

# Unified Approach to Polynomial Algorithms on Graphs of Bounded (bi-)Rank-width

## Petr Hliněný,\* Robert Ganian and Jan Obdržálek

Faculty of Informatics, Masaryk University Botanická 68a, 60200 Brno, Czech Republic

e-mail: hlineny@fi.muni.cz ganian@mail.muni.cz http://www.fi.muni.cz/~hlineny
obdrzalek@fi.muni.cz

P. Hliněný et al., CSASC 201

XP algorithms for bounded (bi-)rank-width

## 0 Introduction

In this presentation, we will mix some very general (and abstract) ideas about graph *"width" decompositions* and dynamic programming algorithms on those, with specific applications to efficient algorithms for hard problems running on *rank-decompositions* of graphs.

## 0 Introduction

In this presentation, we will mix some very general (and abstract) ideas about graph *"width" decompositions* and dynamic programming algorithms on those, with specific applications to efficient algorithms for hard problems running on *rank-decompositions* of graphs.

### Talk Outline

1	Measuring Graph "Width"	3
2	Dynamic Algorithms and Parse Trees	7
3	Parse Trees for Rank-Decompositions	10
4	Canonical Equivalence and Algorithms	12
5	Unified Design Style of XP Algorithms	14
6	Conclusions	17

## 1 Measuring Graph "Width"

Motivation: Trees are easy to understand and to handle, so how "tree-like" our graphs are ..., in some well-defined sense?

 A topic occuring both in pure theory (e.g. Graph Minors), and in algorithms (Fixed parameter tractability).

## 1 Measuring Graph "Width"

Motivation: Trees are easy to understand and to handle, so how "tree-like" our graphs are ..., in some well-defined sense?

- A topic occuring both in pure theory (e.g. Graph Minors), and in algorithms (Fixed parameter tractability).
- Many definitions have been studied so far,
   e.g. tree-width, path-width, branch-width, DAG-width ...

## 1 Measuring Graph "Width"

Motivation: Trees are easy to understand and to handle, so how "tree-like" our graphs are ..., in some well-defined sense?

- A topic occuring both in pure theory (e.g. Graph Minors), and in algorithms (Fixed parameter tractability).
- Many definitions have been studied so far,
   e.g. tree-width, path-width, branch-width, DAG-width ...
- **Clique-width** another graph complexity measure [Courcelle and Olariu], defined by operations on vertex–labeled graphs:
  - create a new vertex with label i,
  - take the disjoint union of two labeled graphs,
  - add all edges between vertices of label i and label j,
  - and relabel all vertices with label i to have label j.

### Rank-Decompositions (a "better view" of clique-width)

 [Oum and Seymour, 03] Bringing the branch-decomposition approach to measure "complexity" of vertex subsets X ⊆ V(G) via cut-rank:

$$\mathcal{Q}_{G}(X) = \text{rank of} \quad X \begin{pmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 \end{pmatrix} \text{ modulo } 2$$

#### Rank-Decompositions (a "better view" of clique-width)

 [Oum and Seymour, 03] Bringing the branch-decomposition approach to measure "complexity" of vertex subsets X ⊆ V(G) via cut-rank:

$$\varrho_{G}(X) = \operatorname{rank} \operatorname{of} X \begin{pmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 \end{pmatrix} \operatorname{modulo} 2$$

**Definition.** Decompose V(G) one-to-one into the leaves of a subcubic tree. Then



width $(e) = \rho_G(X)$  where X is displayed by f in the tree.

#### Rank-Decompositions (a "better view" of clique-width)

 [Oum and Seymour, 03] Bringing the branch-decomposition approach to measure "complexity" of vertex subsets X ⊆ V(G) via cut-rank:

$$\varrho_G(X) = \operatorname{rank} \operatorname{of} X \begin{pmatrix} 0 & 1 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 & 0 \\ 1 & 0 & 0 & 1 & 1 \end{pmatrix} \operatorname{modulo} 2$$

**Definition.** Decompose V(G) one-to-one into the leaves of a subcubic tree. Then



width $(e) = \rho_G(X)$  where X is displayed by f in the tree.

 $\mathsf{Rank-width} = \min_{\mathsf{rank-decs. of } G} \max \left\{ \mathsf{width}(f) : f \text{ tree edge} \right\}$ 

P. Hliněný et al., CSASC 201

XP algorithms for bounded (bi-)rank-width



- Rank-width t is related to clique-width k as  $t \leq k \leq 2^{t+1} 1$ .
- Both these measures are *NP*-hard in general.

- Rank-width t is related to clique-width k as  $t \leq k \leq 2^{t+1} 1$ .
- Both these measures are *NP*-hard in general.
- Clique-width *expressions* seem to be much more "explicit" than *rank- decompositions*, and more suited for design of actual algorithms.

On the other hand, however...

- Rank-width t is related to clique-width k as  $t \leq k \leq 2^{t+1} 1$ .
- Both these measures are *NP*-hard in general.
- Clique-width *expressions* seem to be much more "explicit" than *rank-decompositions*, and more suited for design of actual algorithms.

On the other hand, however...

• [Corneil and Rotics, 05] Clique-width can really be up to exponentially higher than rank-width.

- Rank-width t is related to clique-width k as  $t \le k \le 2^{t+1} 1$ .
- Both these measures are *NP*-hard in general.
- Clique-width *expressions* seem to be much more "explicit" than *rankdecompositions*, and more suited for design of actual algorithms.

On the other hand, however...

- [Corneil and Rotics, 05] Clique-width can really be up to exponentially higher than rank-width.
- [Oum and PH, 07] There is an *FPT algorithm* for computing an optimal rank-decomposition of a graph in time  $O(f(t) \cdot n^3)$ .

- Rank-width t is related to clique-width k as  $t \leq k \leq 2^{t+1} 1$ .
- Both these measures are *NP*-hard in general.
- Clique-width *expressions* seem to be much more "explicit" than *rankdecompositions*, and more suited for design of actual algorithms.

On the other hand, however...

- [Corneil and Rotics, 05] Clique-width can really be up to exponentially higher than rank-width.
- [Oum and PH, 07] There is an *FPT algorithm* for computing an optimal rank-decomposition of a graph in time  $O(f(t) \cdot n^3)$ .
- And some new results suggest that algorithms designed on rank-decompositions run faster than those designed on clique-width expressions...

- A typical idea for a *dynamic algorithm* on a "tree-like" decomposition:
  - Capture all relevant information about the problem on a subtree.
  - Process this information bottom-up in the decomposition.
  - Importantly, this information has limited polynomial size, ideally even constant independent of the input size.

- A typical idea for a *dynamic algorithm* on a "tree-like" decomposition:
  - Capture all relevant information about the problem on a subtree.
  - Process this information bottom-up in the decomposition.
  - Importantly, this information has limited polynomial size, ideally even constant independent of the input size.
- How to understand words "all relevant information about the problem"? Look for inspiration in traditional finite automata theory!

- A typical idea for a *dynamic algorithm* on a "tree-like" decomposition:
  - Capture all relevant information about the problem on a subtree.
  - Process this information bottom-up in the decomposition.
  - Importantly, this information has limited polynomial size, ideally even constant independent of the input size.
- How to understand words "all relevant information about the problem"? Look for inspiration in traditional finite automata theory!

Theorem. [Myhill–Nerode, folklore]
Finite automaton states (this is our information) ↔ *right congruence* classes on the words (of a regular language).

- A typical idea for a *dynamic algorithm* on a "tree-like" decomposition:
  - Capture all relevant information about the problem on a subtree.
  - Process this information bottom-up in the decomposition.
  - Importantly, this information has limited polynomial size, ideally even constant independent of the input size.
- How to understand words "all relevant information about the problem"? Look for inspiration in traditional finite automata theory!

Theorem. [Myhill–Nerode, folklore]
Finite automaton states (this is our information) ↔ *right congruence* classes on the words (of a regular language).

• Combinatorial extensions of this concept appeared e.g. in the works [Abrahamson and Fellows, 93], [PH, 03], or [Ganian and PH, 08].

How does the right congruence extend from formal words with the concatention operation to, say, graphs with a kind of a "join" operation?

How does the right congruence extend from formal words with the concatention operation to, say, graphs with a kind of a "join" operation?

- Consider the universe of graphs  $\mathcal{U}_k$  implicitly associated with
  - some (small) distinguished "boundary of size k" of each graph, and
  - a join operation  $G \oplus H$  acting on the boundaries of disjoint G, H.
- Let  ${\mathcal P}$  be a graph property we study.

How does the right congruence extend from formal words with the concatention operation to, say, graphs with a kind of a "join" operation?

- Consider the universe of graphs  $U_k$  implicitly associated with
  - some (small) distinguished "boundary of size k" of each graph, and - a join operation  $G \oplus H$  acting on the boundaries of disjoint G, H.
- Let  $\mathcal{P}$  be a graph property we study.

**Definition.** The canonical equivalence of  $\mathcal{P}$  on  $\mathcal{U}_k$  is defined:  $G_1 \approx_{\mathcal{P}, k} G_2$  for any  $G_1, G_2 \in \mathcal{U}_k$  if and only if, for all  $H \in \mathcal{U}_k$ ,  $G_1 \oplus H \in \mathcal{P} \iff G_2 \oplus H \in \mathcal{P}$ .

How does the right congruence extend from formal words with the concatention operation to, say, graphs with a kind of a "join" operation?

- Consider the universe of graphs  $\mathcal{U}_k$  implicitly associated with
  - some (small) distinguished "boundary of size k" of each graph, and
  - a join operation  $G \oplus H$  acting on the boundaries of disjoint G, H.
- Let  ${\mathcal P}$  be a graph property we study.

**Definition.** The *canonical equivalence* of  $\mathcal{P}$  on  $\mathcal{U}_k$  is defined:

 $G_1 \approx_{\mathcal{P},k} G_2$  for any  $G_1, G_2 \in \mathcal{U}_k$  if and only if, for all  $H \in \mathcal{U}_k$ ,

 $G_1 \oplus H \in \mathcal{P} \iff G_2 \oplus H \in \mathcal{P}.$ 

• Informally, the classes of  $\approx_{\mathcal{P},k}$  capture all information about the property  $\mathcal{P}$  that can "cross" our graph boundary of size k (regardless of actual meaning of "boundary" and "join").

P. Hliněný et al., CSASC 2010

XP algorithms for bounded (bi-)rank-width

### Parse trees of decompositions

To give a real usable meaning to the above terms "boundary, join, and universe" we set them in the context of tree-shaped decompositions as follows...

### Parse trees of decompositions

To give a real usable meaning to the above terms "boundary, join, and universe" we set them in the context of tree-shaped decompositions as follows...

- Considering a rooted ???-decomposition of a graph *G*, we build on the following correspondence:
  - *boundary size*  $k \leftrightarrow$  restricted bag-size / width / etc in decomposition
  - *join operator*  $\oplus \leftrightarrow$  the way pieces of G "stick together" in decomp.

### Parse trees of decompositions

To give a real usable meaning to the above terms "boundary, join, and universe" we set them in the context of tree-shaped decompositions as follows...

• Considering a rooted ???-decomposition of a graph G, we build on the following correspondence:

boundary size  $k \leftrightarrow$  restricted bag-size / width / etc in decomposition join operator  $\oplus \leftrightarrow$  the way pieces of G "stick together" in decomp.

• This can be (visually) seen as. . .



XP algorithms for bounded (bi-)rank-width

Unlike for branch- or tree-decompositions with obvious parse trees, what is the "boundary" and "join" operation for rank-width?

Our "boundary" includes all vertices, and "join" is just an implicit matrix rank!

Unlike for branch- or tree-decompositions with obvious parse trees, what is the "boundary" and "join" operation for rank-width?

Our "boundary" includes all vertices, and "join" is just an implicit matrix rank!

• Bilinear product approach of [Courcelle and Kanté, 07]:

- boundary ~ labeling  $lab: V(G) \rightarrow 2^{\{1,2,\dots,t\}}$  (multi-colouring),

Unlike for branch- or tree-decompositions with obvious parse trees, what is the "boundary" and "join" operation for rank-width?

Our "boundary" includes all vertices, and "join" is just an implicit matrix rank!

- Bilinear product approach of [Courcelle and Kanté, 07]:
  - boundary ~ labeling  $lab: V(G) \rightarrow 2^{\{1,2,\dots,t\}}$  (multi-colouring),
  - join ~ bilinear form g over  $GF(2)^t$  (i.e. "odd intersection") s.t.

 $\mathsf{edge} \ uv \ \leftrightarrow \ lab(u) \cdot \mathbf{g} \cdot lab(v) = 1.$ 

Unlike for branch- or tree-decompositions with obvious parse trees, what is the "boundary" and "join" operation for rank-width?

Our "boundary" includes all vertices, and "join" is just an implicit matrix rank!

- Bilinear product approach of [Courcelle and Kanté, 07]:
  - boundary ~ labeling  $lab: V(G) \rightarrow 2^{\{1,2,\dots,t\}}$  (multi-colouring),
  - join ~ bilinear form g over  $GF(2)^t$  (i.e. "odd intersection") s.t. edge  $uv \leftrightarrow lab(u) \cdot g \cdot lab(v) = 1$ .
- Join  $\rightarrow$  a composition operator with relabelings  $f_1, f_2$ ;  $(G_1, lab^1) \otimes [\mathbf{g} \mid f_1, f_2] (G_2, lab^2) = (H, lab)$

 $\implies$  the rank-width **parse tree** [Ganian and PH, 08]:

Unlike for branch- or tree-decompositions with obvious parse trees, what is the "boundary" and "join" operation for rank-width?

Our "boundary" includes all vertices, and "join" is just an implicit matrix rank!

- Bilinear product approach of [Courcelle and Kanté, 07]:
  - boundary ~ labeling  $lab: V(G) \rightarrow 2^{\{1,2,\dots,t\}}$  (multi-colouring),
  - join ~ bilinear form g over  $GF(2)^t$  (i.e. "odd intersection") s.t. edge  $uv \leftrightarrow lab(u) \cdot g \cdot lab(v) = 1$ .
- Join  $\rightarrow$  a composition operator with relabelings  $f_1, f_2$ ;  $(G_1, lab^1) \otimes [\mathbf{g} \mid f_1, f_2] (G_2, lab^2) = (H, lab)$ 
  - $\implies$  the rank-width **parse tree** [Ganian and PH, 08]:

*t*-labeling parse tree for  $G \iff$  rank-width of  $G \le t$ .

Unlike for branch- or tree-decompositions with obvious parse trees, what is the "boundary" and "join" operation for rank-width?

Our "boundary" includes all vertices, and "join" is just an implicit matrix rank!

- Bilinear product approach of [Courcelle and Kanté, 07]:
  - boundary ~ labeling  $lab: V(G) \rightarrow 2^{\{1,2,\dots,t\}}$  (multi-colouring),
  - join ~ bilinear form  $\mathbf{g}$  over  $GF(2)^t$  (i.e. "odd intersection") s.t. edge  $uv \leftrightarrow lab(u) \cdot \mathbf{g} \cdot lab(v) = 1$ .
- Join  $\rightarrow$  a composition operator with relabelings  $f_1, f_2$ ;  $(G_1, lab^1) \otimes [\mathbf{g} \mid f_1, f_2] (G_2, lab^2) = (H, lab)$ 
  - $\implies$  the rank-width **parse tree** [Ganian and PH, 08]:

*t*-labeling parse tree for  $G \iff$  rank-width of  $G \leq t$ .

• Independently considered related notion of  $R_t$ -join decompositions by [Bui-Xuan, Telle, and Vatshelle, 08].

) XP algorithms for bounded (bi-)rank-width



So, how can one use a canonical equivalence when designing actual algorithms?

So, how can one use a canonical equivalence when designing actual algorithms?

• Let us recall...

 Theorem.
 [Myhill–Nerode, folklore]

 A finite automaton accepts a given language
 ↔

 the number of *right congruence* classes on the words is finite.

So, how can one use a canonical equivalence when designing actual algorithms?

• Let us recall...

 Theorem.
 [Myhill–Nerode, folklore]

 A finite automaton accepts a given language
 ↔

 the number of *right congruence* classes on the words is finite.

• This automaton is constructible and can be emulated in linear time.

So, how can one use a canonical equivalence when designing actual algorithms?

• Let us recall...

Theorem. [Myhill–Nerode, folklore]
A finite automaton accepts a given language ↔
the number of *right congruence* classes on the words is finite.

- This automaton is constructible and can be emulated in linear time.
- For parse trees, a straightforward generalization reads:

### **Theorem.** (Analogy of [Myhill–Nerode])

 ${\mathcal P}$  is accepted by a finite tree automaton on parse trees of boundary size  $\leq k$ 

 $\Rightarrow$  the canonical equivalence  $\approx_{\mathcal{P},k}$  has finitely many classes on  $\mathcal{U}_k$ .

(Actually, this is a "metatheorem" which requires several more unspoken technical conditions on the parse trees to hold true...)

P. Hliněný et al., CSASC 2010

2 XP algorithms for bounded (bi-)rank-width

#### **Extended canonical equivalence**

 $G_1 \approx_{\mathcal{P}, k} G_2$  for any  $G_1, G_2 \in \mathcal{U}_k$  if and only if, for all  $H \in \mathcal{U}_k$ ,  $G_1 \oplus H \models \mathcal{P} \iff G_2 \oplus H \models \mathcal{P}$ .

• To apply this concept to predicates  $\mathcal{P}(X_1,...)$  with free variables, we extend the universe  $\mathcal{U}_k$  to partially-equipped graphs of boundary  $\leq k$ .

#### **Extended canonical equivalence**

 $G_1 \approx_{\mathcal{P}, k} G_2$  for any  $G_1, G_2 \in \mathcal{U}_k$  if and only if, for all  $H \in \mathcal{U}_k$ ,  $G_1 \oplus H \models \mathcal{P} \iff G_2 \oplus H \models \mathcal{P}$ .

• To apply this concept to predicates  $\mathcal{P}(X_1,...)$  with free variables, we extend the universe  $\mathcal{U}_k$  to partially-equipped graphs of boundary  $\leq k$ .

#### Theorem. [Ganian and PH, 08]

Suppose  $\phi$  is a formula in the language MS<sub>1</sub>. Then the canonical equivalence  $\approx_{\phi,t}$  has finite index in the universe of *t*-labeled partially-equipped graphs.

#### **Extended canonical equivalence**

 $G_1 \approx_{\mathcal{P},k} G_2$  for any  $G_1, G_2 \in \mathcal{U}_k$  if and only if, for all  $H \in \mathcal{U}_k$ ,  $G_1 \oplus H \models \mathcal{P} \iff G_2 \oplus H \models \mathcal{P}$ .

• To apply this concept to predicates  $\mathcal{P}(X_1,...)$  with free variables, we extend the universe  $\mathcal{U}_k$  to partially-equipped graphs of boundary  $\leq k$ .

#### Theorem. [Ganian and PH, 08]

Suppose  $\phi$  is a formula in the language MS<sub>1</sub>. Then the canonical equivalence  $\approx_{\phi,t}$  has finite index in the universe of *t*-labeled partially-equipped graphs.

• From that one easily concludes an older result:

**Theorem.** [Courcelle, Makowsky, and Rotics 00] All *LinEMSO graph optimization* problems (in MS<sub>1</sub> language – only vertices!) on the graphs of bounded rank-width t can be solved in FPT time  $O(f(t) \cdot n)$ .

Core idea: In dynamic processing of the given parse tree, record optimal representatives of each class of the extended canonical equivalence  $\approx_{\phi,t} \dots$ 

ý et al., CSASC 2010 13 XP algorithms for bounded (bi-)rank-width

(XP: running in time  $O(n^{f(k)})$ , not FPT)

**Starting point:** For many problems  $\mathcal{P}$ , the number of classes of  $\approx_{\mathcal{P},k}$  depends on the input size n ( $\rightarrow$  likely no FPT algorithm exists).

(XP: running in time  $O(n^{f(k)})$ , not FPT)

**Starting point:** For many problems  $\mathcal{P}$ , the number of classes of  $\approx_{\mathcal{P},k}$  depends on the input size n ( $\rightarrow$  likely no FPT algorithm exists).

Yet there are known algorithms for them dynamically processing "information" of polynomial size  $O(n^{f(k)})$ ... How do they work?

We try to give a unified formal description...

(XP: running in time  $O(n^{f(k)})$ , not FPT)

**Starting point:** For many problems  $\mathcal{P}$ , the number of classes of  $\approx_{\mathcal{P},k}$  depends on the input size n ( $\rightarrow$  likely no FPT algorithm exists).

Yet there are known algorithms for them dynamically processing "information" of polynomial size  $O(n^{f(k)})$ ... How do they work?

We try to give a unified formal description...

In our parse-tree (width k) formalism, we

• assoc. the equiv. classes of  $\approx_{\mathcal{P},k}$  with an enum. of suitable "fragments",

(XP: running in time  $O(n^{f(k)})$ , not FPT)

**Starting point:** For many problems  $\mathcal{P}$ , the number of classes of  $\approx_{\mathcal{P},k}$  depends on the input size n ( $\rightarrow$  likely no FPT algorithm exists).

Yet there are known algorithms for them dynamically processing "information" of polynomial size  $O(n^{f(k)})$ ... How do they work?

We try to give a unified formal description...

In our parse-tree (width k) formalism, we

- assoc. the equiv. classes of  $\approx_{\mathcal{P},k}$  with an enum. of suitable "fragments",
- where the number of distinct "fragments" depends only on k,

(XP: running in time  $O(n^{f(k)})$ , not FPT)

**Starting point:** For many problems  $\mathcal{P}$ , the number of classes of  $\approx_{\mathcal{P},k}$  depends on the input size n ( $\rightarrow$  likely no FPT algorithm exists).

Yet there are known algorithms for them dynamically processing "information" of polynomial size  $O(n^{f(k)})$ ... How do they work?

We try to give a unified formal description...

In our parse-tree (width k) formalism, we

- assoc. the equiv. classes of  $\approx_{\mathcal{P},k}$  with an enum. of suitable "fragments",
- where the number of distinct "fragments" depends only on k,
- and we can recombine the fragment enumerations efficiently.

XP algorithm wrt. clique-width given by [Espelage, Gurski, and Wanke, 2001].

**Theorem.** Decide whether a graph G of rank-width t has a Hamiltonian path in time

$$O\left(|V(G)|^{\ell(t)}\right)$$
 where  $\ell(t) = 4^{t+1} + O(1)$ 

XP algorithm wrt. clique-width given by [Espelage, Gurski, and Wanke, 2001].

**Theorem.** Decide whether a graph G of rank-width t has a Hamiltonian path in time

$$O\left(|V(G)|^{\ell(t)}
ight)$$
 where  $\ell(t) = 4^{t+1} + O(1)$ .

**Proof:** 

• Considering a Hamiltonian path P in the join  $G \oplus H$ ,

XP algorithm wrt. clique-width given by [Espelage, Gurski, and Wanke, 2001].

**Theorem.** Decide whether a graph G of rank-width t has a Hamiltonian path in time

$$O\left(|V(G)|^{\ell(t)}\right) \text{ where } \ell(t) = 4^{t+1} + O(1) \,.$$

- Considering a Hamiltonian path P in the join  $G \oplus H$ ,
- the "fragments" are the subpaths  $P_i \subseteq P$  on the *G*-side

XP algorithm wrt. clique-width given by [Espelage, Gurski, and Wanke, 2001].

**Theorem.** Decide whether a graph G of rank-width t has a Hamiltonian path in time

$$O\left(|V(G)|^{\ell(t)}\right)$$
 where  $\ell(t) = 4^{t+1} + O(1)$ .

- Considering a Hamiltonian path P in the join  $G \oplus H$ ,
- the "fragments" are the subpaths  $P_i \subseteq P$  on the *G*-side
  - identified by labeling pairs of their ends (only  $4^t$  distinct!),
  - and enumerated at every parse tree node as one multiset.

XP algorithm wrt. clique-width given by [Espelage, Gurski, and Wanke, 2001].

**Theorem.** Decide whether a graph G of rank-width t has a Hamiltonian path in time

$$O\left(|V(G)|^{\ell(t)}\right)$$
 where  $\ell(t) = 4^{t+1} + O(1)$ .

- Considering a Hamiltonian path P in the join  $G \oplus H$ ,
- the "fragments" are the subpaths  $P_i \subseteq P$  on the *G*-side
  - identified by labeling pairs of their ends (only  $4^t$  distinct!),
  - and enumerated at every parse tree node as one multiset.
- Straightforward dynamic alg. processing then gives the result.

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

Considered recently by [Kolman, Lidický, and Sereni, 2009] wrt. tree-width.

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

Considered recently by [Kolman, Lidický, and Sereni, 2009] wrt. tree-width.

**Fact.** For fixed q, this is an MSOL partitioning problem.

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

Considered recently by [Kolman, Lidický, and Sereni, 2009] wrt. tree-width.

**Fact.** For fixed q, this is an MSOL partitioning problem.

**Theorem.** The defective  $(\ell, q)$ -colouring problem with fixed  $\ell$  parts (i.e. minimizing q) can be solved on a graph G of rank-width t in time

 $O\left(|V(G)|^{k(t,\ell)}\right)$  where  $k(t,\ell)=4\ell\cdot 2^t+O(1)$ 

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

Considered recently by [Kolman, Lidický, and Sereni, 2009] wrt. tree-width.

**Fact.** For fixed q, this is an MSOL partitioning problem.

**Theorem.** The defective  $(\ell, q)$ -colouring problem with fixed  $\ell$  parts (i.e. minimizing q) can be solved on a graph G of rank-width t in time

$$O\left(|V(G)|^{k(t,\ell)}
ight)$$
 where  $k(t,\ell) = 4\ell \cdot 2^t + O(1)$ .

**Proof:** 

• Consider separately each one colour class X.

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

Considered recently by [Kolman, Lidický, and Sereni, 2009] wrt. tree-width.

**Fact.** For fixed q, this is an MSOL partitioning problem.

**Theorem.** The defective  $(\ell, q)$ -colouring problem with fixed  $\ell$  parts (i.e. minimizing q) can be solved on a graph G of rank-width t in time

$$O\left(|V(G)|^{k(t,\ell)}
ight)$$
 where  $k(t,\ell) = 4\ell \cdot 2^t + O(1)$ .

- Consider separately each one colour class X.
- A "fragment" one vertex labeling in X, but one needs also to record its max. degree in X!

**Defective**  $(\ell, q)$ -colouring – partition the vertices into  $\ell$  parts such that – each part induces a subgr. of max. degree  $\leq q$ .

Considered recently by [Kolman, Lidický, and Sereni, 2009] wrt. tree-width.

**Fact.** For fixed q, this is an MSOL partitioning problem.

**Theorem.** The defective  $(\ell, q)$ -colouring problem with fixed  $\ell$  parts (i.e. minimizing q) can be solved on a graph G of rank-width t in time

$$O\left(|V(G)|^{k(t,\ell)}
ight)$$
 where  $k(t,\ell) = 4\ell \cdot 2^t + O(1)$ .

**Proof:** 

- Consider separately each one colour class X.
- A "fragment" one vertex labeling in X, but one needs also to record its max. degree in X !
- Slightly out of our formalism, and so deserves a closer look...

16 XP algorithms for bounded (bi-)rank-width

• The power of the *Myhill–Nerode–type* formalism extends beyond the finite-state (i.e. related to finite automata) properties. Nice, isn't it?

- The power of the *Myhill–Nerode–type* formalism extends beyond the finite-state (i.e. related to finite automata) properties. Nice, isn't it?
- Still, one would like to see an explicit (perhaps logic-based) *framework for XP algorithms*, analogously to the MSOL framework with FPT algorithms, cf. [Courcelle] et al.

- The power of the *Myhill–Nerode–type* formalism extends beyond the finite-state (i.e. related to finite automata) properties. Nice, isn't it?
- Still, one would like to see an explicit (perhaps logic-based) *framework for XP algorithms*, analogously to the MSOL framework with FPT algorithms, cf. [Courcelle] et al.
  - Our presented unified approach shows this should be possible...

- The power of the *Myhill–Nerode–type* formalism extends beyond the finite-state (i.e. related to finite automata) properties. Nice, isn't it?
- Still, one would like to see an explicit (perhaps logic-based) *framework for XP algorithms*, analogously to the MSOL framework with FPT algorithms, cf. [Courcelle] et al.
  - Our presented unified approach shows this should be possible...
  - And very recently, [Král', Obdržálek, and PH, 2010] have succeded in finding such a framework.

- The power of the *Myhill–Nerode–type* formalism extends beyond the finite-state (i.e. related to finite automata) properties. Nice, isn't it?
- Still, one would like to see an explicit (perhaps logic-based) *framework for XP algorithms*, analogously to the MSOL framework with FPT algorithms, cf. [Courcelle] et al.
  - Our presented unified approach shows this should be possible...
  - And very recently, [Král', Obdržálek, and PH, 2010] have succeded in finding such a framework.
- **BTW** (totally unrelated...)

Have you already heard that the *crossing number of almost planar graphs* is NP-complete? [Cabello and Mohar, 2010]

- The power of the *Myhill–Nerode–type* formalism extends beyond the finite-state (i.e. related to finite automata) properties. Nice, isn't it?
- Still, one would like to see an explicit (perhaps logic-based) *framework for XP algorithms*, analogously to the MSOL framework with FPT algorithms, cf. [Courcelle] et al.
  - Our presented unified approach shows this should be possible...
  - And very recently, [Král', Obdržálek, and PH, 2010] have succeded in finding such a framework.
- **BTW** (totally unrelated...)

Have you already heard that the *crossing number of almost planar graphs* is NP-complete? [Cabello and Mohar, 2010]

### THANK YOU FOR YOUR ATTENTION

P. Hliněný et al., CSASC 2010

XP algorithms for bounded (bi-)rank-width