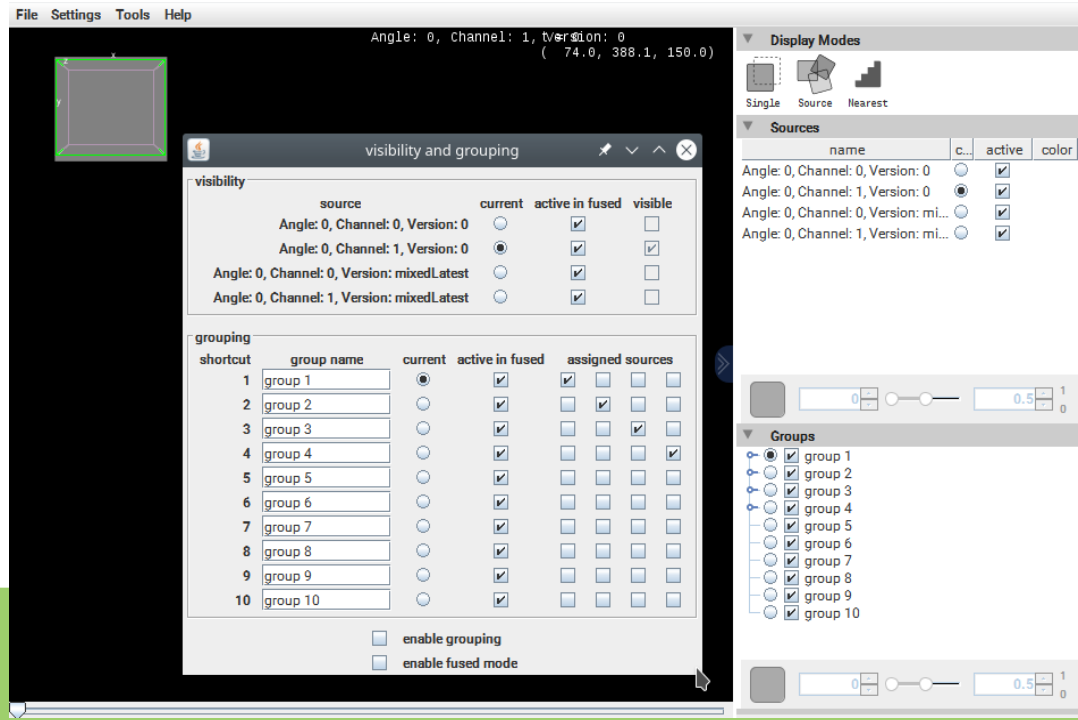

Slice Rendering

BigDataViewer inside other SWs:

- BDV “flattens” dimensionality to 4D: x, y, z, **source = ViewSetup**
- Example from BigStitcher

```
<ViewSetups>
  <ViewSetup>
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```
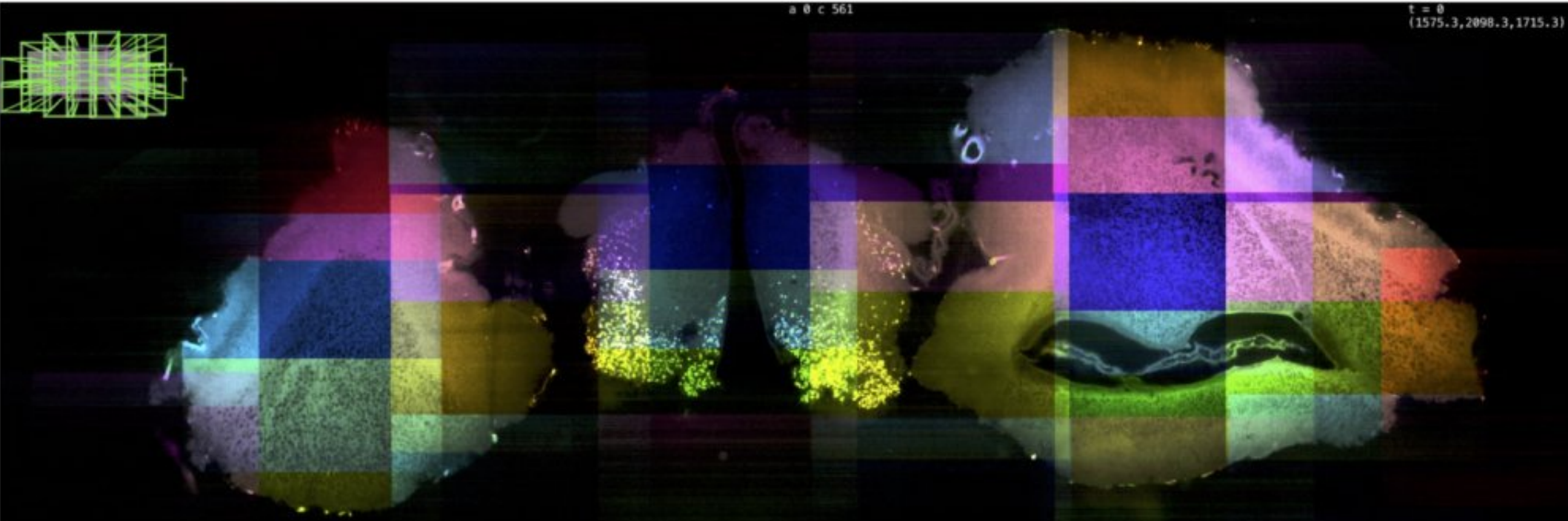
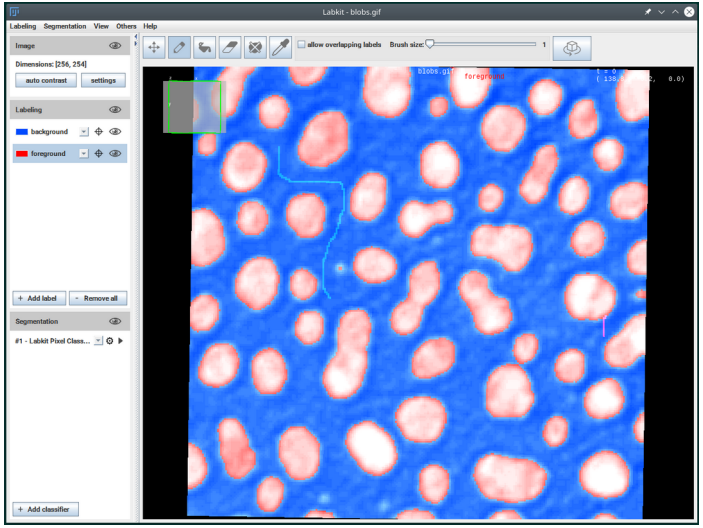



Slice Rendering

BigDataViewer as a core image viewer inside other SWs:

- LabKit, LabelEditor (Jug lab)
- MaMuT, Mastodon (Pasteur + CBG)
- knip (KNIME image processing)
- Paintera, BigWarp, BigCAT (Saalfeld lab)
- BigStitcher (Preibisch lab)
- BigDataProcessor2 (Tischi EMBL)
- MoBIE (Tischi EMBL)
- Mostly by MPI-CBG alumni or friends

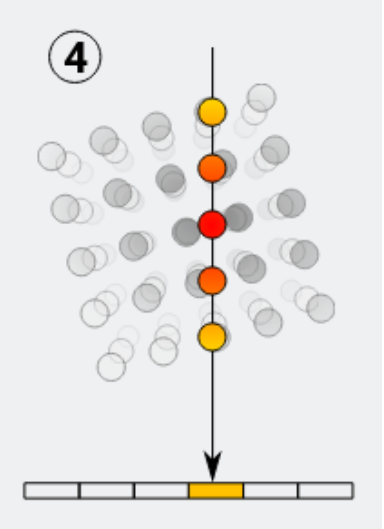
- We will exercise BDV later today...



Volume Rendering

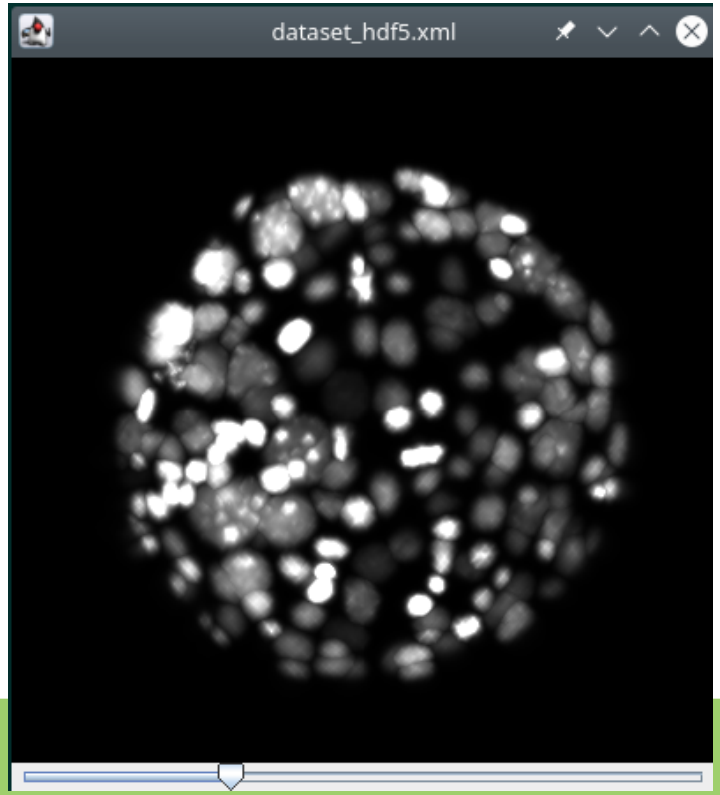
Idea: Collect voxels along line**s** of sight (rays), and show cummulated value.

Maximum intensity projection is a special case of this.



Example SW freely in Fiji:

- **BigVolumeViewer** (BVV) →
  - Consumes the same **dataset.xml**
  - Similar to BDV
- SciView
  - Uses BVV
  - Future Fiji viewer(?)



Volume Rendering

Idea: Collect voxels along line**s** of sight (rays), and show cummulated value.

Both available via the *SciView* update site...

Example SW freely in Fiji:

- BigVolumeViewer (BVV)
  - Consumes the same **dataset.xml**
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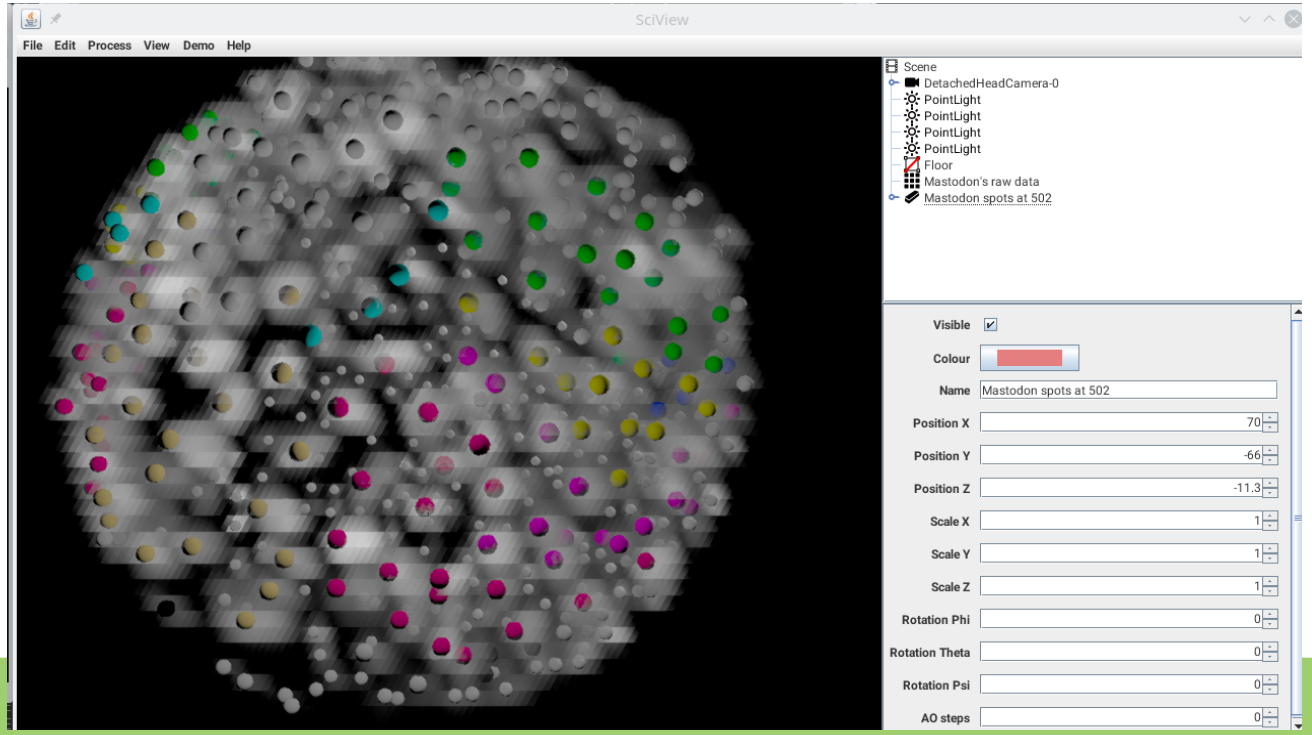
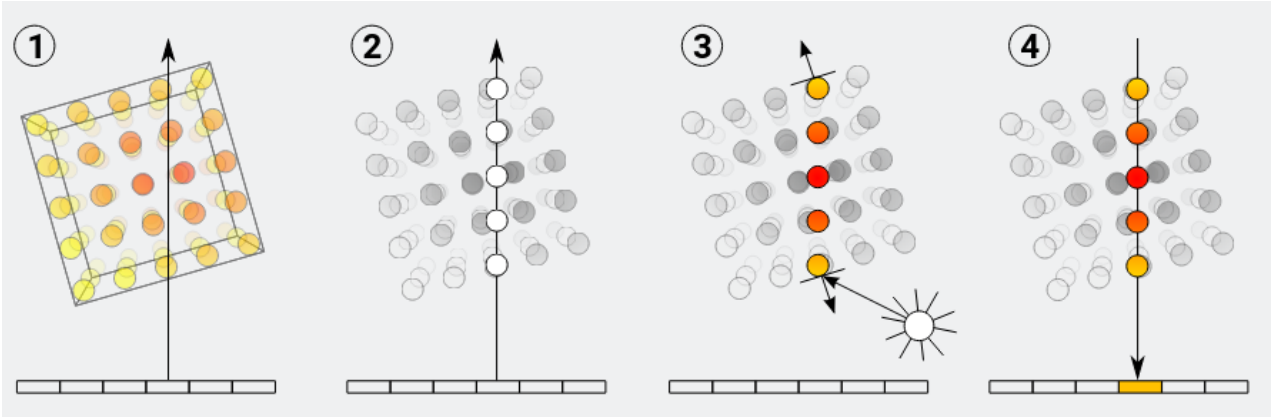


Volume Rendering

Idea: Collect voxels along line**s** of sight, show cummulated value.

1) Cast ray to get value for every screen pixel
2) Fetch (off-grid) voxel values along the ray
3) Assign color considering coloring scheme, lighting conditions, transfer function
4) Composite colors to a final shown one



A true rendering is expensive:

- **Large** viewing **window** → **more rays** to be cast… and inspected
- **Large volume** → **each ray** needs to visit **more voxels** to obtain the display value
- New camera position → **recompute all over**

Volume Rendering

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- *New camera position* → ***recompute all over***
- But requires no data understanding

Consider:

- Requesting smaller window to display the rendering
- Downscaling the displayed volume

Idea B: Decide what is foreground and background in the image, fit 3D surface mesh to the foreground, triangles take color from image, do standard rendering of triangles

- Actually, particularly popular solution…

Volume Rendering

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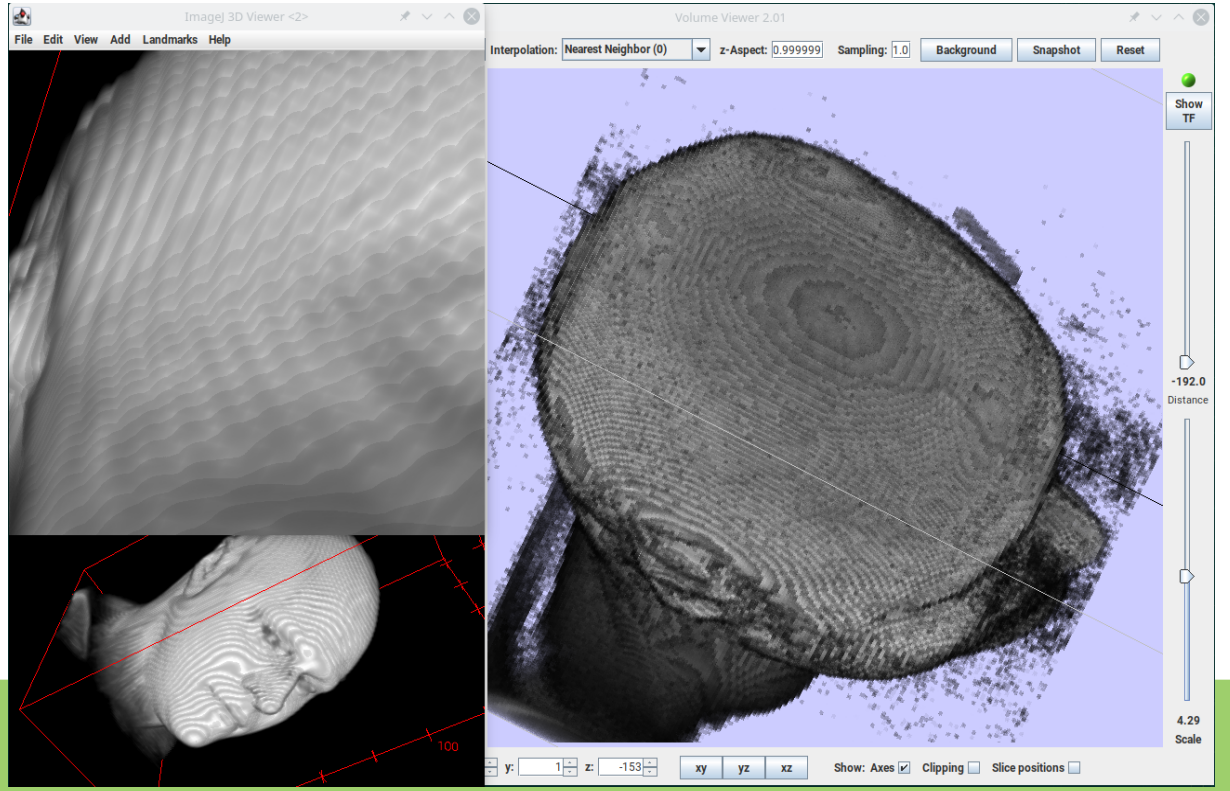
Example SW freely in Fiji:

- **3D Viewer** →
- **Volume Viewer** →
- 3D script
  - Rendering post-processed
  - Video exports
  - Friendly animation narrator



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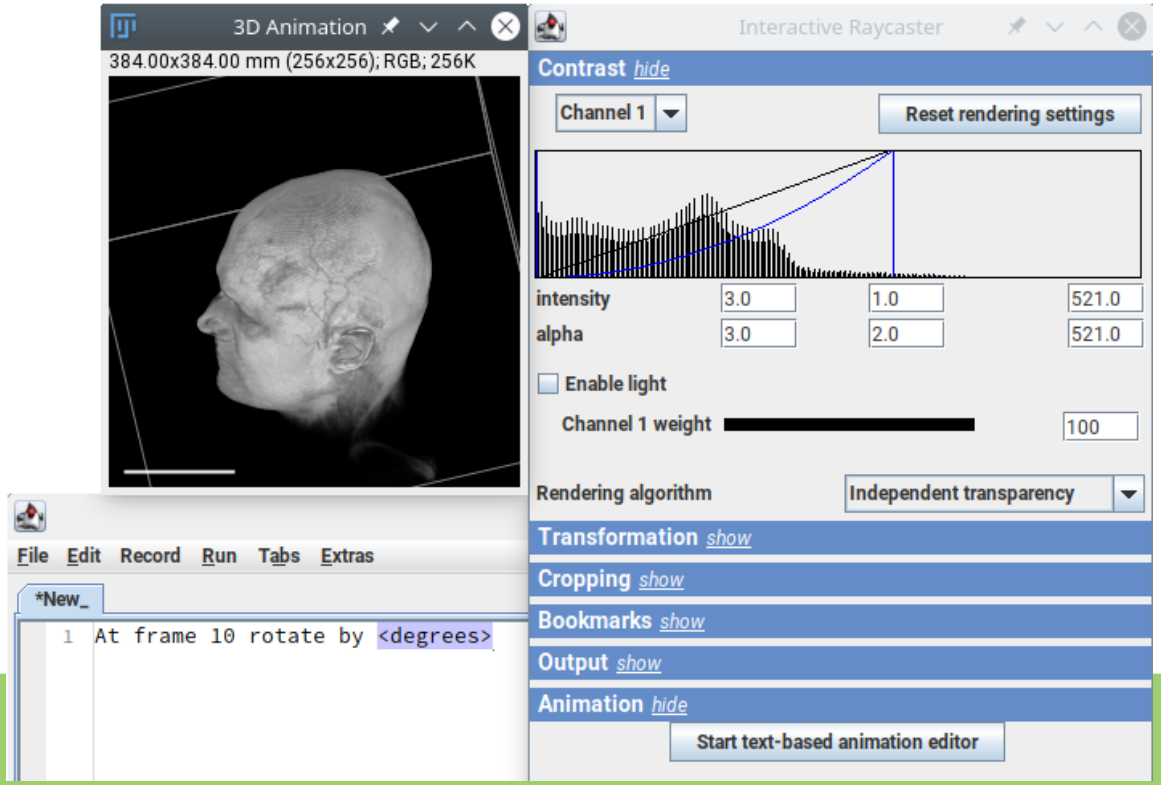
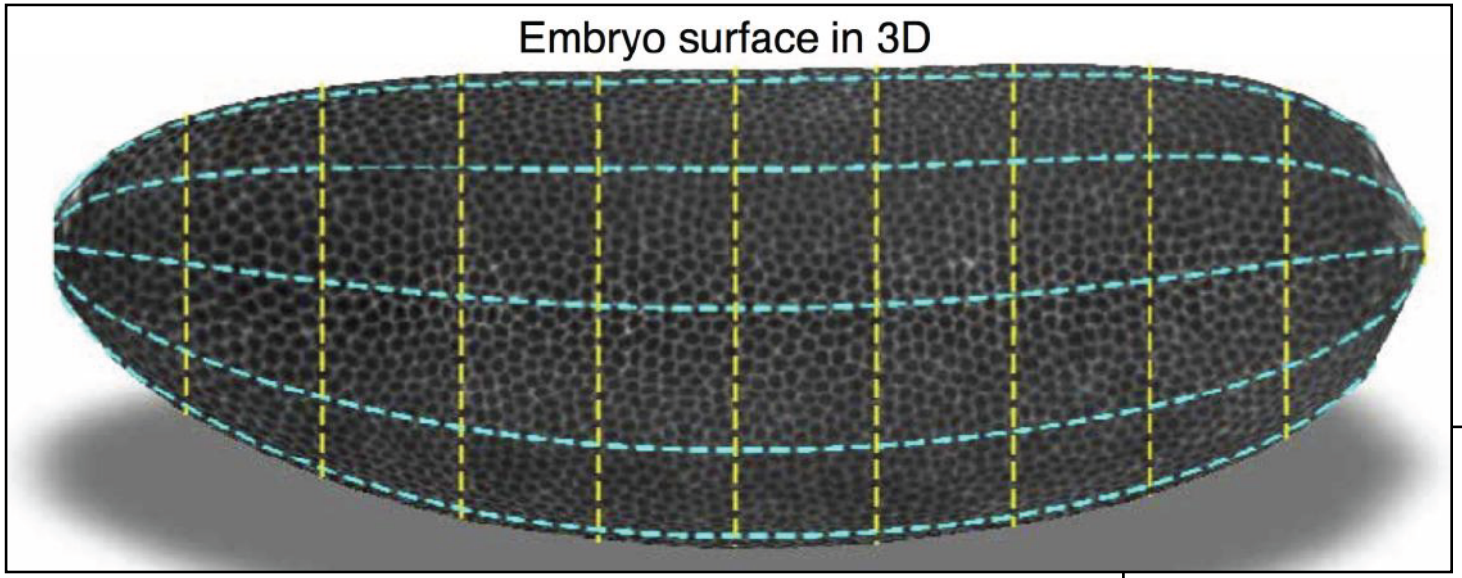
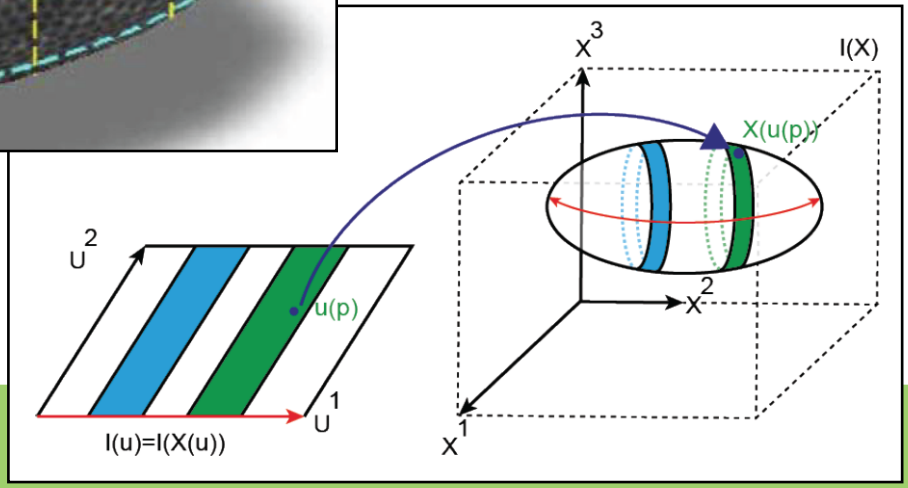


Cartographic Projections

Idea: (Interesting) Data is mostly on a mathematical-ish object? Unfold!



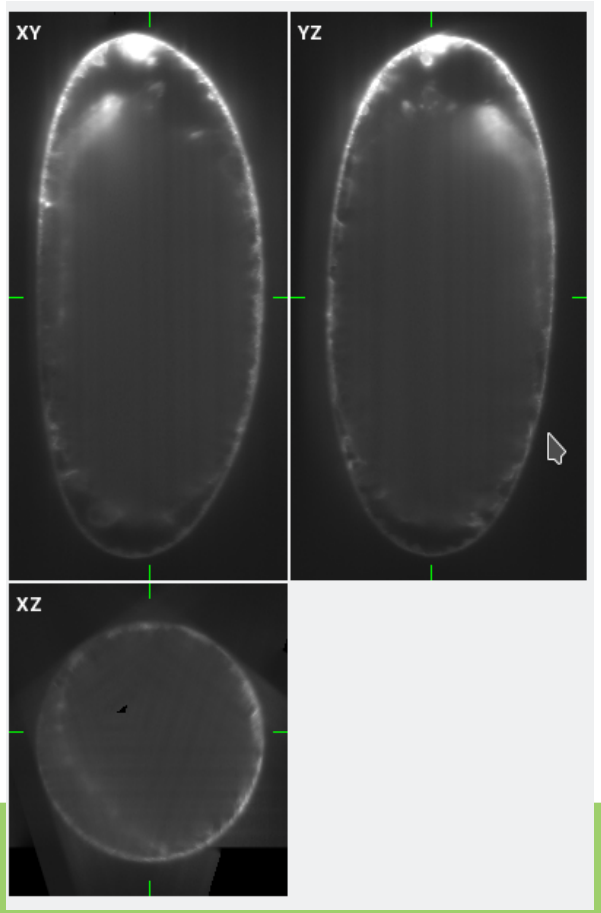


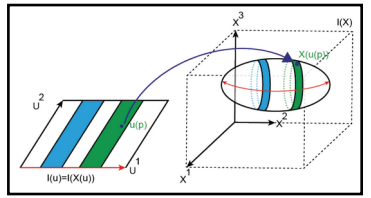
Cartographic Projections

Idea: (Interesting) Data is mostly on a mathematical-ish object? Unfold!

“Classical”

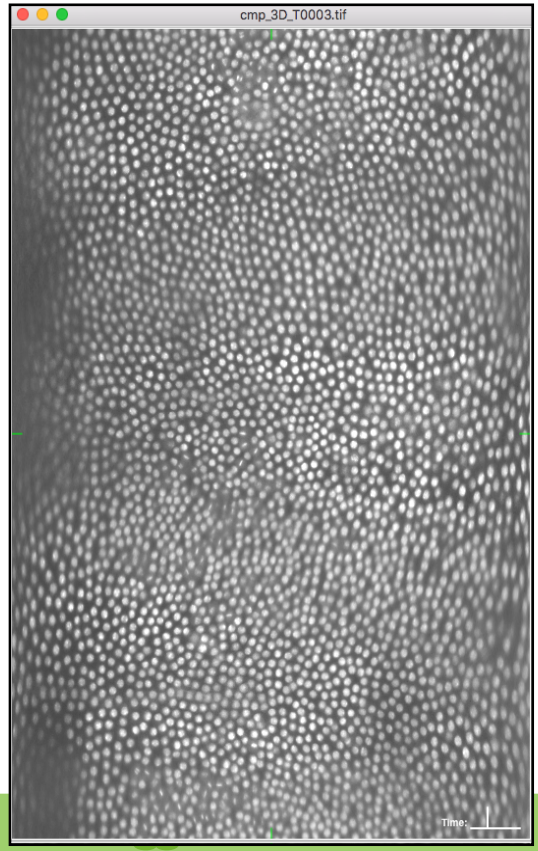
3D volume





Cartographic

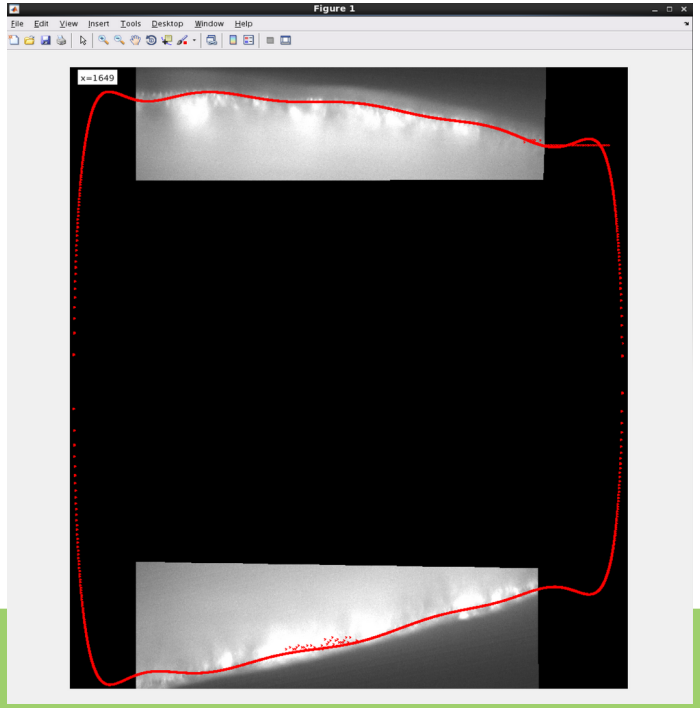
2D slice

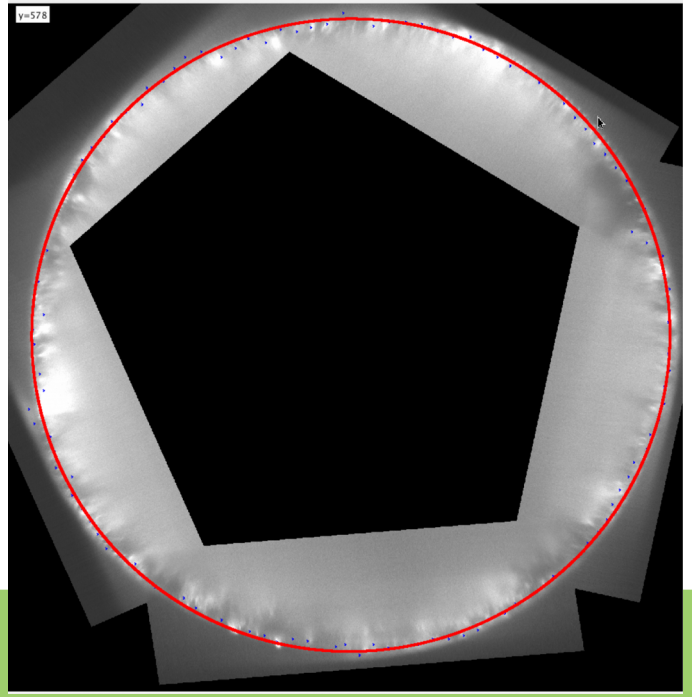


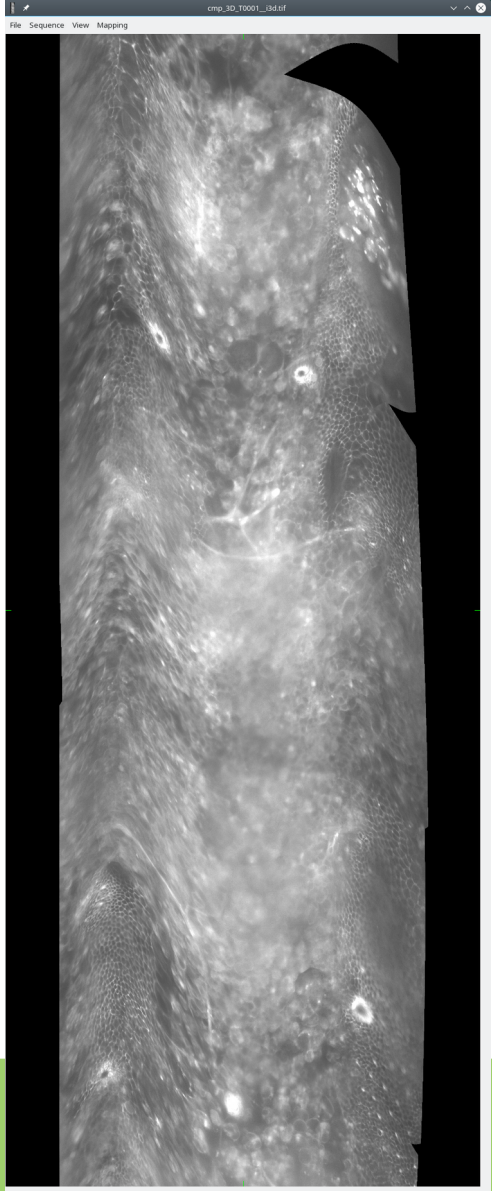
Cartographic Projections

Idea: (Interesting) Data is mostly on a mathematical-ish object?

- Requires precise boundary detection…
- Reduces data, here to 1000x
  3D 42.5 GB (2990 x 2536 x 3011) → 2D 41.8 MB (2517 x 8716)







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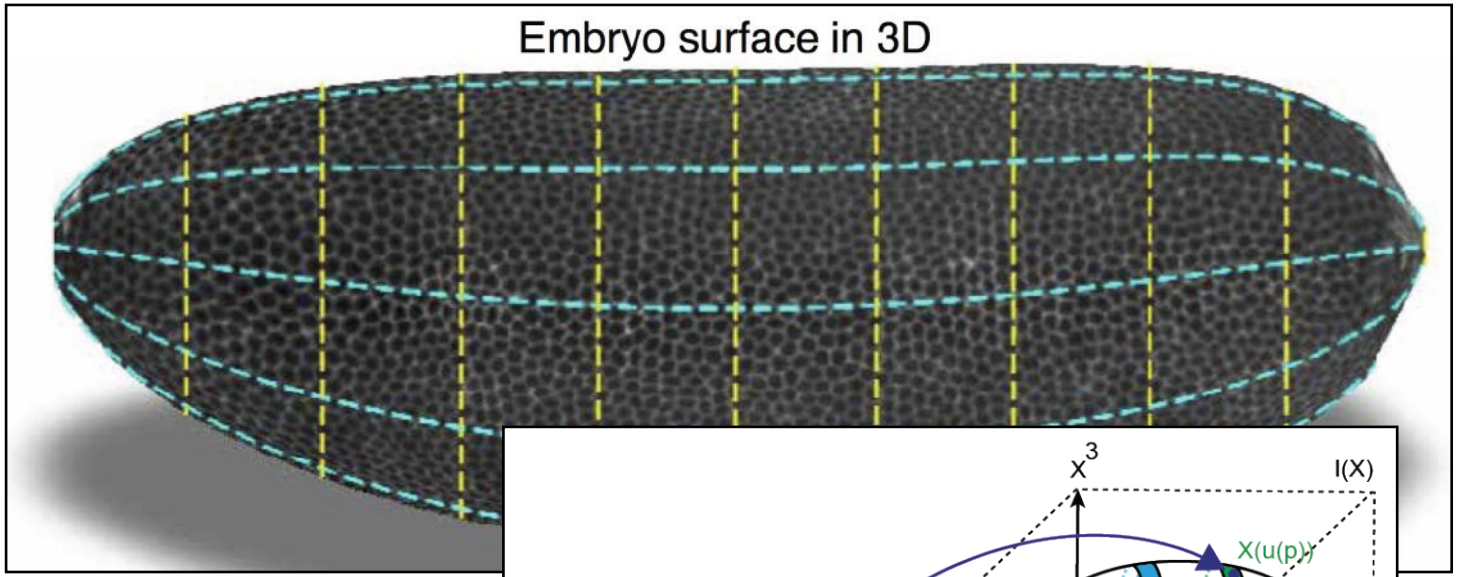
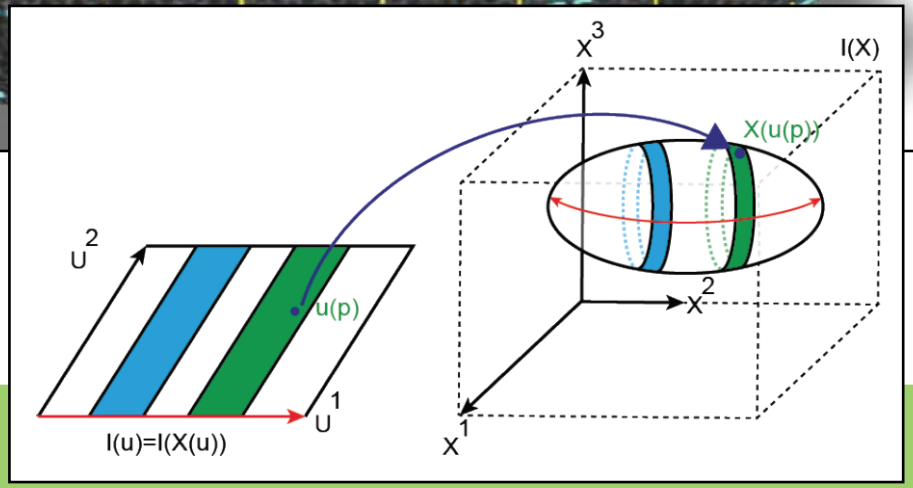
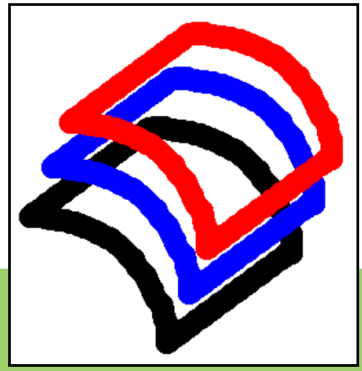




“Onion” layers



Cartographic Projections

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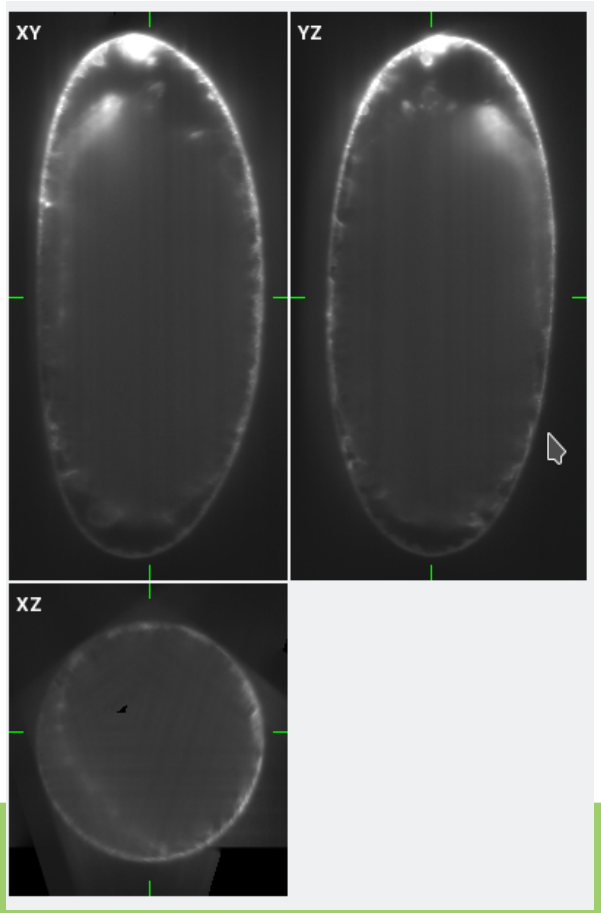
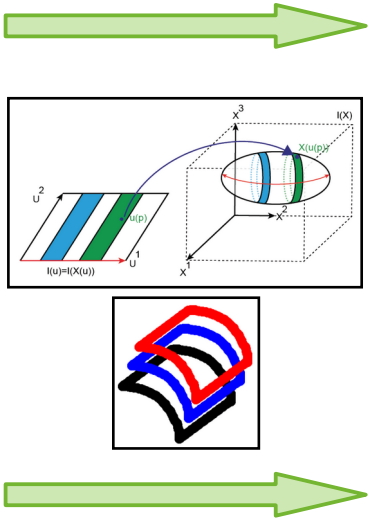
“Classical”

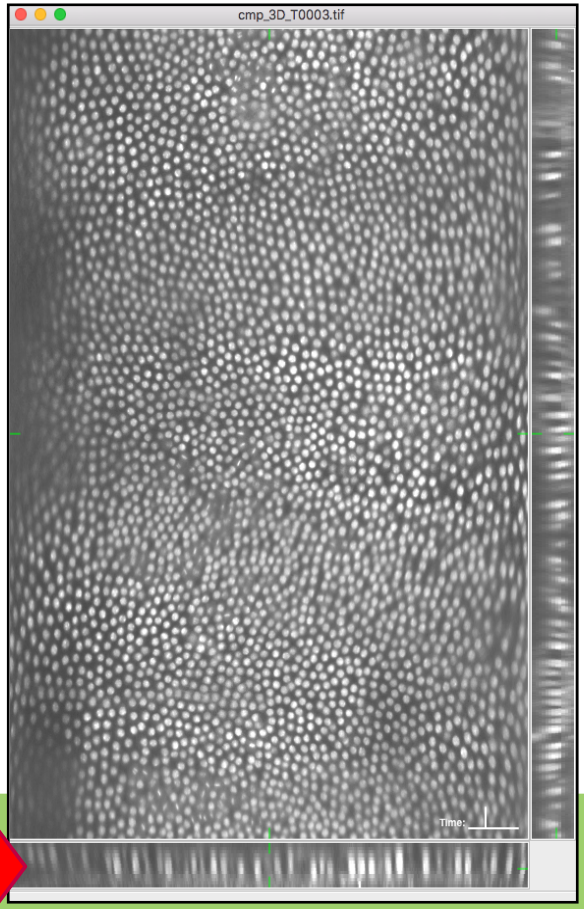
3D volume



Cartographic

3D volume



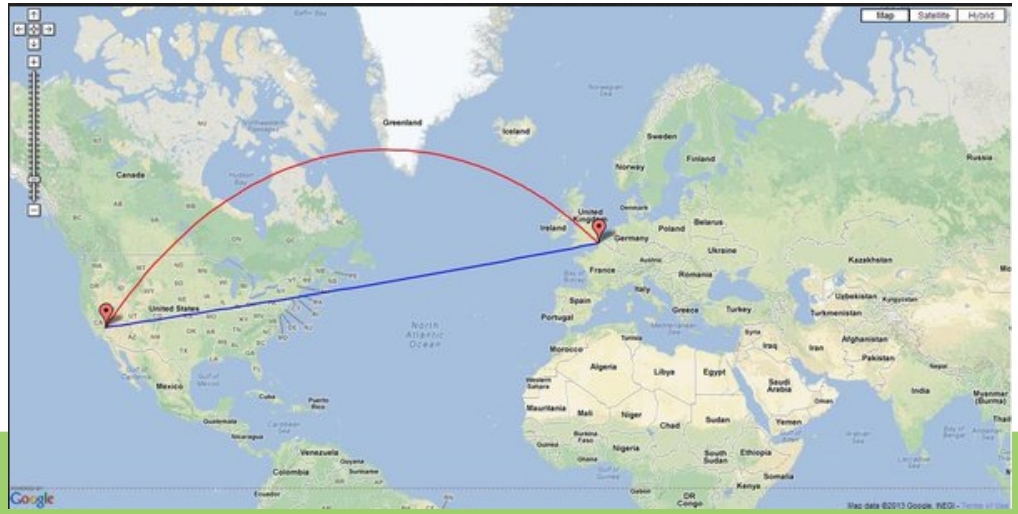


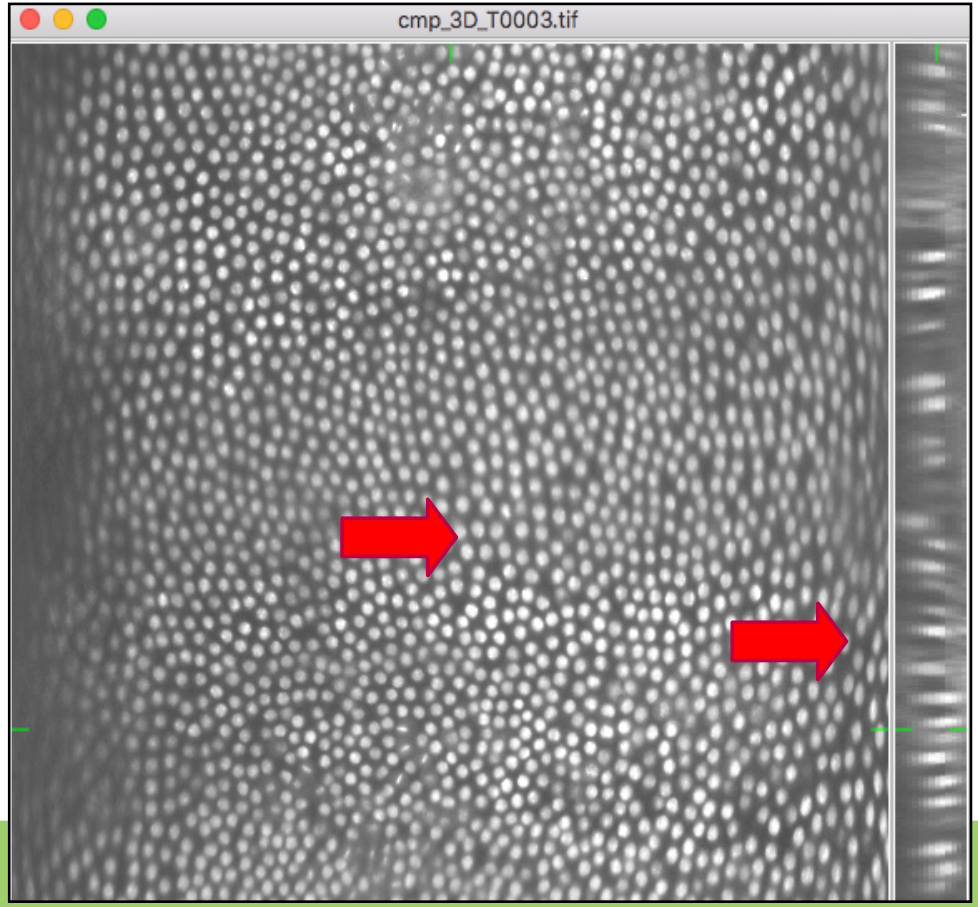
Cartographic Projections

Idea: (Interesting) Data is mostly on a mathematical-ish object?

- *Requires precise boundary detection…*
- *Reduces data…*

- **Distorts data**
  Is the flight route EU→US a direct line?





Cartographic Projections

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- *Requires precise boundary detection…*
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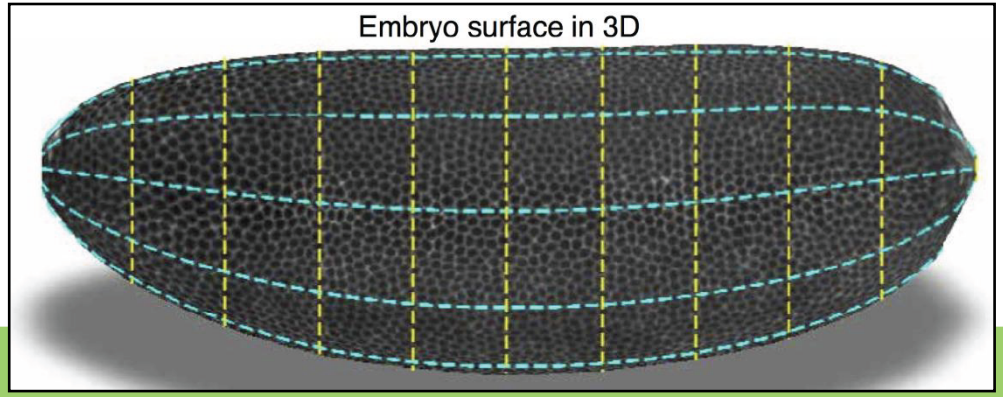
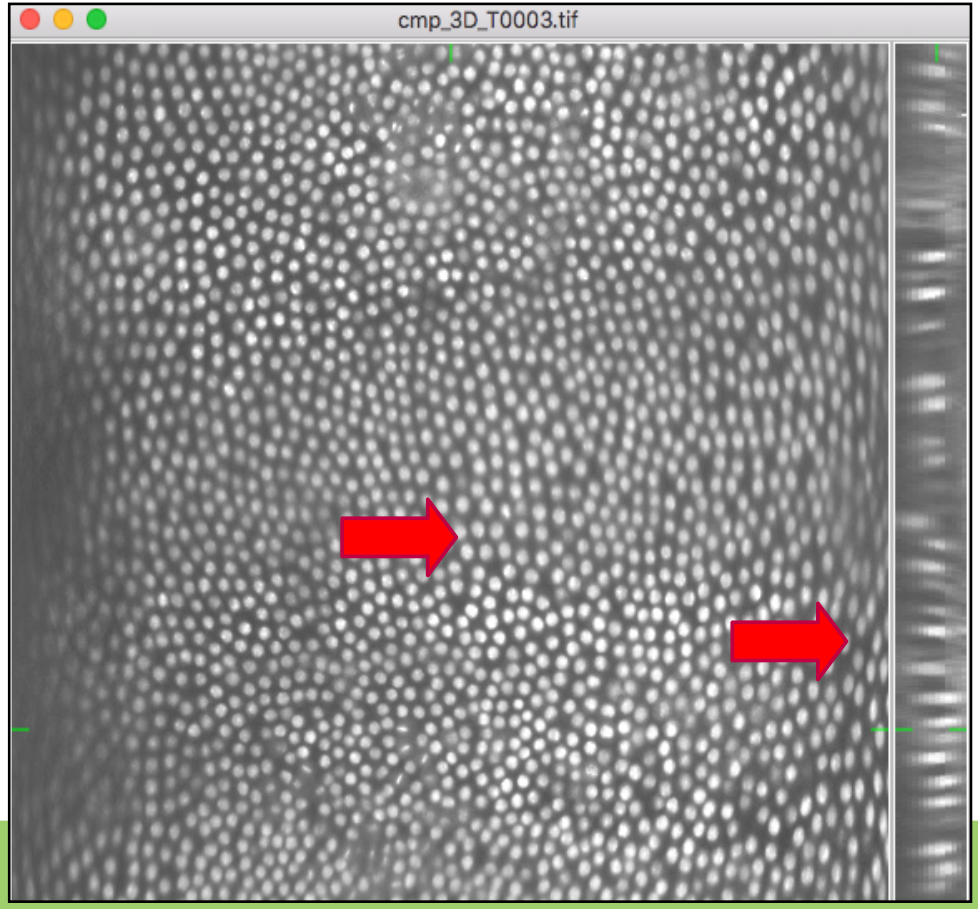
- **Distorts data** (**SW:** ImSAnE, Matlab)
  - Maps to a “horizontal” cylinder
  - Voxels at poles are stretched





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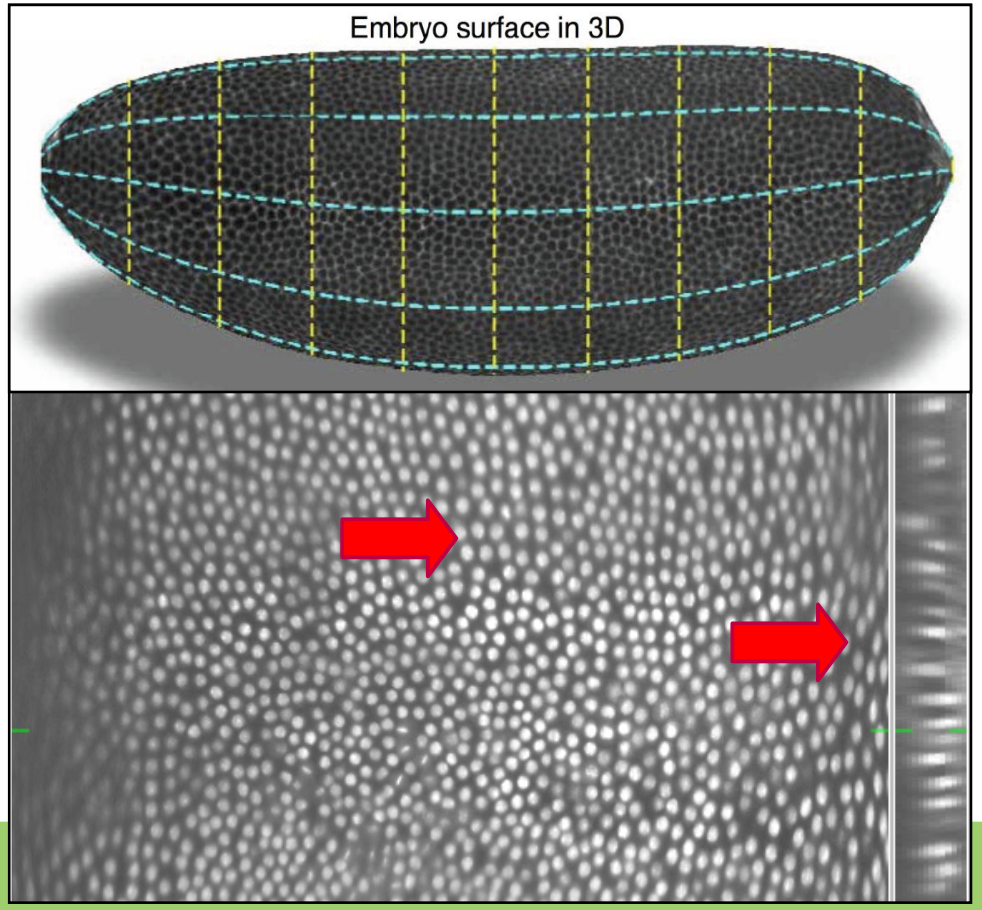
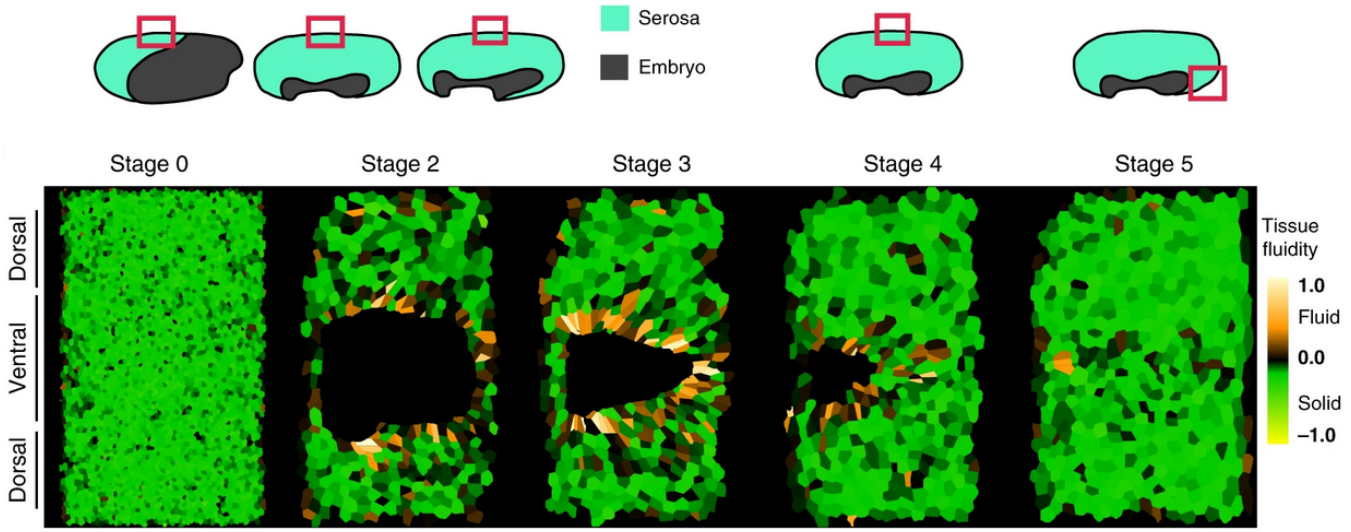
- *Reduces data…*

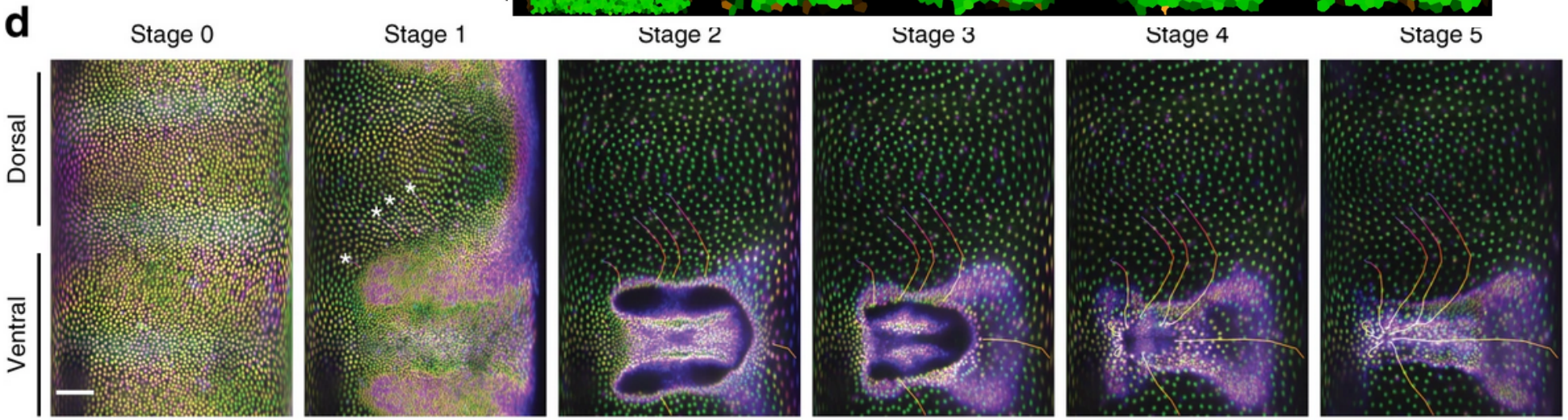
- **Distorts data** (**SW:** ImSAnE, Matlab)
  - Maps to a “horizontal” cylinder
  - Voxels at poles are stretched
  - Spatially varies
    - Real dist. between carto-pixels
    - Real area a carto-pixel represents
  - Known surface provides **correction maps**
  - **Adapted** image processing routines



Cartographic Projections

- From Jain et al. 2020:
- Development of cell properties
  - Fluidity → →
  - Position:





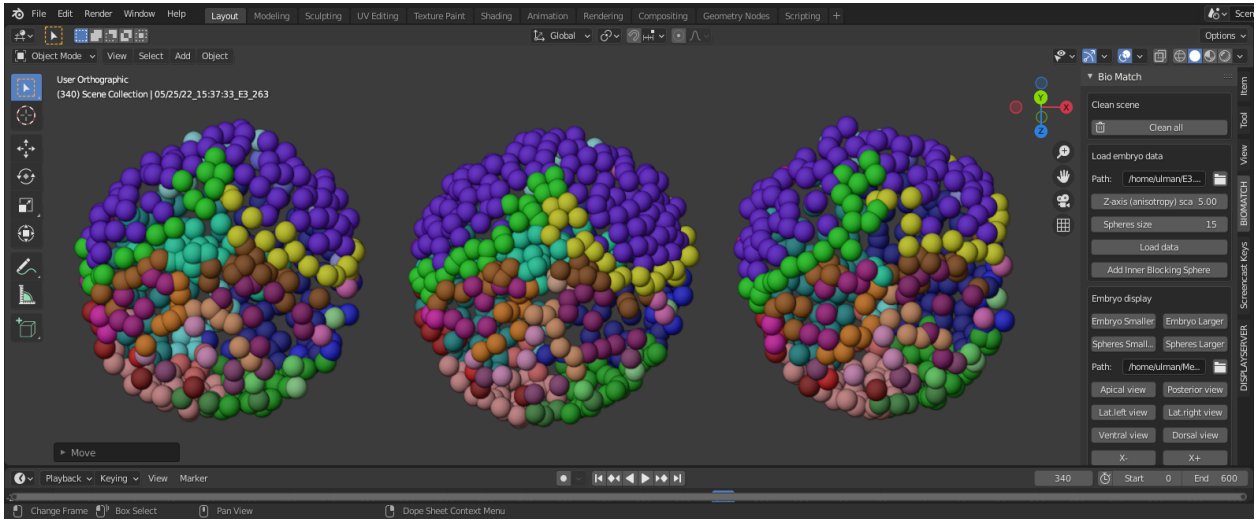
Graphical Representations

Idea: Show (3D) tabular data with computer graphics primitives.

➡ Suprissingly informative desptite tremendous information reduction.

Example SW

- SciView in Fiji
  - Uses BVV
  - Future Fiji viewer(?)



- Blender → → →
  - https://www.blender.org/
  - ”*Blender is Free and Open Source software, forever.*”

Graphical Representations

Idea: Show (3D) tabular data with computer graphics primitives.

Suprissingly informative desptite tremendous information reduction.

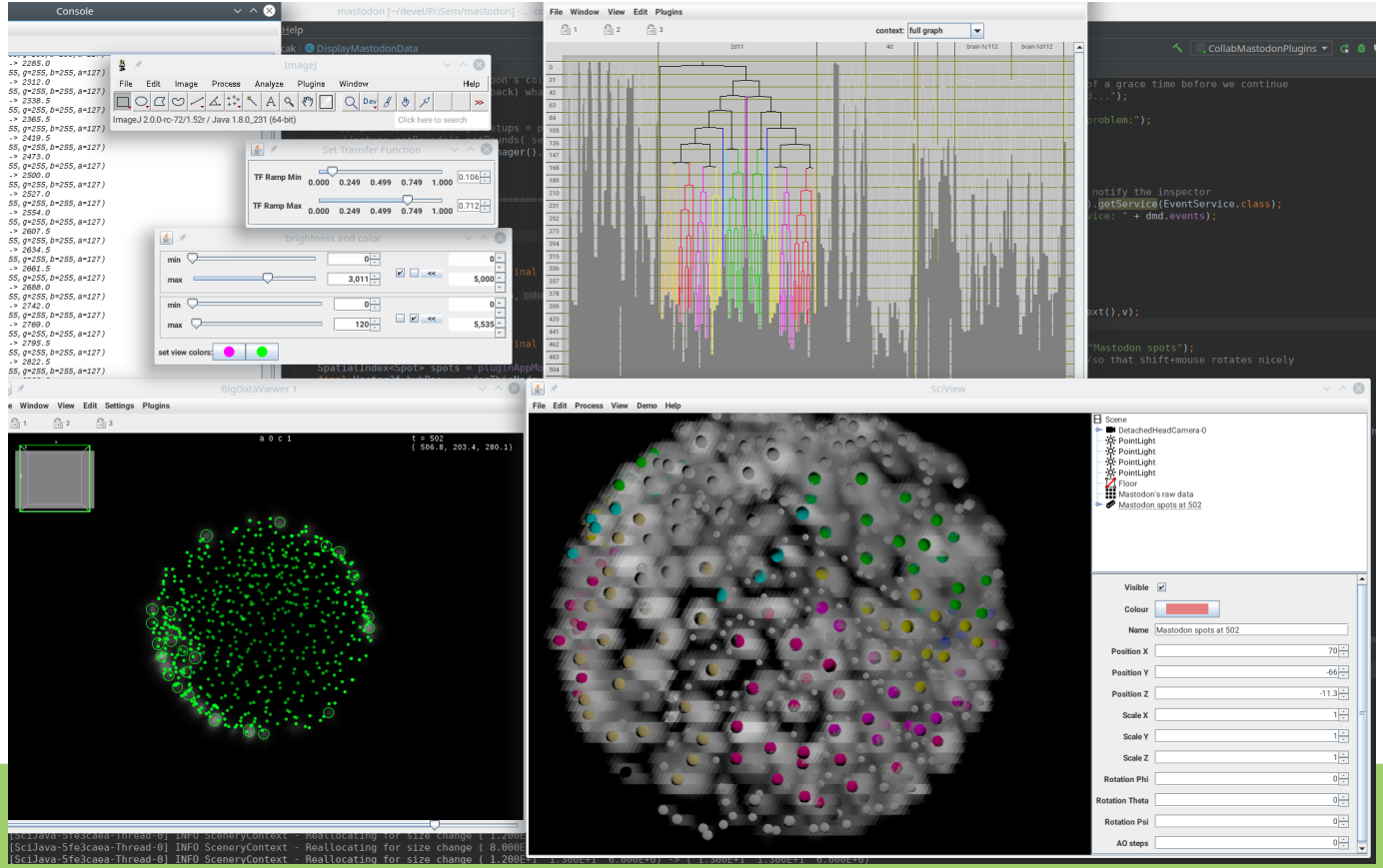
```
# from project /home/ulman/aa__triangleMethodTesting.mastodon
# TIME   X  Y  Z  TRACK_ID PARENT_TRACK_ID   SPOT LABEL

# one tree of tracks:
#  1
0  363.25   511.55000000000007   56.000000000000002 1  0  S
1  365.44999999999993   508.25   56.000000000000002 1  0  38
2  365.44999999999993   508.25   56.000000000000002 1  0  39
3  365.44999999999993   508.25   56.000000000000002 1  0  40
4  365.44999999999993   508.25   56.000000000000002 1  0  41
5  365.44999999999993   508.25   56.000000000000002 1  0  42
6  365.44999999999993   508.25   56.000000000000002 1  0  43
7  365.44999999999993   508.25   56.000000000000002 1  0  44


# one tree of tracks:
#  2
0  373.15   88.050000000000028 56.000000000000001 2  0  N
1  363.25   291.55   56.000000000000001 2  0  24
2  363.25   291.55   56.000000000000001 2  0  25
3  363.25   291.55   56.000000000000001 2  0  26
4  363.25   291.55   56.000000000000001 2  0  27
5  363.25   291.55   56.000000000000001 2  0  28
6  363.25   291.55   56.000000000000001 2  0  29
7  363.25   291.55   56.000000000000001 2  0  30
```

Graphical Representations

- SciView visualization (2020): featuring tag colors, **vol. rendering**, spots, trajectories, adjustable vizu, interconnected!



also: little fragile, HW heavy

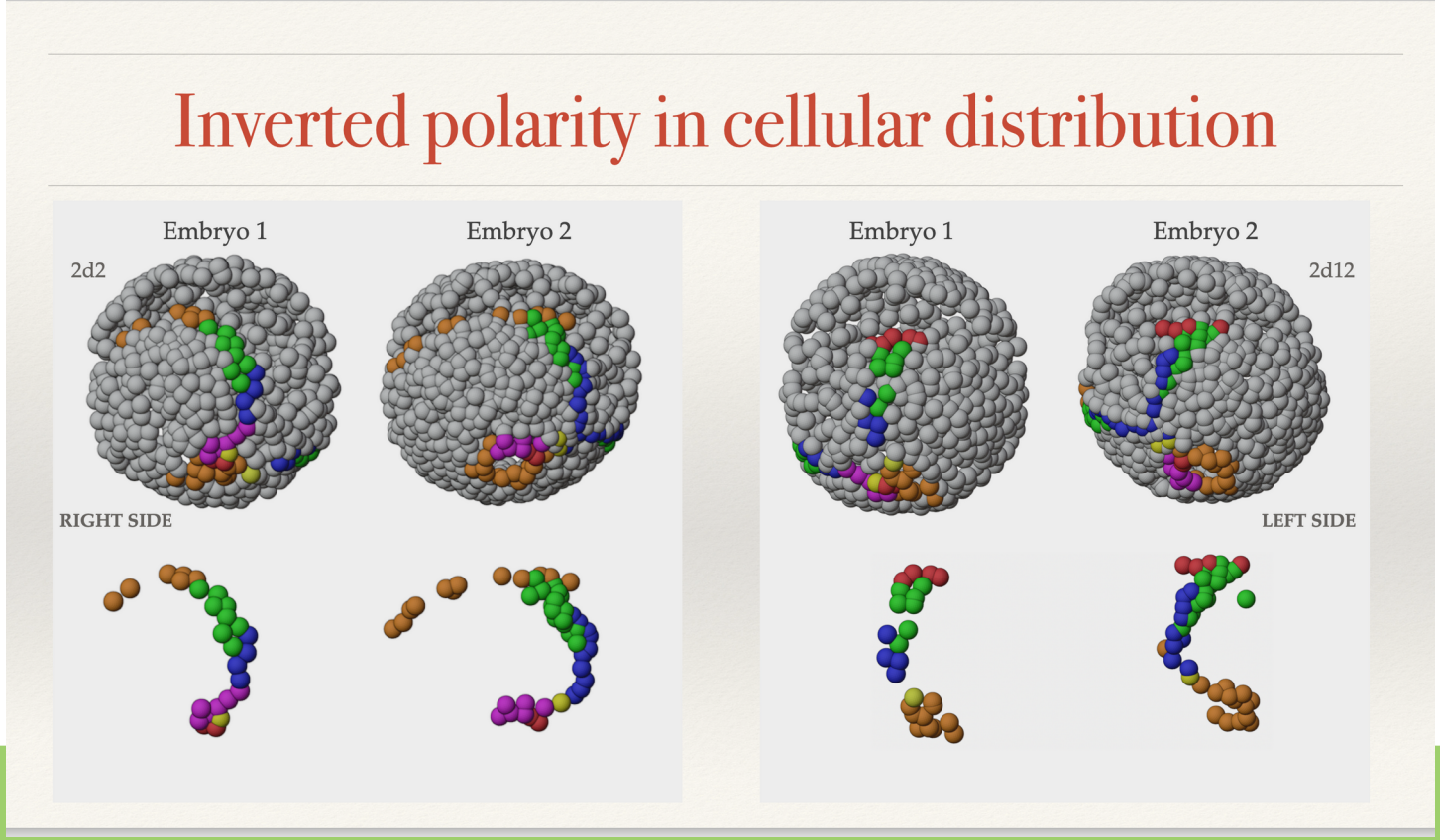
Graphical Representations

- Blender visualization (newest, 2021):

stable, known, advanced…

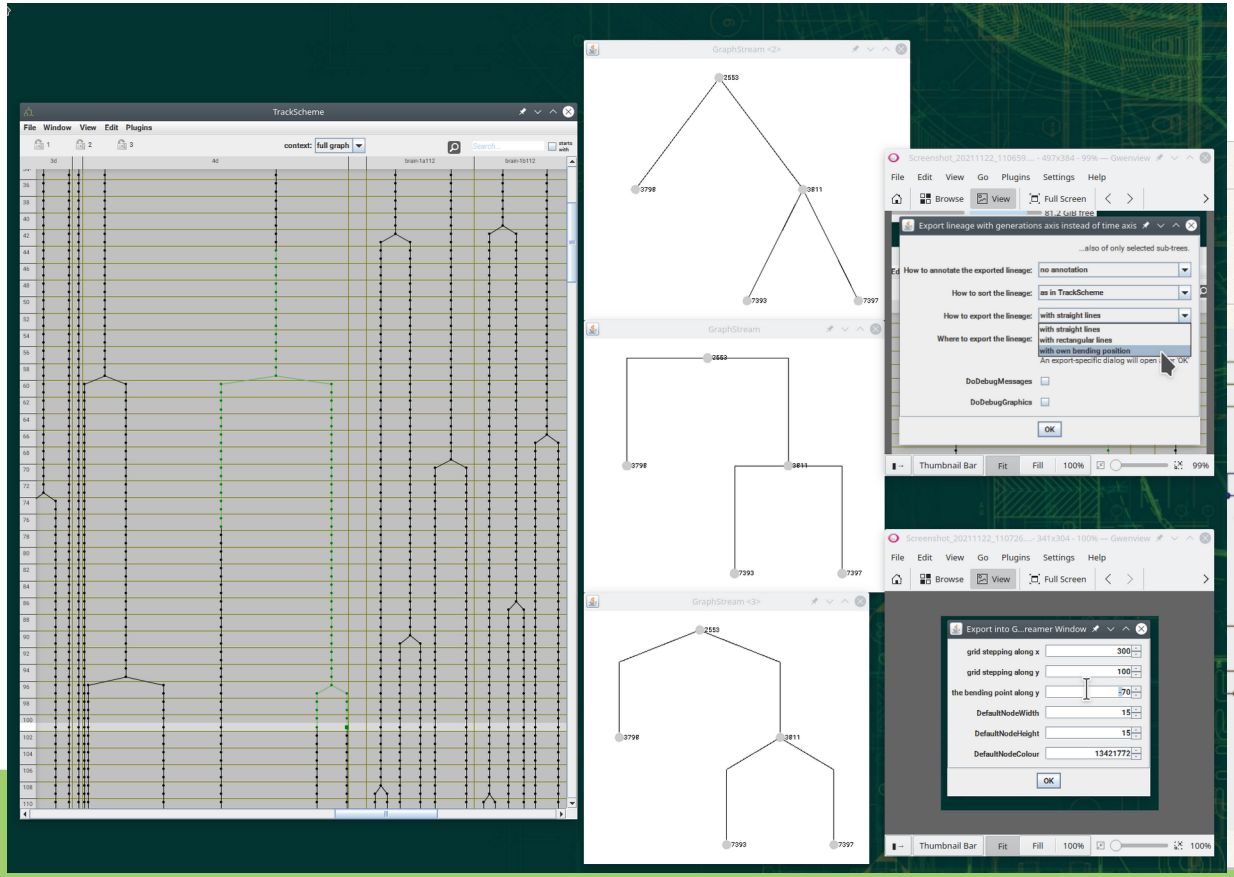
overwhelming, google-able

capable, performant

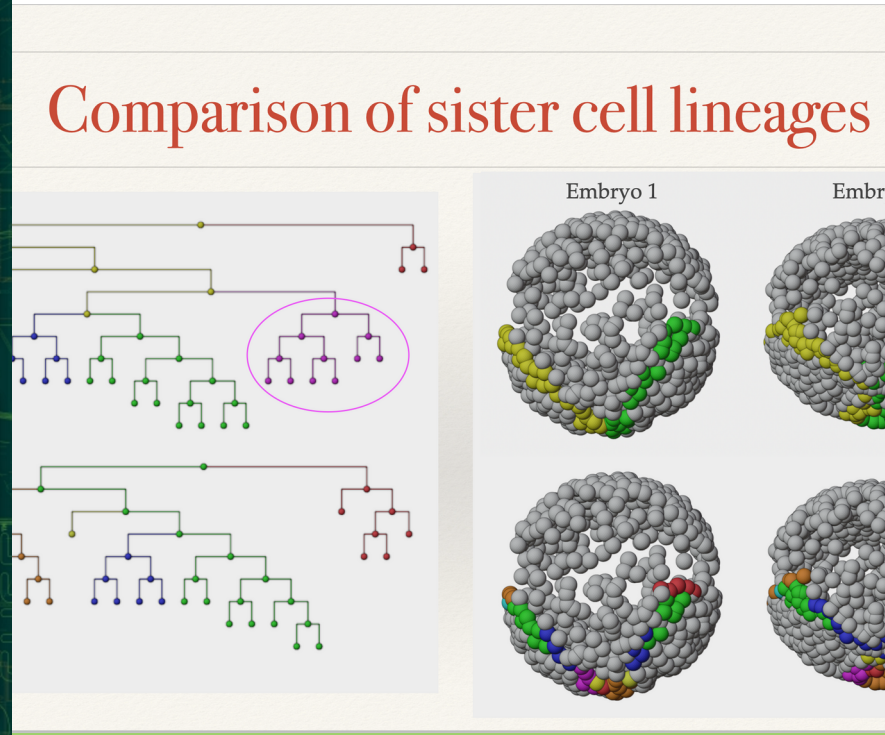


Graphical Representations

- Blender visualization (newest, 2021):

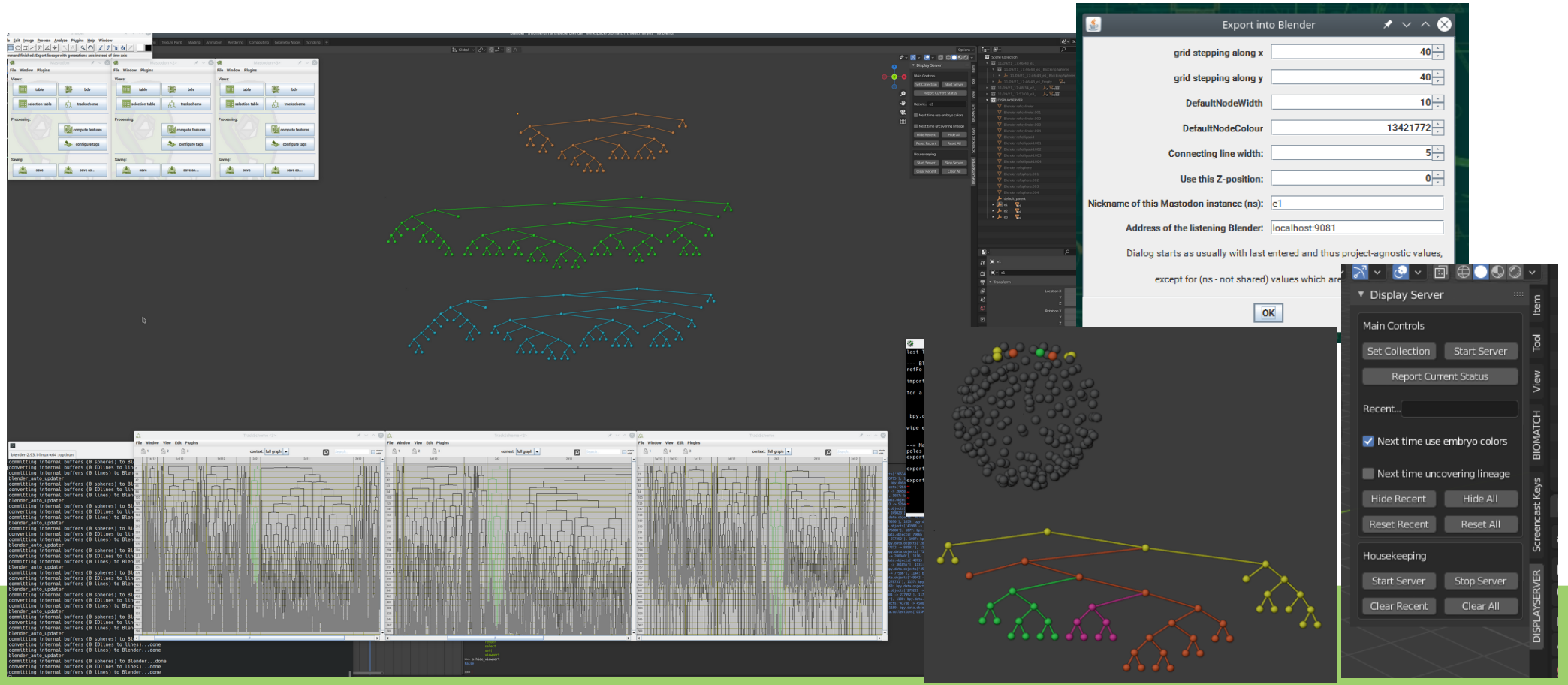


lineage vizu (options)



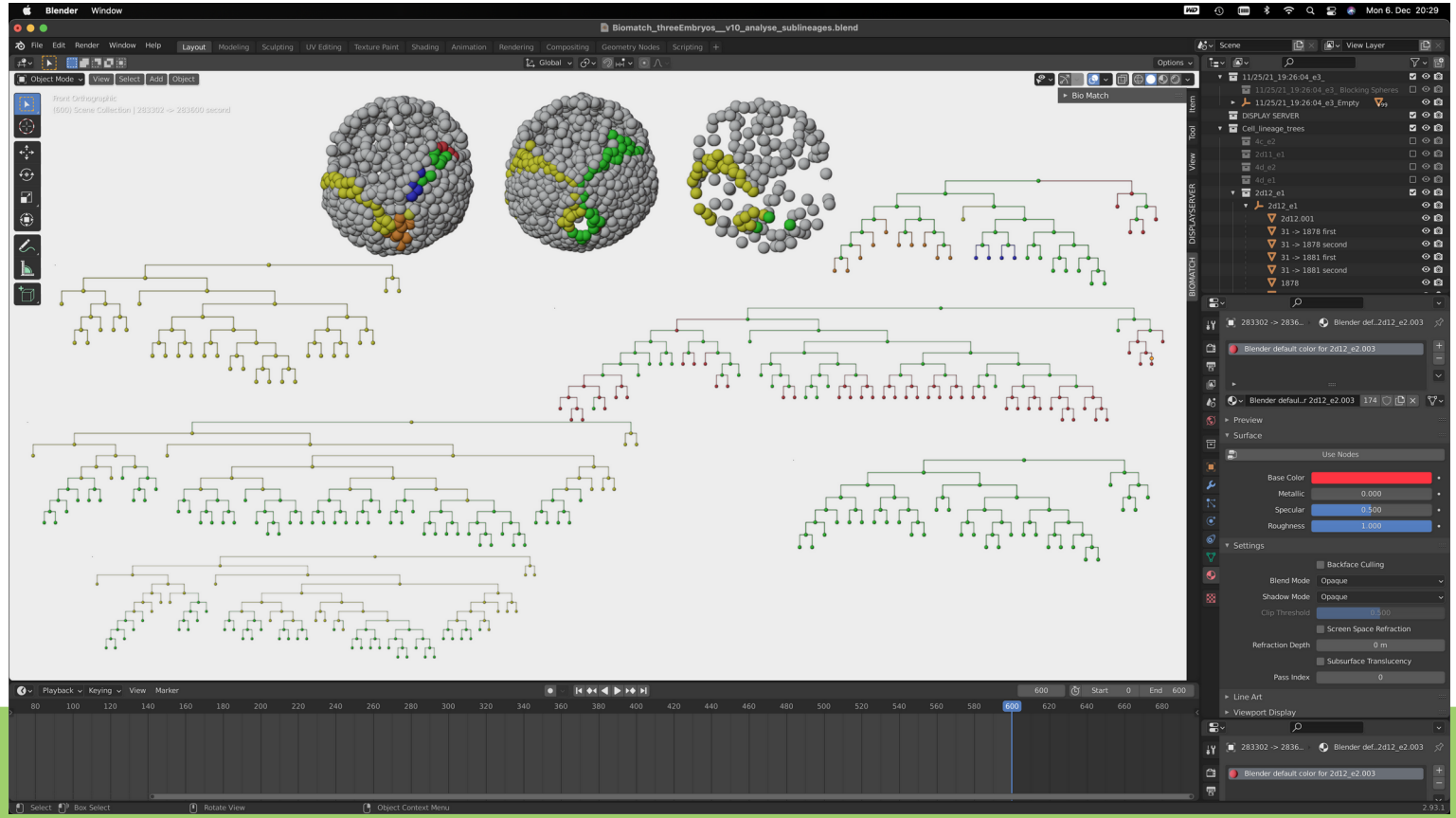
Graphical Representations

- Blender visualization (newest, 2021): comparing trees (4K LCD)



Graphical Representations

- Blender visualization (newest, 2021):



flexibility,

animations,

interactivity,

ATM: <u>very</u>

much a

prototype

THANK YOU

- I thank all my colleagues and supporters

- I’m available both weeks, full time
- I’m here to help
  ….and also to experiment ;-)
- Please, don’t hesitate to approach me

- Download: **https://www.fi.muni.cz/~xulman/files/EMBO_LS2022.pdf**